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Prediction and Verification of Creep Behavior in Metallic Materials and Components for the Space Shuttle Thermal Protection System

VOLUME III

Phase III — Full Size Heat Shield Data Correlation and Design Criteria

AUGUST 1975

Prepared By B. A. Cramer and J. W. Davis

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Prediction and Verification of Creep Behavior in Metallic Materials and Components for the Space Shuttle Thermal Protection System VOLUME III

Phase III — Full Size Heat Shield Data Correlation and Design Criteria AUGUST 1975

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Prepared under Contract NAS 1-11774

Prepared by McDonnell Douglas Astronautics Company-East

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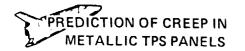
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ABSTRACT

Analysis methods, developed in Phase II, for predicting cyclic creep deflection in stiffened panel structures, were applied to full size panels. Results were compared with measured deflections from cyclic tests of thin gage L605, Rene' 41, and TDNiCr full size corrugation stiffened panels for which data were available in the literature. Empirical equations used in the analysis were developed for each material based on correlation with tensile cyclic creep data during Phase I of the program.

Based on results from the study, a design criteria is formulated for metallic TPS panels subjected to creep. This criteria addresses TPS design considerations, data requirements for creep analysis, and creep deflection analysis. Also included in this report are the users'information and listing for the TPSC (Thermal Protection System Creep) Computer Program developed to calculate creep deflections.



FORWARD

This report was prepared by McDonnell Douglas Astronautics Company - East under Contract NAS 1-11774 for the National Aeronautics and Space Administration, Langley Research Center, Hampton, Virginia. It was administered under the direction of the Materials Division, Materials Research Branch, with Mr. D. R. Rummler acting as the technical representative of the contracting office. The McDonnell Douglas program manager was Mr. J. W. Davis. Mr. B. A. Cramer was responsible for structural considerations, analytical methods, and data analysis.

The TPSC Computer Program analysis approach was initiated in the MDAC-E Advanced Structural Technology Group by Mr. O. R. Otto and Mr. J. K. Lehman. Mr. B. A. Cramer was responsible for development of the TPSC program under the contract. Mr. M. B. Gedera assisted in programming the TPSC program.

This report covers the period from December 1974 to April 1975.

i. SUMMARY

Presented in this report are the results of both the Phase III and Phase IV contract phases. Phase III was directed at correlating results of full size panel cyclic testing based on material cyclic creep response behavior determined in Phase I studies (Reference 1) and analysis capability developed in Phase II (Reference 2). Full size panel data for this effort, were obtained from the literature. Phase IV effort was directed at summarizing program results into a TPS panel design criteria. Phase III is presented in Sections 2 through 4 of the report and Phase IV is presented in Section 5. The Users information and listing for the TPSC (Thermal Protection system Creep) Computer Program developed during Phase II are presented in Appendices B and C respectively.

Comparisons of predicted and test deflections are presented for L605 panels and Rene' 41 panels tested at McDonnell Douglas Corporation and for Haynes 25 (L605) and TDNiCr panels tested at Grumman Aerospace Corporation.

Resulting predictions for the L605 and Rene' 41 panels provided good correlation with test results. For both materials there was approximately a factor of two difference between test deflection results for two identical panels tested simultaneously. No explanation for this difference could be determined, Predictions for these panels were made both at the center, where temperatures were highest and at the panel transverse edges where temperatures were somewhat lower. For the L605 panels the predicted center deflections were approximately 20% less than the lowest panel test deflection agreed closely with the average test deflections. For the Rene' 41 panels the predicted deflection was very close to the higher of the test deflections at the panel center. Sensitivity of predicted deflections to variations in material gage and test temperature was demonstrated for the Rene' 41.

Predictions for the Haynes 25 panel and TDNiCr panel were both low in comparison to test deflections although considerable variation was evident in the data measured for four spans on the TDNiCr panel and the prediction was within the data range. This variation in test data could not be accounted for by temperature variations in the panels. The trend in the prediction relative to test deflections as a function of cycle for TDNiCr was shown to be consistent with prediction capability of the empirical cyclic creep equation. Test deflections for the Haynes 25 panel were two times higher than predictions.



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 $(x_1, \dots, x_n) \in \mathbb{R}^n \times \mathbb{R$



1.0 INTRODUCTION

One of the design requirements of reentry vehicle metallic thermal protection systems (TPS) is that deflections, occurring during ascent and entry mission phases, due to differential pressure and thermal loading, do not exceed design limits. These deflection limitations are established to maintain the aerodynamic shape, minimize localized aerodynamic heating and to minimize the need for panel refurbishment. Because deflections include permanent deformation due to creep, methods for predicting these deformations are needed.

Several arrangements of metallic TPS components have been investigated in the coures of previous spacecraft studies. The baseline design used in the McDonnell Douglas Phase B Shuttle Study Program is shown in Figure 1-1. Radiative metallic panels form the outer moldline. These panels are backed by fibrous insulation blankets. Differential air pressure loads on the panels are transmitted by beam bending to transverse support beams located at approximately a 50 cm (~20 inches) spacing. Retaining straps are attached to the transverse support beams and retaining straps. Longitudinal joints between panels provide normal-to-panel shear continuity between adjacent panels, preventing joint gapping by forcing adjacent panels to deflect simultaneously under applied loads. Transverse support beams transmit loads to support struts which carry the loads to primary load carrying structure. Drag links, spanning diagonally between transverse support beams and primary structure, provide support structure system stability and carry longitudinal loads.

During Phase I (Reference 1) of this program, the influence of cyclic entry conditions on creep response was investigated for four material alloys: Ti-6Al-4V, Rene' 41, L605, and TDNiCr. Analysis of tensile creep test data during this phase resulted in empirical equations, for each material, which describe cyclic creep

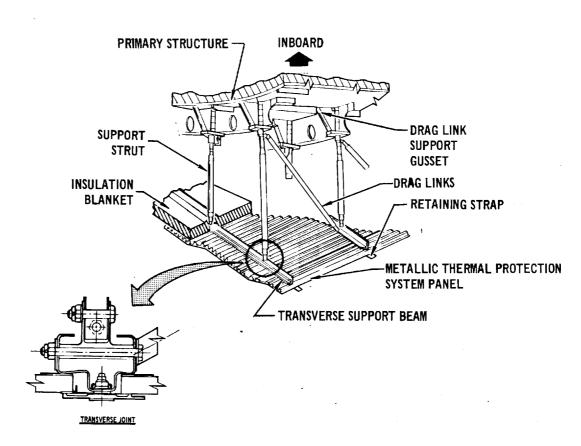


FIGURE 1-1 TYPICAL METALLIC THERMAL PROTECTION SYSTEM STRUCTURE

response characteristics as a function of stress, temperature, and time. These equations were used in conjunction with the time and strain hardening theories of creep accumulation to investigate creep prediction capability for cyclic trajectory stress and temperature profiles.

Phase II (Reference 2) was directed toward developing and verifying capability or prediction of creep deflection in metallic heat shields subjected to cyclic entry environments.

A computer program, Thermal Protection System Creep (TPSC) was developed for predicting beam creep deflections (Appendix B and C). This program offers an approach to creep predictions through application of iterative techniques and numerical integration. In the analysis, panel length is divided into segments over which bending moments are assumed constant and panel depth is divided into increments over which stresses and strains are assumed constant. Using a linear strain assumption, beam rotations are iteratively determined, based on either the time hardening or strain hardening theories of creep accumulation. Material cyclic creep response properties were defined by empirical equations developed from tests \circ f tensile creep specimens in Phase I. The TPSC program capability includes definition of temperature as a function of beam length and depth, application of either the strain hardening or time hardening theory of creep accumulation, and the application of bending distributions for a full size panel based on the edge stiffness and the longitudinal and transverse panel stiffness. Program output includes defintion of both elastic and creep deflected shapes, residual stresses, and creep strains as a function of cycle.

Seventeen subsize panel specimens, 6.35 cm by 3.05 cm, were tested to provide creep deflection data for verification of prediction capability. Corrugation cross section specimens were fabricated for test using thin gage (~.025 cm) L605, Rene' 41, Ti-6Al-4V, and TDNiCr sheet material. Rib cross section specimens were also

fabricated for test using thicker gage (~.060 cm) L605 and Ti-6A1-4V sheet material. These materials were procured for use both in Phase I and II. Each test consisted of cycling the panel for up to 100 entry thermal and bending load profiles representative of Shuttle entry missions. Testing was conducted in a vacuum furnace, using a load mechanism specifically designed to apply a two-point panel load that would be independent of panel deflection. Permanent deflections, due to creep, were measured as a function of cycle.

Comparisons of subsize panel creep deflection predictions with test results were made. Generally, good correlation was obtained between predicted and test deflections.

The objective of the program Phase III effort was to analyze full size panel creep data obtained from available test programs and to compare test results with prediction using methods of analyses developed during Phase I and II. Every effort was made to include all possible variations that could be ascertained from the documentation that might affect creep response so that as much confidence as possible could be associated with the comparison of predicted and test results. To this extent, the documented test data and results are summarized in this report. In addition, loads, temperatures, and panel geometry data required for creep analysis are reported.

The international system of units (SI) are used in this report. U.S. Customary Units are also generally provided. Applicable conversion factors are presented in Appendix A.



2.0 Background from Phase I and II

During Phase I and II of this program, the influence of cyclic entry conditions on creep response of L605, Rene' 41, TDNiCr, and Ti-6A1-4V were investigated and prediction capability for TPS panel creep deflections was developed. These cyclic creep data and analysis methods have been applied in the evaluation of full size panel test data in Phase III. Presented in this section are discussions of Phase I and Phase II results as they apply to the Phase III evaluation of full size L605, Rene' 41, and TDNiCr TPS panel test data.

2.1 PHASE I - CYCLIC TENSILE TESTING

In Phase I, thin gage tensile specimens were tested under cyclic loads and temperatures. Initially, creep response data were generated in what was designated as series of basic cyclic tests. These tests were conducted using the stress and temperature profiles shown in Figure 2-1 where the time per cycle was twenty minutes and the time between cycles (required for heat up and cool down portions of the profile) was 35 minutes. For each material, tests were conducted at three stress levels at each of four temperatures covering the range of temperature applicability for the respective materials.

Test temperature ranges were 978K (1300°F) to 1255 (1800°F) for L605, 1033K (1400°F) to 1155K (1620°F) for Rene' 41, and 1089K (1500°F) to 1478K (2200°F) for TDNiCr. Stress levels were selected at each temperature to yield 100 cycle creep strains of up to approximately 1%, the range of interest in analysis of TPS panels.

Analysis of cyclic tensile test data for each material resulted in empirical equations describing cyclic creep response characteristics as a function of stress, temperature, and time. These equations are presented in Table 2-1. Each equation represents a fit of cyclic data based on regression analysis. For each material

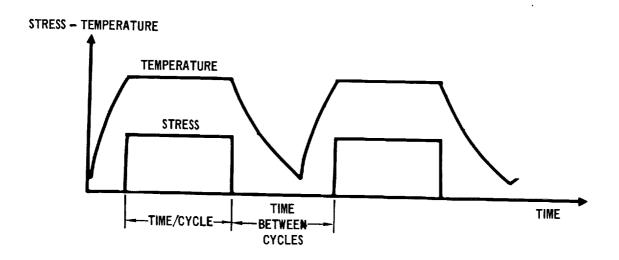


FIGURE 2-1 STRESS AND TEMPERATURE PROFILES FOR PHASE I TENSILE CYCLIC CREEP TESTS

TABLE 2-1 CYCLIC CREEP EQUATIONS DEVELOPED FOR PHASE I TENSILE CREEP DATA

MATERIAL	EQUATION (t = time, hours) σ = stress, MPa (T = Temperature, K/1000)	APPLICABLE TEMPERATURE MAXIMUM
L605	ln ε = -2.8941301743t + .54892 ln t + 1.31015 lnσ -6.66548 (1/T) + .19131 σ ln T + .00021 (Τσt).	1255 K (1800°F)
RENE'41	lns = -39.55860 + 29.13646T + .71922 lnt + .92125 (lns - 1.931) 000016σ ² + .08183 (lns - 1.931) ³ 000125 tsT + .0000105t ³	1155 K (1620°F)
TDNiCr	ln ε = -3.48443 -10.37282 $(\frac{1}{T})$ + .28314 ln t +2.00118 ln σ	1478 K (2200°F)

The equation developed for Ti-6Al-4V can be found in References 1 and 2. NOTE:

considerable effort was directed toward determining appropriate equation forms, including stress, time and temperature interaction terms, to provide a "best fit" over the entire range of data resulting in the different equation forms shown.

Typical comparisons of the tensile cyclic data and empirical equation predictions for each material are shown in Figures 2-2 through 2-4. Generally, the TDNiCr specimens failed at creep strains below .15%.

Because the empirical equations presented in Table 2-1 were derived from 100 cycle testing for 20 minutes at load per cycle, the total time of applicability of each of the equations is 33.3 hours. In the analysis of TPS panels subjected to mission load and temperature profiles, the profiles are "idealized" by dividing them into steps of constant load and temperature. To investigate the applicability of the empirical equations to these profiles, tests were also conducted for each material using the profile shown in Figure 2-1 with a ten-minute per cycle time at load and peak temperature. Results of these comparisons for each of the 10 minutes per cycle and 20 minutes per cycle materials are shown in Figure 2-5 for equal total time at load. Because close agreement between these test data was obtained, the equations are considered to be applicable in analysis of idealized mission profiles where smaller time steps are used. Also, this total time of equation applicability of 33.3 hours will be important in the analysis of test data where longer times of the stress and temperature profiles may result in a reduction of the number of cycles over which the equations are applicable.

Cyclic tensile tests were also conducted where stress was varied as a function of cycle (stepped stress tests) and where stress and temperature were varied within each cycle (mission profile tests). These test data were used to evaluate the applicability of the time and strain hardening theories of creep accumulation. Comparison of predicted creep strains using these hardening theories in conjunction with the empirical equations indicated that neither theory consistently provided

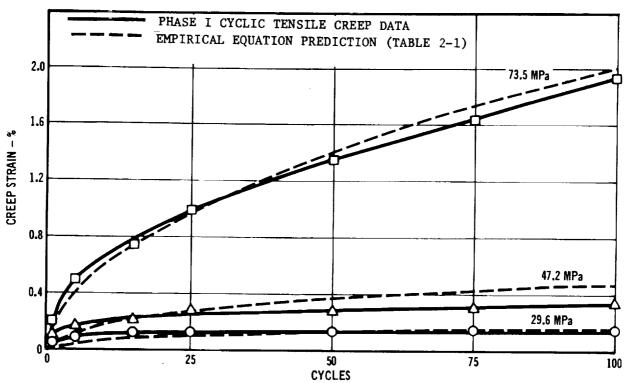


FIGURE 2-2 COMPARISON OF L605 PREDICTED AND CYCLIC TEST CREEP STRAINS AT 1144 K

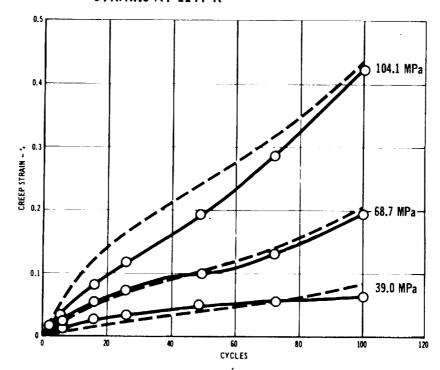


FIGURE 2-3 COMPARISON OF RENE 41 PREDICTED AND CYCLIC TEST CREEP STRAINS AT 1111 K

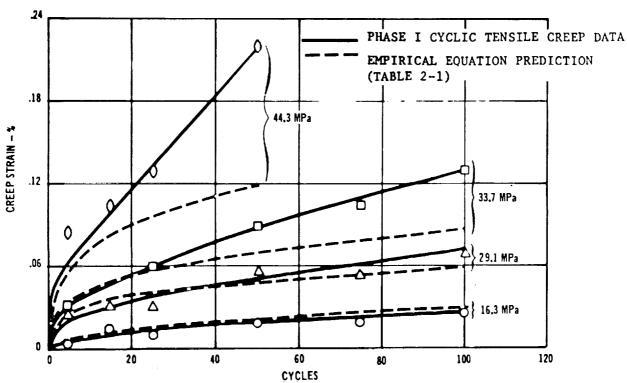
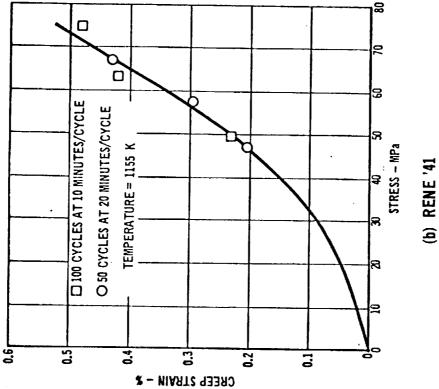
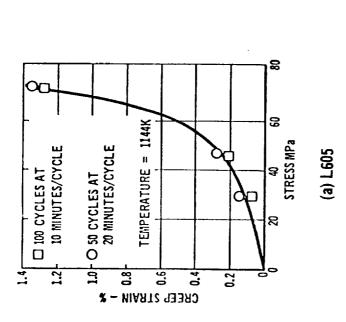


FIGURE 2-4 COMPARISON OF TONIC PREDICTED AND CYCLIC TEST CREEP STRAINS AT 1478 K



PHASE III SUMMARY REPORT





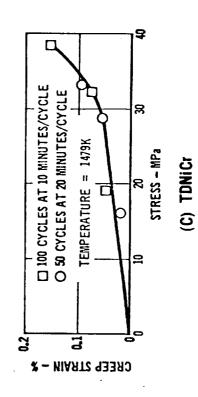


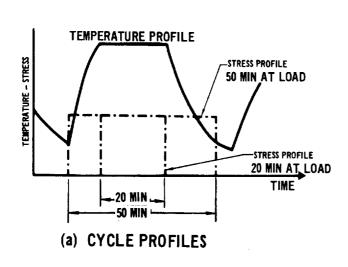
FIGURE 2-5 CYCLIC TENSILE CREEP STRAINS AT DIFFERENT TIME PER CYCLE COMPARED AT EQUAL TIME AT LOAD

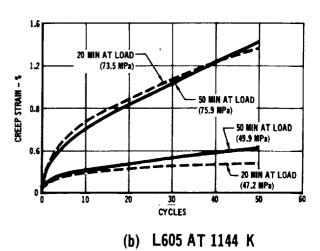
good predictions. Comparison of strain hardening and time hardening predictions with L605 cyclic tensile data showed that the strain hardening theory provided the best predictions for tests where stress was continually decreased as a function of cycle and the time hardening theory provided the best prediction for tests where stress was continually increased as a function of cycle. Therefore, an approach was proposed where both strain hardening and time hardening theories were used at each analysis step depending on whether the creep strain rate decreased or increased, respectively. Although this improved predictions for the L605 mission profile trajectory tests, it did not improve prediction for the other materials.

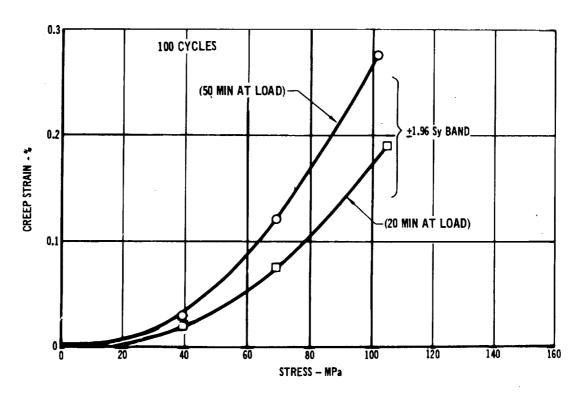
For Rene' 41, predictions based on the time hardening theory of creep accumulation were generally considered best. Predictions based on the strain hardening theory of creep accumulation were found to be approximately the same as for time hardening in predicting strains for testing where the stress was continuously increased as a function of cycle. Both predictions were close to test values. For specimens where stress was continually decreased, the time hardening predictions were up to 30% higher than test strains. However, predictions based on strain hardening were even higher, up to 75% higher than the time hardening predictions.

Predictions of creep strains for TDNiCr trajectory profile tensile tests using the cyclic creep equation, were found to be from 30% to 70% of test strains at 100 cycles. The applicability of hardening theories used in panel analysis will significantly effect prediction capability.

Another variable considered in Phase I tensile creep testing was the possible effect of recovery phenomena. To investigate this, tests were conducted where the stress profile was maintained for a longer period of time while temperature was being decreased rapidly, as shown in Figure 2-6(a). These comparative tests were conducted on L605 and Rene' 41 tensile specimens. Test results, shown in Figure 2-6(b), indicated that no variation in creep strains could be determined for the







(c) RENE '41 AT 1111 K

FIGURE 2-6 EFFECT OF MAINTAINING LOAD DURING HEAT UP AND COOL DOWN PORTIONS OF THE CYCLE PROFILE



L605 specimens, as indicated by the strain-time data plots. However, Rene' 41 creep strain results were consistently higher for each of three specimens tested. These results, plotted as a function of the stress levels, at 100 cycles are shown in Figure 2-6(c). This variation in creep strains for Rene' 41 was greater than expected based on data scatter as determined in the development of empirical equations. From these results it is difficult to draw conclusions as to the differences between the mission profile test results and predictions based on empirical equations developed for the twenty minute per cycle stress level. However, it has been demonstrated that an effect, due to possibly a material recovery phenomena, may exist to different degrees in the different materials, which may effect panel deflection predictions.

The empirical cyclic creep strain equations developed in Phase I were based on tests conducted on the thin gage sheet specimens (\sim .025 cm) for each material. Initially in Phase I, steady state tests were conducted on both these thin gage materials and also on specimens from a sheet thickness of .064 cm. An effect of gage on creep response (thin gages creep faster) was noted in the L605 steady state tests and also in steady state data obtained from the literature. This effect is attributed to a change in material processing at about t = .064 cm. This type of effect is discussed here to point out possible effects from sheet to sheet and due to thickness which may effect prediction capability in applying empirical equations developed on this program to panel tests from other programs.

For each of the alloys, cyclic tensile creep tests were conducted in Phase I to obtain data for the assessment of possible effects of atmosphere pressure on creep response. To provide these data, replicate tests were conducted, using idealized mission stress and temperature profiles. However, atmospheric pressure was held constant at 1.33 Pa, in one of the tests while a mission pressure profile was



applied in the other test. In each case variations in creep strain results were relatively small and were considered within the range of scatter for replicate tests. Therefore, no effect was attributed to atmospheric pressure.

2.2 PHASE II - PREDICTION AND VERIFICATION OF PANEL CREEP DEFLECTIONS

Phase II was directed toward developing and verifying capability for prediction of creep deflections in metallic heat shields subjected to cyclic entry environments.

A computer program, Thermal Protection System Creep (TPSC) was developed for predicting beam creep deflections and was used to predict results of subsize panel testing. Details of this work have been reported in the Phase II Summary report (Reference 2) and in the TPSC Program User Manual (Appendix B). This program offers an approach to creep predictions through application of iterative techniques and numerical integration. In the analysis, panel length is divided into segments over which bending moments are assumed constant and panel depth is divided into increments over which stresses and strains are assumed constant. The single skin corrugation TPS configuration with a skin bead, is automatically idealized through appropriate geometry input to the program. All of the full size panels analyzed in Phase III were of this configuration.

Using a linear strain assumption, beam rotations are iteratively determined, based on either the time hardening or strain hardening theories of creep accumulation. Material cyclic creep response properties developed from tests of tensile creep specimens in Phase I were used in the analysis and because the time hardening approach provided more consistently the best predictions of subsize panel data in Phase II, it was used for analysis purposes in Phase III. The TPSC program capability also includes definition of temperature as a function of beam length and depth, and the application of bending distributions for a full size panel based on the edge stiffness and the longitudinal and transverse panel stiffness. The



capability of including temperature as a function of panel length was utilized in analysis of the Reference 3 studies (Section 3.1) where temperature distributions were known.

Moment distributions are internally defined based on uniform pressure loads and simple panel supports. In addition, the moment distribution can be automatically calculated as a function of panel edge stiffness and the ratio of panel stiffness in the longitudinal and transverse directions. This option is based on combining solutions for an isotropic plate with two sides simply supported and two sides elastically supported as offered by Timoshenko (Reference 4) and the solution for an orthotropic plate with four sides simply supported as offered by Lekhnitskii (Reference 5). This option provides a first order approach to account for Poisson's effects in orthotropic plate structures. However, this option was not applied to the analysis of full size panel data in Phase III because of the large ratio of longitudinal to transverse stiffness for corrugated panels analyzed and because of the general lack of edge stiffness in the test panels. Edge stiffness was generally minimized in the full size panel tests to simulate as closely as possible actual entry vehicle panel conditions.

Both pressure and temperature load inputs are based on idealization of the test profiles into discrete time steps. During Phase I, cyclic tensile tests were conducted for both mission profiles and idealized profiles. Comparison of test results indicated that a minimum number of steps (4 steps used in Phase I testing) provided good correlation of results.

The following basic assumptions are made in the analysis:

a) Only bending stresses are considered in the analysis. Deflections due to shear are assumed negligible.

- b) Total creep strain plus elastic strain distributions through the panel depth are linear.
- c) Load and temperature distributions and calculated deflections are assumed symmetrical with respect to the panel centerline
- d) Creep response equations, defined by the user, are assumed to be applicable for both tensile and compressive stresses. In addition, the equations developed based on Phase I cyclic testing are assumed to be applicable for the sheet material used in fabrication of the full size panels.
- e) Stress distributions are assumed uniform in the horizontal thin gage sections of the panel cross sections. In particular, the thin gage skin, loaded in compression, is assumed to carry load uniformly (except as altered by the My/I distribution in the bead) across the pitch length.

It is difficult to determine how much each of these assumptions might influence the predictive capability of the TPSC program. The first three of these assumptions probably are the most applicable to the analysis. The last two assumptions are of most concern as to applicability. Certainly the scatter documented in literature for sheet to sheet variations in creep response as well as variations in TPS panel skin stress distributions evidenced through strain gage data (References 3 and 6) and the occurrence of skin buckling (References 2 and 3) noted in TPS panel testing will effect creep deflections. Applicability of the hardening theories to the real material response will also be an unknown in the full size panel analysis.

Even with all of these assumptions considered, the TPSC computer program has been demonstrated to provide needed capability for prediction of permanent deflections, due to creep, in entry vehicle metallic thermal protection system panels subjected to complex cyclic loading conditions. The TPSC program is written in Fortran IV and is operational on the CDC 6600.

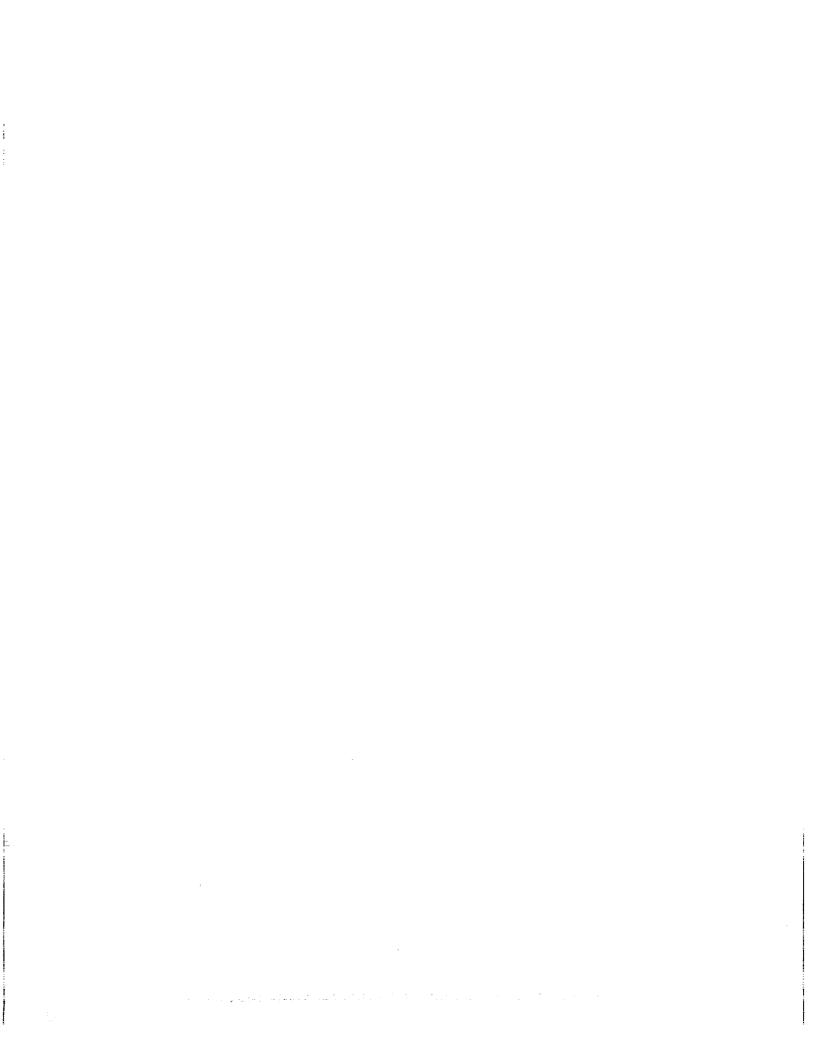
Four L605, three Rene' 41, four Ti-6A1-4V, and two TDNiCr subsize (6.35 cm by 30.5 cm) corrugation stiffened TPS panels were tested to provide creep deflection data for verification of prediction capability in Phase II. These specimens were fabricated using thin gage (approximately .025 cm) sheet material, however, the section geometry was more compact (pitch = 1.91 cm and depth = 1.27 cm) than those found in the full size panel testing. In addition, no skin bead was used in the subsize panels. Rib cross section specimens were also fabricated for test using thicker gage (~.064 cm) L605 and Ti-6A1-4V sheet material.

Testing of subsize panels was conducted in a vacuum furnace, using a load mechanism specifically designed to apply panel bending loads that would be independent of panel deflection. Permanent deflections, due to creep, were measured as a function of cycle. Each test consisted of cycling the panel for up to 100 temperature and bending load profiles representative of Shuttle entry missions. Two types of cyclic profiles were used. The first consisted of a constant load and temperature applied for twenty minutes, with heat up and cool down periods at zero load yielding total cycle time of fifty five minutes. Two L605, two Rene' 41, three Ti-6Al-4V, and one TDNiCr subsize panels were tested to this type profile. The second type of profile consisted of mission temperature and load profiles for the same total cycle time as for the constant load cycles. The remainder of the seventeen panels (four L605, one Rene' 41, three Ti-6Al-4V, and one TDNiCr) were tested to these mission profiles.

Comparisons of the subsize panel creep deflection predictions with test results were made in Phase II (Reference 2). Predicted deflections, as a function of cycle, for the L605 subsize panels tended to be lower than test values for approximately 15 cycles and then increase to higher than test values by the conclusion of the test. This same trend was noted in the comparison of tensile



creep data and empirical equation predictions. Predicted panel creep deflections obtained using the time hardening theory of creep accumulation were found to generally yield the best predictions. Predicted deflections for the Rene' 41 panels generally were not as close to test values as had been demonstrated in the case of L605. Again, the time hardening theory of creep accumulation provided the best deflection predictions, although these predictions were lower than test data for the mission profile and higher than test data for the constant load and temperature profiles. Predictions for the Ti-6A1-4V panels generally agreed with test results. The shape of the predicted deflection curve as a function of time (or cycle) was in good agreement with the test data which is consistent with the prediction capability of the empirical equation for Ti-6A1-4V. Predictions for the TDNiCr subsize panels were a factor of two high in one test and a factor of two low in the other test. No rational was determined for this apparent inconsistency although all deflections were small (0.05 cm).



3.0 ANALYSIS OF FULL SIZE PANEL DATA

The Phase III effort consists of evaluation and analysis of full size panel data. In each case, analysis consists of the idealization of test load and temperature profiles and calculation of the TPS panel deflections using the material cyclic creep properties developed in Phase I and creep deflection prediction methods developed in Phase II.

Four sets of panel data were evaluated in this phase. These data were for L605 panels and Rene' 41 panels tested at McDonnell Douglas Corporation (Reference 3) and Haynes 25 (L605) and TDNiCr panels tested at Grumman Aerospace Corporation (References 6, 7 and 8). Although it was desirable to evaluate data on panels for each of the four materials studied in Phases I and II, no test data on testing of full size titanium TPS panels were found.

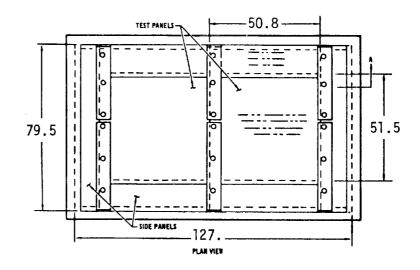
3.1 SSTP PROGRAM L605 AND RENE' 41 PANELS

The SSTP program (Supplementary Structural Test Program) was a supplement to the Space Shuttle System Program Definition, conducted at McDonnell Douglas Astronautics Company - East. This program consisted of designing, fabricating, and testing of Space Shuttle primary structure and thermal protection systems. Purposes of the program were to verify feasibility of design concept, provide design data, demonstrate producibility, demonstrate reusability and verify unit weight predictions. Included in this program was the testing of L605 and Rene' 41 full scale metallic TPS panels.

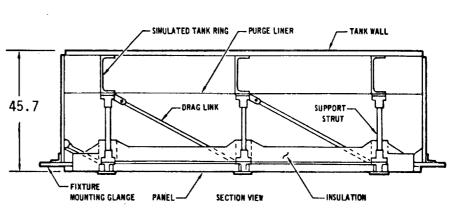
Each test assembly consisted of two test panels, smaller side panels to provide proper boundary conditions, support beams and struts, and a section of simulated tank structure. Figure 3-1 shows the test assembly. The two primary test panels are each $50.8 \text{ cm} \times 50.8 \text{ cm} (20" \times 20")$. The 12.7 cm (5 in.) wide



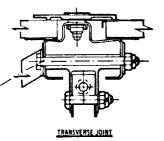
(a) FULL SCALE
SSTP PANELS
IN TEST FIXTURE



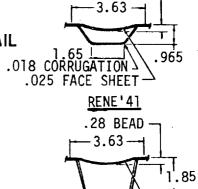
(b) SSTP
SUPPORT STRUCTURE
AND INSULATION
LARGE PANEL
TEST







(d) PANEL
DESIGN DETAIL



2.12

.018 CORRUGATION -

.025 FACE SHEET

L605

.28 BEAD

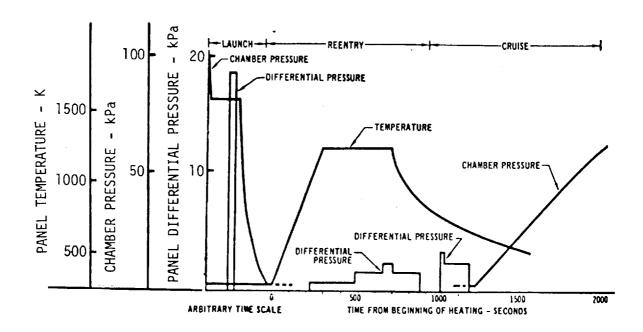
LONGITUDINAL JOINT

FIGURE 3-1 SSTP PANEL TEST GEOMETRY

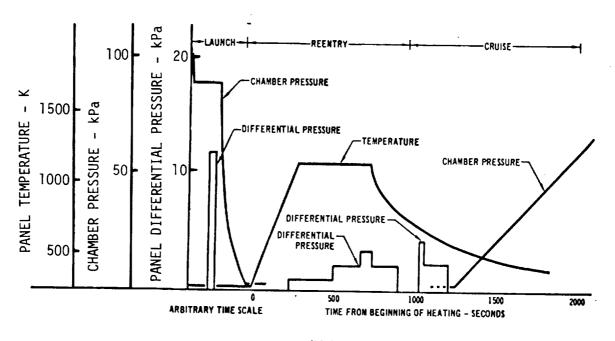
side panels simulated the boundary conditions by isolating the primary panels from the water cooled test fixture. The support beams for the panels were 50.8 cm (20 in.) apart. The panels were supported by "hat section beams and retaining straps with sufficient clearance to permit free expansion. The beams in turn were supported by tubular struts and drag links. Figures 3-1(a), 3-1(b), and 3-1(c) show the details of this construction. The beam also supported the insulation packages. To accommodate thermal expansion, the panels were mounted with slip fit joints. For the analysis, the panels were assumed to have simple supports at the edges because end fixity and friction were difficult to define.

The panels of both materials were the same basic design; single faced, corrugation stiffened, with beaded face skins and reinforcing doublers on the ends of the corrugations. The doublers served a dual purpose. They not only stiffened the corrugation ends, but they were also made thick enough so that after assembly a light machine cut could be taken across the doublers to make a close tolerance uniform thickness panel. Panels differed in corrugation depth as shown in Figure 3-1(d). The shallow beads in the face skins were designed to relieve the stresses caused by the thermal gradients. Heat treatment of the L605 and Rene' 41 panels were performed in two phases. For the first phase the panels were heated in air, without any restraining fixtures, so that a high emittance oxide coating would form on all surfaces. The panels were then clamped and heated a second time. These coating and straightening operations were incorporated into the normal heat treating sequence for the materials.

Testing consisted of exposing the structures to repeated cycles of simulated mission environment. Each cycle consisted of exposure to assent pressure, entry pressure and temperature, and cruise pressure, as shown in Figures 3-2(a) and (b) for L605 and Rene' 41 panels respectively. Blocks of these cycles were followed by blocks of acoustic test cycles.



(a) L605 Panel



(b) Rene' 41 Panel

FIGURE 3-2 SIMULATED TEST MISSIONS USED IN SSTP PROGRAM

The programmed TPS differential pressure levels were met during the entry phase of the mission. Launch differential pressure levels were usually 35% low and cruise differential pressures were 50% low due to high TPS panel leakage. The Rene' 41 TPS panel was subjected to the complete 100 mission program, while the L605 panel was exposed to 30 temperature-pressure tests and 100 acoustic tests. Throughout each cycle the panel temperatures, not influenced by the joint, were controlled during heating. The cooling portion of the mission, however, was uncontrolled and in all cases cooled somewhat faster than expected. The lamp array used for heating the panels was made in sections creating an unavoidable gradient in the panels. Thermocouples were positioned so this gradient could be measured.

As part of the periodic inspections, the surface of the panels were mapped to detect any warpage or permanent set caused by the simulated missions. The aft panel on each of these assemblies deflected more than the forward panel. There was no obvious explanation for this difference, although it was probably caused by some phenomena associated with the test set—up. It is possible that the time at temperature for one panel was consistently slightly longer than the other.

The following sections describe the effort in evaluating data and in providing cyclic creep deflection predictions for these L605 and Rene' 41 TPS panels.

3.1.1 SSTP PROGRAM L605 PANEL

SSTP L605 temperature data (Reference 3) were reviewed to define actual panel temperature distributions which would be applicable to the panel analysis. The data points for several representative cycles are used in developing the temperature variations shown in Figure 3-3. As indicated in the referenced report, the influence of the lamp bank splice was approximately 30K (~50°F). Variation is noted between the panel edge and center temperature levels, however, no significant

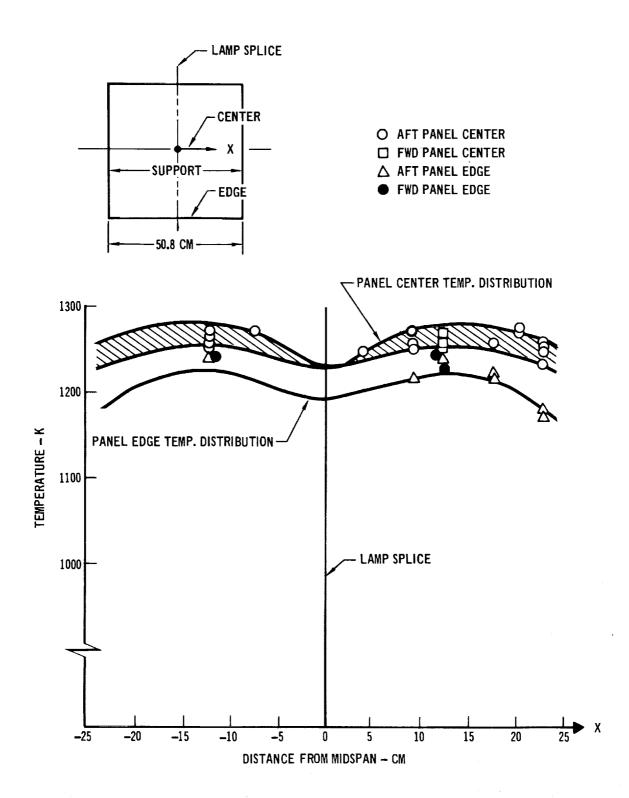


FIGURE 3-3 L605 TPS PANEL MEASURED TEMPERATURE DISTRIBUTIONS



difference can be detected between the forward and aft panels at either the center or edge locations.

Analysis of the panels was conducted for the reentry portion of the mission profile (Figure 3-2(a)). This profile was idealized into five constant temperature and differential pressure steps as indicated in Figure 3-4. Analysis was based on using the panel temperature distributions from Figure 3-3 defined as a function of time by the profiles in Figure 3-4.

Comparisons of creep deflection predictions with measured deflection data are presented in Figure 3-5. Considerable effort was given to evaluation of the creep deflection test data. A significant amount of variation was noted as indicated in the plots of Figure 3-5. Therefore, it is difficult to draw conclusions as to the prediction capability. A careful review of the reference 4 data did not reveal any differences which would account for the variation in deflection between the forward and aft panels as indicated in Figure 3-5(a). The prediction shown is based on the maximum of the temperature range shown in Figure 3-3 at the panel center. Analysis conducted using the minimum value of the temperature range resulted in approximately a 10% lower creep deflection prediction. The prediction shown for the panel edge in Figure 3-5(b) is based on the corresponding temperature distribution in Figure 3-3. Predicted deflections are based on the same unsupported span length (45.7 cm) and referenced measurement length (41.3 cm) as used in the SSTP Program. Data used in the analysis are presented in Tables 3-1(a), (b), and (c).

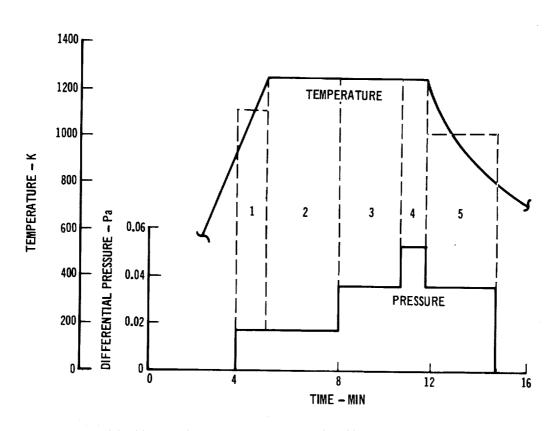
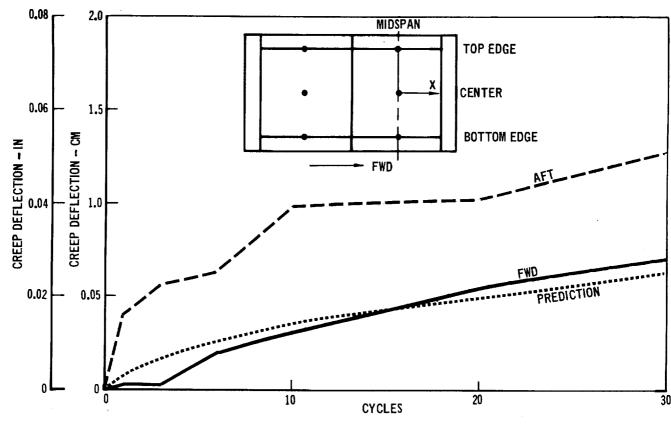


FIGURE 3-4 L605 ENTRY PROFILE USED IN CREEP PREDICTION ANALYSIS





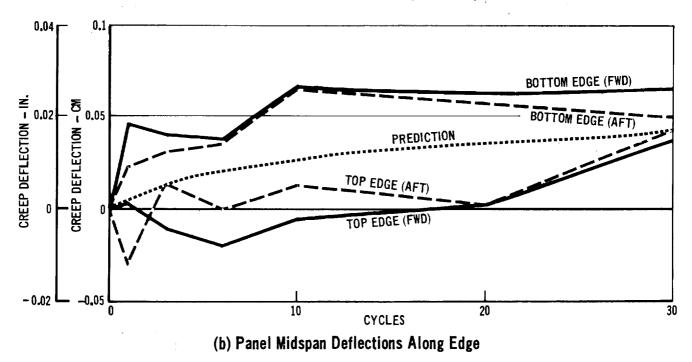
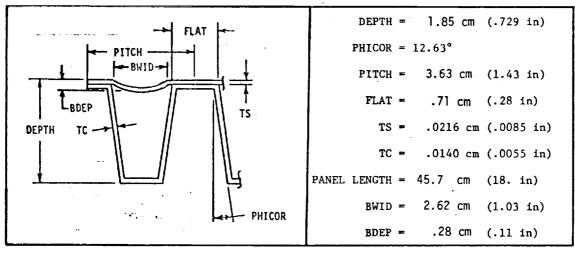


FIGURE 3-5 COMPARISON OF L605 PANEL TEST AND PREDICTED CREEP DEFLECTIONS



(a) L605 Panel Geometry

TIME (MIN)	PRESSURE KPa (PSI)	PANEL TEMPERATURE ~ K (°F)						
		X=0	X=5.1	X=10.2	X=15.2	X=20.3	X=22.9	
0 - 1.33	.76	1149	1162	1167	1159	1129	1122	
	(.11)	(1609)	(1631)	(1640)	(1627)	(1573)	(1560)	
1.33 - 4.67	.76	1261	1275	1281	1272	1239	1231	
	(.11)	(1810)	(1835)	(1845)	(1830)	(1770)	(1755)	
4.67 - 7.50	1.65	1261	1275	1281	1272	1239	1231	
	(.24)	(1810)	(1835)	(1845)	(1830)	(1770)	(1755)	
7.50 - 8.50	2.48	1256	1269	1275	1267	1233	1225	
	(.36)	(1800)	(1825)	(1835)	(1820)	(1760)	(1745)	
8.50 - 11.33	1.65	1038	1048	1053	1046	1021	1014	
	(.24)	(1408)	(1427)	(1435)	(1423)	(1377)	(1365)	

(b) Temperatures and Pressures Along Panel Center

TIME (MIN)	PRESSURE KPa (PSI)	PANEL TEMPERATURE ~ K (°F)						
		X=0	X=5.1	X=10.2	X=15.2	X=20.3	X=22.9	
0 - 1.33	.76	1076	1108	1115	1108	1090	1088	
	(.11)	(1476)	(1534)	(1547)	(1534)	(1502)	(1498)	
1.33 - 4.67	.76	1178	1214	1222	1214	1194	1192	
	(.11)	(1660)	(1725)	(1740)	(1725)	(1690)	(1685)	
4.67 - 7.50	1.65	1178	1214	1222	1214	1194	1192	
	(.24)	(1660)	(1725)	(1740)	(1725)	(1690)	(1685)	
7.50 - 8.50	2.48	1173	1209	1217	1209	1194	1187	
	(.36)	(1651)	(1716)	(1731)	(1716)	(1681)	(1676)	
8.50 - 11.33	1.65	973	1001	1007	1001	986	وَ98	
	(.24)	(1291)	(1341)	(1353)	(1341)	(1314)	(1310)	

(c) Temperatures and Pressures Along Panel Edge

TABLE 3-1. GEOMETRY AND LOADING DATA USED IN L605 PANEL ANALYSIS

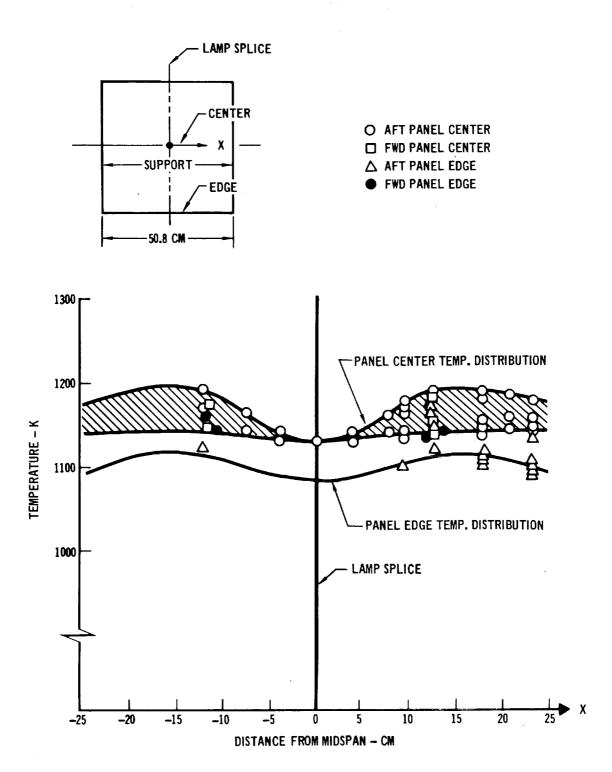


FIGURE 3-6 RENE'41 TPS PANEL MEASURED TEMPERATURE DISTRIBUTIONS

Initial analysis using a five time step idealization of the temperature and load profiles (reference Figure 3-4 for L605) indicated that less than 2 percent of the creep deflection occurred during the first and last time steps due to lower temperatures than in the other three steps. Therefore, subsequent analysis for Rene' 41 panels was conducted using the three step idealization of the entry test profiles as shown in Figure 3-7. The first step at constant peak temperature was extended in this case by approximately one half minute to compensate for the deleted two steps.

Comparisons of predicted panel deflections with test data are provided in Figure 3-8. Three predicted deflection curves are shown for the panel midspan (Figure 3-8(a)). The two curves of highest predicted creep deflection (designated A and B) are based on constant panel temperatures of 1144K (1600°F) and 1128K (1570°F) corresponding to the trajectory profile (Figure 3-7) temperature and the minimum panel center temperature distribution (Figure 3-6), respectively. These two analyses show the effect of this temperature variation on the predicted creep deflections. Both of these predicted curves are based on skin and corrugation gages of .0216 cm (.0085 in) and .0140 cm (.0055 in), respectively.

In an effort to demonstrate the effect of gage effects on the creep deflection, a third analysis was conducted (curve C) using the skin and corrugation gages of .0254 cm (.0100 in) and .0178 cm (.0070 in). The constant temperature of 1128K (1570°F) was applied, allowing comparison with the corresponding predicted deflection presented for the thinner gages (curve B). Again considerable variation was evident in the deflection data for the forward and aft panels tested. Shown in Figure 3-8(b) is the predicted creep deflection based on the panel edge temperature distribution defined in Figure 3-6. The panel dimensions, loads, and temperatures used in the analysis are defined in Table 3-2(a), (b), and (c).

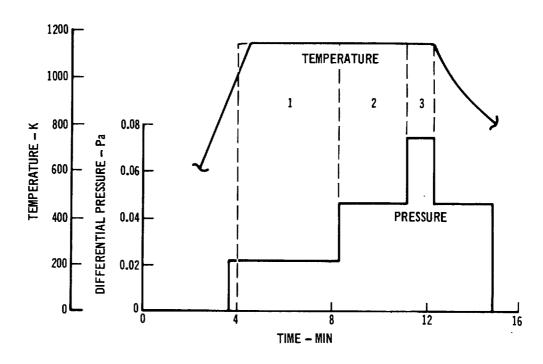


FIGURE 3-7 RENE'41 ENTRY PROFILE USED IN CREEP PREDICTION ANALYSIS

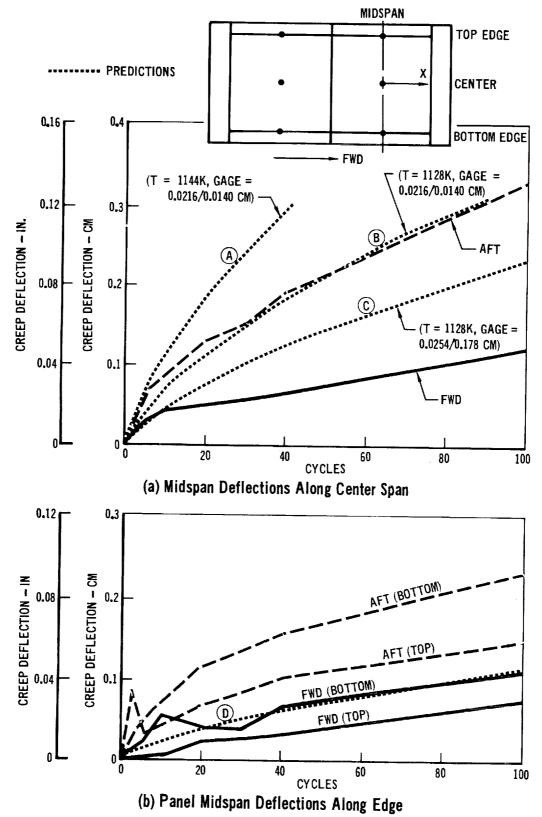
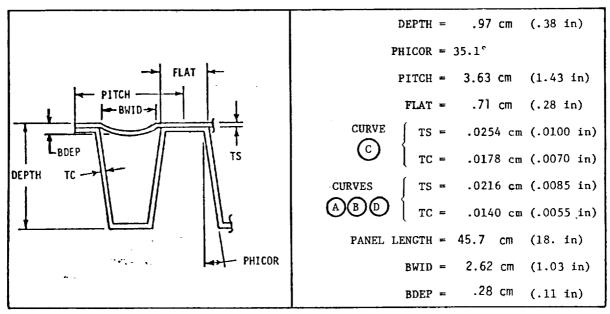


FIGURE 3-8 COMPARISON OF RENE'41 PANEL TEST AND PREDICTED CREEP DEFLECTIONS



(a) Rene' 41 Panel Geometry

PRESSUR		TEMPERATURE (CONSTANT ALONG LENGTH)				
TIME (MIN)	KPa (PSI)	CURVE (A) (FIG. 3-8)	CURVE B (FIG. 3-8)	CURVE C (FIG. 3-8)		
0 - 4.2	1.03 (.15)					
4.2 - 7.0	2.20 (.32)	1144 K (1600 °F)	1128 K (1570°F)	1128 K (1570°F)		
7.0 - 8.0	3.45 (.50)					

(b) Temperatures and Pressures Along Panel Center

TIME (MIN)	PRESSURE	TEMPERATURE ~ K (°F)					
TIME (MIN)	KPa (PSI)	X=0	X=5.1	X=10.2	X=15.2	X=20.3	X=22.9
0 - 4.2	1.03 (.15)						
4.2 - 7.0	2.20 (.32)	1100 (1520)	1111 (1540)	1111 (1540)	1097 (1515)	1083 (1490)	1081 (1485)
7.0 - 8.0	3.45 (.50)						

(c) Temperatures and Pressures Along Panel Edge

TABLE 3-2. GEOMETRY AND LOADING DATA USED IN RENE' 41 PANEL ANALYSIS

3.2 GRUMMAN TDNiCr PANEL

Evaluation of TDNiCr, from the standpoint of creep deflections in TPS panels, represents a different case than the other TPS materials because relatively little creep is evident in this material before failure occurs. Because of these low creep strains and resulting low test panel deflections, the data have tended to exhibit a greater amount of scatter.

The TDNiCr panel data evaluated in this section were obtained from Reference 8. The TPS panel tested consisted of a corrugation stiffened TDNi-20 Cr metallic heat shield backed by a flexible fibrous quartz and radiative shield insulation system. The test article represents the intersection of two 50.8 cm (20 inch) square panels as shown in Figure 3-9. Each panel consists of a beaded 0.025 cm (.010 inch) skin and corrugation. Detail dimensions of the corrugation cross section, used in analysis for panel deflections, are presented in Figure 3-10.

These panels were tested to 90 cycles of combined pressure and temperature loading, simulating critical heating and aerodynamic pressure environments expected during repeated missions of a reentry vehicle. Prior to these 90 cycles, the panels were subjected to 10 cycles of heating conditions only. Typical thermal distributions determined during these cycles are included in Figure 3-9 at various locations on the panels.

Entry test profiles (Reference 8) and idealizations used in the analysis are shown in Figure 3-11. For purposes of analysis these profiles were idealized into the three constant load and temperature steps shown. These temperatures were assumed to be constant along a panel length of 47. cm (18.5 in.). Analysis of the corrugation panel geometry under the idealized loads and temperature profiles was conducted using the analytical methods developed in Phase II (Reference 2). The empirical creep strain equation (Table 2-1) developed in Phase I, was used in the

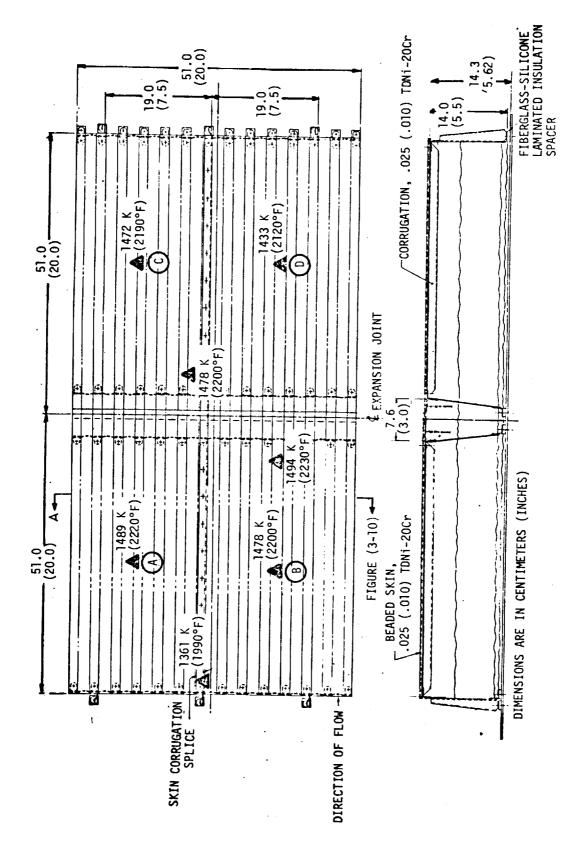
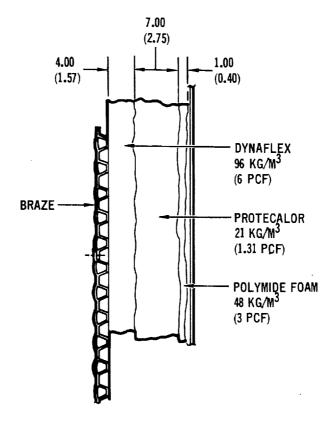


FIGURE 3-9 GRUMMAN TD NIC' TEST PANEL SETUP



Section A - A (Figure 3 -9)

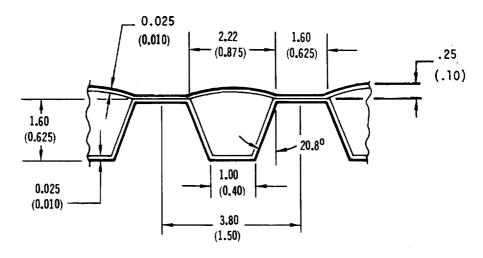


FIGURE 3-10 TDNi Cr TEST PANEL CORRUGATION DEFINITION

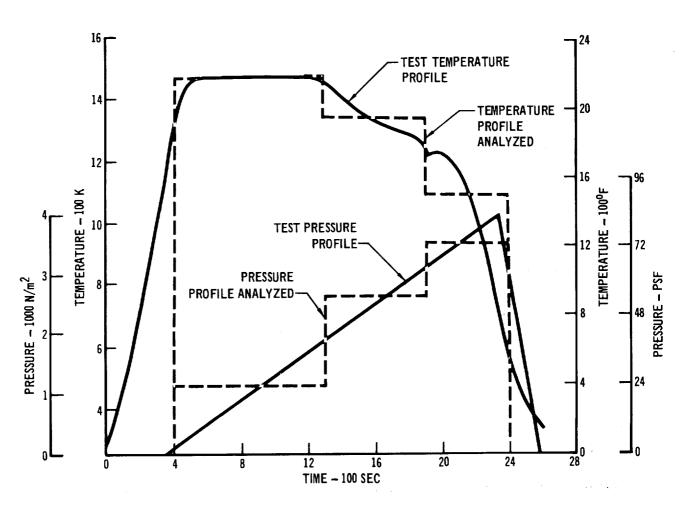
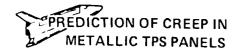


FIGURE 3-11 TEST AND IDEALIZED LOADING AND TEMPERATURE PROFILES



analysis to represent the material creep strain response and the time hardening theory of creep accumulation was applied.

Shown in Figure 3-12 are comparisons of the predicted creep deflections with measured permanent test deflections. The test deflections are plotted from initiation of the combined load and temperature cycles for four midspan locations referenced to the panel geometry in Figure 3-9. A significant variation is noted in these test data. In the reference 8 report the variation was attributed to the slightly higher temperatures observed at locations A and B. In addition it was noted that there was a significant increase in permanent deflection at locations C and D, between cycles 1 and 9. This was attributed to residual stresses, built into the panel during manufacture and assembly as well as thermally induced loads. Therefore, there remains some question as to the true amount of creep occurring between cycles 1 and 9.

The predicted creep deflections indicate a lower rate of creep than observed in testing. This is attributed to the empirical equation in the stress and temperature range applied. The analysis showed that approximately 75% of the creep occurred during the first load-temperature step in the profile (Figure 3-11). Temperature during this step was 1478K (2200°F) and calculated corrugation outer fiber stress was approximately 23 MPa (3300 psi). Comparison of Phase I cyclic tensile creep data with the empirical equation predictions shown in Figure 2-4 also indicate the lower slope of the predicted strains. The wide variation in creep deflections cannot be predicted, based on the temperature data.

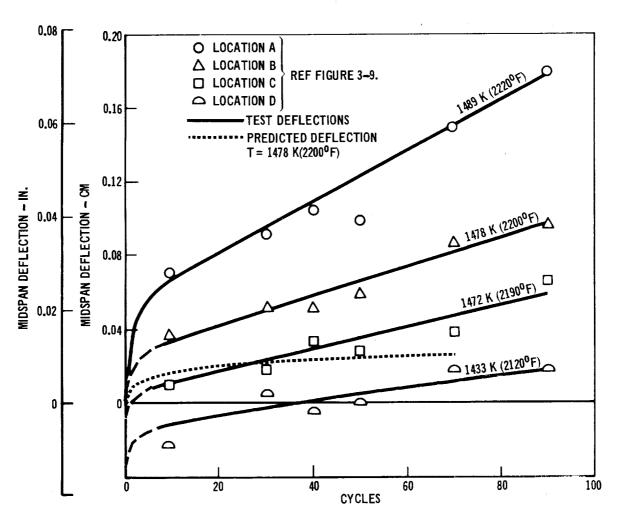


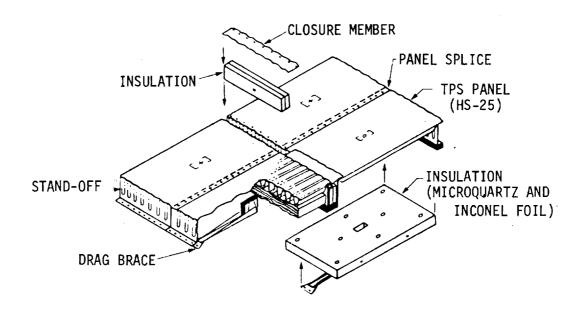
FIGURE 3-12 COMPARISON OF TD NICI PANEL TEST DEFLECTIONS
AND PREDICTIONS



3.3 GRUMMAN HAYNES 25 PANEL

A Haynes 25 (L605) panel was tested by Grumman Aerospace Corporation and results presented in References 6 and 7. The panel tested was designated as panel No. 3 in the references and was segmented, as shown in Figure 3-13, into four separate test panels. The cross section geometry was single face corrugation stiffened with a skin bead of approximately 0.25 cm (0.10 in.) depth. These panels were supported at the ends (simple support assumed for analysis) over a 47.2 cm (18.6 inch) span and subjected to a uniform pressure profile of 2.42 kPa (0.35 psi). The temperature profile used in the cyclic testing is presented in Figure 3-14. Also shown is the two step idealized temperature profile used in the analysis. Panel geometry and dimensions used in the analysis are provided in Figure 3-13. For each of the panels, analysis was conducted for two different temperature levels because of the cycle to cycle test temperature variations as indicated in Figure 3-15. The time hardening theory of creep accumulation was applied in conjunction with the L605 cycle creep empirical equation (Table 2-1) developed in Phase I.

Comparison of resulting predictions with the Reference 6 experimental data, shown for the NE and SW panels in Figure 3-16(a) and (b), respectively, show that the experimental deflections are considerably higher than predicted. No explanation of this variation between theory and test has been determined based on the data in the reference.



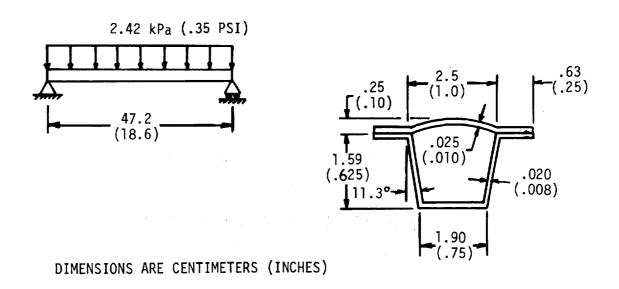


FIGURE 3-13 PANEL GEOMETRY FOR GRUMMAN HAYNES 25 PANEL TESTS

3-23

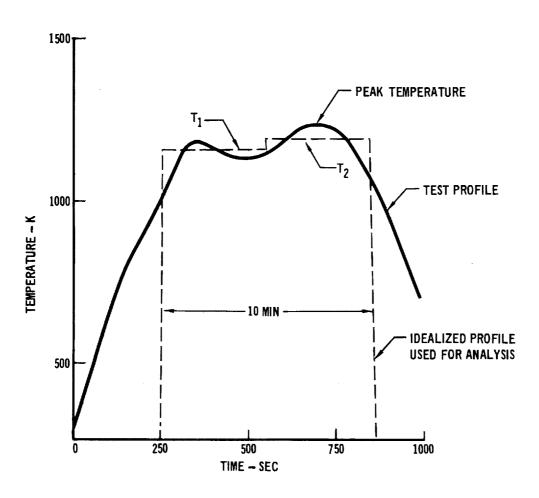


FIGURE 3-14 HAYNES 25 PANEL TEMPERATURE PROFILE

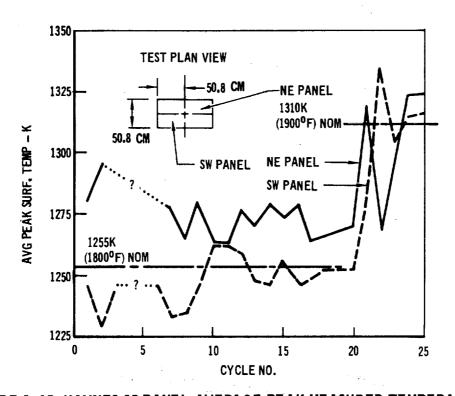
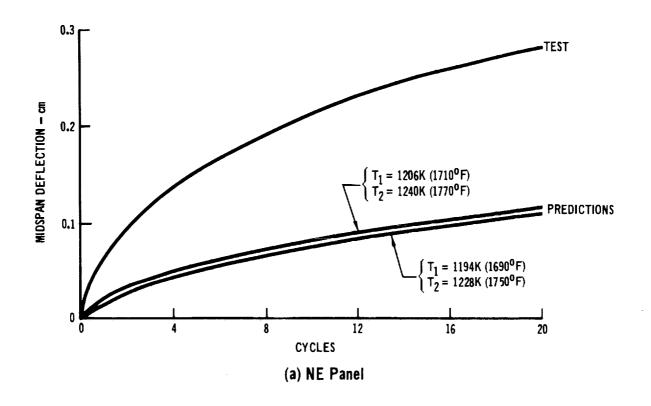


FIGURE 3-15 HAYNES 25 PANEL AVERAGE PEAK MEASURED TEMPERATURE



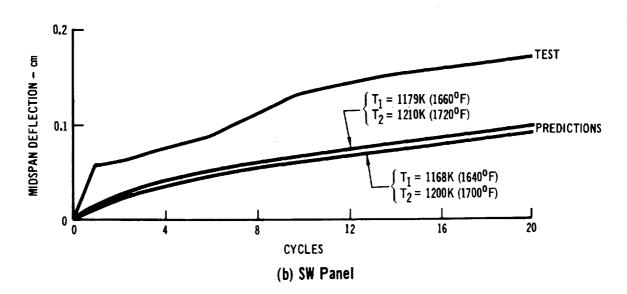


FIGURE 3-16 COMPARISON OF PREDICTED CREEP DEFLECTIONS WITH TEST DATA FOR HAYNES 25 PANELS



4.0 PHASE III CONCLUSIONS

Comparison of permanent cyclic creep deflections, obtained in testing of full size thermal protection system panels, with predicted values has met with varied degrees of success. Prediction capability for L605 and Rene' 41 appears to be reasonably good, although there is much variation in the test data, even for panels tested simultaneously to the same temperature and load level. Prediction capability for TDNiCr appears to be less accurate although recognition of the low creep rate of TDNiCr has led to minimization of effort on creep response definition throughout the program. Predictions for the full size panels are summarized in Table 4-1, showing that prediction accuracies cannot, in general, be expected to be better than a factor of two. These predictions were made using the time hardening theory of creep accumulation.

Resulting predictions of cyclic creep deflection have been shown to be sensitive to both stress level and temperature. This makes prediction capability more difficult since variations from cycle to cycle were known to occur but may not have been defined for each cycle. Such factors as an overshoot in temperature for only one cycle or a few cycles could significantly increase the total test deflections attained. In addition, the test panels were generally subjected to other environments such as high launch phase loading and acoustic environments, which possibly contribute to redistribution of panel relative displacement and variation in the data.



TABLE 4-1. SUMMARY OF FULL SIZE PANEL CREEP DEFLECTIONS

TEST PANEL		RANGE OF TEST DEFLECTIONS Cm	PREDICTION Cm	PREDICTION AS % OF TEST AVERAGE	
L605 (Sec. 3.1.1)	CENTER	.071127	.064	64%	
30 Cycles	EDGE	.036066	.043	85%	
Rene' 41 (Sec. 3.1.2)	CENTER	.127330	.033	144%	
100 Cycles	EDGE	.076239	.114	73%	
TDNiCr (Sec. 3.2) 50 Cycles	(Sec. 3.2) .013305		.064	40%	
Haynes 25 (Sec. 3.3) 20 Cycles		.170290	.100120	48%	



5.0 THERMAL PROTECTION SYSTEM DESIGN CRITERIA

During the course of Phases I, II, and III of this program several factors affecting creep of metallic TPS and considerations in the design and analysis of metallic TPS have been identified. During Phase I (Reference 1) tensile creep testing was conducted on L605, Ti-6A1-4V, Rene' 41, and TDNiCr specimens under both steady state and cyclic loading and temperature conditions. Test matrices were established to provide maximum data throughout the temperature, stress, and strain range of interest with a minimum number of tests. Resulting data were analyzed to provide empirical equations expressing both steady state and cyclic creep strain as a function of temperature, stress, and time. Additional tests were conducted to evaluate other factors influencing cyclic creep strain such as the applicability of creep accumulation theories and effects of test time per cycle and material thickness. During Phase II (Reference 2) methods were developed for predicting creep deflections of thin gage metallic thermal protection system panels subjected to complex temperature and loading environments. Subsize panels, fabricated from the same material as used in Phase I, were tested to provide data for analysis verification. In the analysis of these data, factors such as sensitivity of the prediction to temperature variations were studied and expected accuracies were noted. Analysis of full size TPS panel test data in Phase III provided additional insight into expected analysis accuracies.

This section summarizes program results in a format which can serve as a criteria in accounting for creep in the preliminary design of metallic thermal protection systems. In addition to specific information obtained on this program, applicable experience based on results from other programs felt applicable to creep of TPS is also included.



5.1 GENERAL CONSIDERATIONS

Critical Design Conditions

TPS panels must first be sized based on strength and stiffness considerations over the entire range of flight conditions. The material choice is dictated by the peak temperatures occurring during entry. Critical design conditions have generally been found to be peak pressure loads and acoustic loadings occurring at relatively low temperatures during ascent or cruise conditions. Envelopes of panel strength and flight conditions such as that demonstrated in Figure 5-1 are helpful in visualizing the critical conditions for these panels. The example shows the panel to be critical during cruise where the peak pressure is applied at low temperatures. The panel strength then exceeds requirements throughout the remainder of the mission.

Panel Deflections

Deflections which must be considered are elastic deflections of the panel under applied differential pressure loads, thermal deflections which result from temperature gradients through the panel depth, and permanent creep deflections which accumulate throughout the life of the TPS panel. Various allowable deflections have been established such as those in References 9 and 10 which are shown in Equation (1) and (2) respectively.

$$\delta = .25 + .01L \text{ cm} \tag{1}$$

$$\delta = .25 + .04L [(B.S.-30.5)/280] \text{ cm}$$
 (2)

where B.S. = VEHICLE BODY STATION

These equations provide for maximum deflections of .75 cm and 2.25 cm (@ B.S.=787 cm (310 in)), respectively for a 50 cm (20 inch) long panel. Allowable total deflections must be established for each system based on the thermodynamic and aerodynamic requirements.

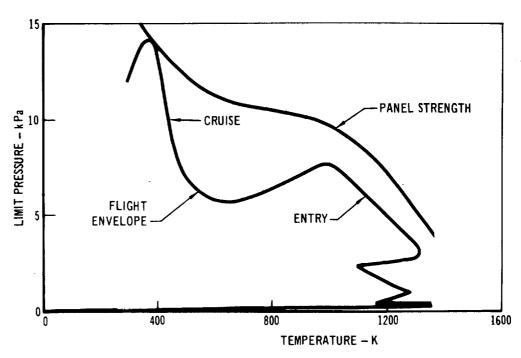


FIGURE 5-1 L 605 PANEL STRENGTH FOR FLIGHT ENVELOPE

The relative importance of thermal deflection has generally not been assessed in past studies. These deflections will be zero during steady state conditions where temperatures are uniform through the panel depth. During heating, when the maximum temperature occurs on the outer surface of the panel, the deflections will be in the opposite direction from the elastic and accumulated creep deflections.

Panel Replacement and Inspection

In the context of panel deflections, a failure will be an excessive deflection which requires panel replacement. Requirements for the panel design deflections will result from trading off refurbishment cost against any weight penalty which might result from the necessity to resist creep deflections.

It is expected that panels in one area of the vehicle might creep much faster than in other areas due to particular mission maneuvers, etc. Therefore, replacement of same panels may be required after each mission. It does not seem to be desirable or possible to optimize these panels from the standpoint of deflection over the entire vehicle since the mission requirements will provide considerable variation in applied loadings from one mission to another and from one location to another location on the vehicle. Visual inspection with spot centerline measurements, using a simple bar/dial gage tool would be sufficient to detect excessive deflections.

5.2 DESIGN CONSIDERATIONS - THERMAL EXPANSION

One of the primary considerations in the design of TPS panels is that the panel be allowed to expand freely under thermal loadings. Allowances must be made for thermal expansion both at the panel joints and on the panel surface.

Expansion is generally accomplished at the joints by fixing the panel at one end and allowing it to slide longitudinally at the other end. Transverse deflections are accomplished by slotted holes at both attachment locations and by

providing for expansion in the longitudinal joints between adjacent panels. Typical designs can be found in References (3) and (11).

Temperature variations along the panel length due to the heat sink at the panel support cause thermal stresses in the transverse direction. During heat up of the panel, the midspan is hotter than the edges at the supports causing compressive stresses at the center and tensile stresses at the edges. These stresses are reversed during cooldown.

The presence of beads relieves the thermal stresses and prevents thermal buckling (Reference 12) of the thin skin between stiffeners by allowing the skin to flex as thermal expansion occurs. Analysis can be used to define required bead depths. Particular attention should be given to the approach for closing out the bead near the panel ends. Testing (Reference 3) has shown that cracking can occur in the skin at the tips of the beads where the beads are transitioned into a flat skin. It would be desirable from this standpoint to extend the bead to the panel ends. This, however, complicates the design at the panel joints.

5.3 DATA REQUIREMENTS FOR CREEP ANALYSIS

During Phase I (Reference 1) testing was conducted under both steady state and cyclic conditions to evaluate the creep response characteristics of the materials studied and to provide data for use in the analysis for panel creep deflections. During these studies considerable effort was directed at obtaining the required test data.

Test Matrix - Basic Data Required

One of the objectives in evaluating creep deflections should be minimizing the required testing. However, it is of interest to cover the complete range of stress, temperature, time, and strain required to provide an adequate material response definition for use in the analysis. The analyst does not want to be in



the position where extrapolation of the available data is required.

The range of strain which is required will be dependent upon the criteria for allowable deflection used. As an example of possible calculations it could be assumed that creep deflections obtained in testing will be approximately 50% of those obtained using a linear creep stress-strain assumption. This assumption tends to account for the redistribution of beam stressed due to nonlinear creep strain-stress properties. The assumption is expressed in the following equation:

$$\frac{\Delta_{c}}{\varepsilon_{c}} = .5 \frac{\Delta_{E}}{\varepsilon_{E}}$$

where: Δ_{E} = BEAM midspan elastic deflection

 $\varepsilon_{\rm E}$ = Maximum midspan elastic strain (extreme fiber)

 Δ_c = Beam midspan creep deflection

 ε_c = Maximum midspan creep strain (extreme fiber)

Applying this equation and assuming an elastic deflection based on a uniform pressure loading the following equation can be derived for creep strain at the beam midspan.

$$\varepsilon_{\rm c} = \frac{2\Delta_{\rm c}}{\Delta_{\rm E}} \quad \varepsilon_{\rm E} = \frac{2\Delta_{\rm c}}{\frac{5}{384} \frac{\rm WL}{\rm ET}} \quad \frac{{\rm WL}^2 \, \overline{\rm Y}}{8 \, \rm E1} = 19.2 \, \frac{\Delta_{\rm c} \, \overline{\rm Y}}{\rm L}^2$$

Where: W = Beam pressure load

L = Panel length

E = Elastic modulus

I = Panel moment of inertial

 \overline{Y} = Maximum distance from neutral axis to extreme fiber

For a full size panel of 50 cm length, Δ_c = .75 cm (based on .25 + .01L cm criteria), and \overline{Y} = 1.5 cm, the required creep strain would then be .86%.



It is of interest to note that if this calculation was carried out for a shorter TPS panel, the creep strain required to attain the same creep deflection is higher because the strain is inversely proportional to the square of beam length. Therefore, use of a deflection criterion with subsize panels results in requirements for greater creep strains than would be attained in a full size panel under the same criterion.

Test matricles can be established on stress-temperature charts upon which approximate constant strain lines can be drawn. In the Phase I studies (Reference 1) these were based on evaluation of steady state literature survey data. Typical designs for the test matricles are shown in Figure 5-2 based on the Reference L605 evaluation. Requirements for the designs include:

- (1) Test data should be amenable to development of an empirical creep strain equation. Applicability of each design for satisfying this requirement can be checked by generating simulated creep strain data using an available equation, performing regression analysis, and evaluating the resulting prediction equation.
- (2) Test temperatures should cover the range of interest for the material being tested.
- (3) Test temperatures and stress levels should produce creep strains in the range of interest.

The designs shown in Figure 5-2(a) and (b) include a simple 3 x 3 factorial design and an orthogonal composite design. They are described in References 14 and 15. Although both designs satisfy the first requirement (1) above, they may satisfy the second or third requirements, in this case as indicated in the figure.

In addition to these two designs, the design shown in Figure 5-2(c) was also considered because it provides maximum coverage of the test temperature and stress range of interest. However, it was subsequently demonstrated that the resulting prediction equation, based on this design, was a function of time only.

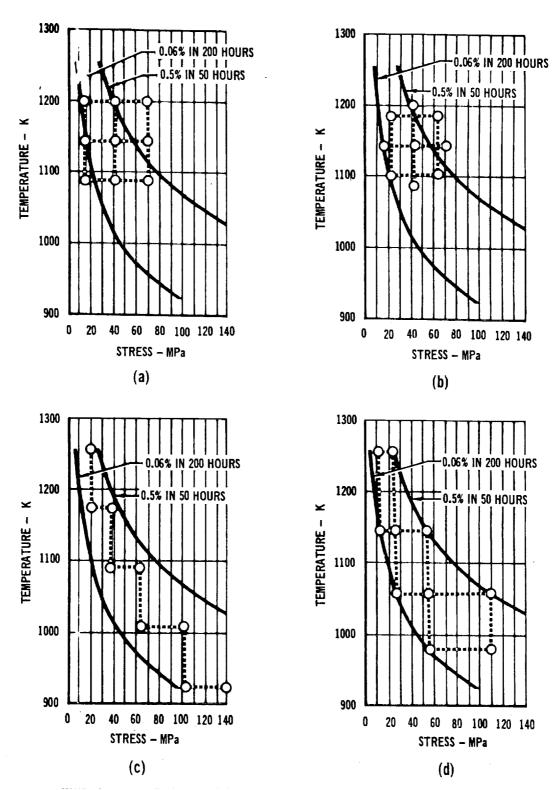


FIGURE 5-2 EXPERIMENTAL DESIGNS FOR CREEP TESTING

A fourth design considered is shown in Figure 5-2(d). This design allows testing over a wide stress and temperature range and evaluation of the design indicated that an empirical equation can be derived from the resulting data.

For the data range of interest in this program it was found that the design shown in Figure 5-2(d) was best.

The orthogonal composite design (Figure 5-2(b)) was, however, used in the Rene' 41 evaluation (Reference 1) where the lines of constant strain were found to be further apart on the stress temperature plot.

A study of proposed test designs is recommended, using applicable regression techniques, prior to conducting creep tests.

Determination of Empirical Equations

A very large number of equations are found in the literature which have been developed over the years to describe the complex physical process of creep. In addition, an infinite number of new relationships (or models) can be formulated.

The description of a new equation involves the determination of the relationship between the dependent variable, strain, and the independent variables, such as temperature, stress, time, thickness, and orientation. A convenient procedure for determining this relationship is the use of multiple regression techniques. Two parameters associated with this technique are (1) the multiple correlation coefficient, R, and (2) the standard error of estimate, S_y . The multiple correlation coefficient is a measure of how well the fitted equation explains the variation in the data (Reference 15). The closer the value of R^2 (or R) is to 1, the better the equation will fit the data. The standard error of estimate is an estimate of the variance about the regression line. Therefore, the precision of the estimate would be considered better the lower the value of S_y . Accordingly, in the development of the various regression equations that were examined during



the program, emphasis was placed on obtaining equations which resulted in large values of R and small values of $\mathbf{S}_{_{\mathbf{V}}}$.

The development and selection of each predictive equation generally followed an interative procedure as outlined below:

- Step 1 Select first order independent variables.
- Step 2 Using variables identified in Step 1, form new independent variables for the regression analysis consisting of higher order terms and interreaction (first and higher order) terms. Many computer programs are available to perform the regression analysis to determine the significant variables from the total identified and constructed in Steps 1 and 2.
- Step 3 Examine the residual of plots of the dependent variable vs. regressed variables. The residual is the difference between what is actually observed and what is predicted by the regression equation. If the proper variables were selected, the residual plots will have a uniform distribution with a zero mean. If the proper variables were not in the equation, then the residual plots tend to take a shape which indicates if the analysis should be weighted or a different term should have been used. An in-depth discussion of the examination of residuals and their significance is presented in Reference 15.
- Step 4 Repeat Step 2 using new variables and compare R and S with previously established values. Repeat Step 3 (i.e., review of plots of residuals) and form additional independent variables, if required.
- Step 5 Plot predicted creep responses and compare with experimentally observed creep curves with particular emphasis placed in identifying

discrepancies in fit and general form of the predicted surfaces.

Step 6 - If major discrepancies are observed in Step 5, modify and/or add

new independent variables and repeat from Step 2.

In general, the regression analyses will be conducted using the natural logarithm of strain, lns, as the dependent variable. There are two primary advantages in using logarithmic strain which are: (1) the model tends to come closer to minimizing the percentage deviations which is desirable, (2) the model can be forced to satisfy initial boundary value considerations. For example, the model

$$\ln \varepsilon = A_0 + A_1 \ln \sigma + A_2 \ln t$$

when transformed to strain becomes

$$\varepsilon = e^{A_0} \sigma^{A_1} t^{A_2}$$

and if σ or t equal zero, the strain is forced to also equal zero. Boundary conditions for the equations should be carefully investigated to insure applicability to low stress and time ranges required in the TPS panel analysis.

Another factor to be considered in obtaining empirical creep equations in the exclusion of high and low strains. By excluding higher strains, a small downward bias, as shown in Figure 5-3, is introduced in the predictive equations. Likewise, a small upward bias is introduced into the predictive equation at low strains when low strains are omitted as is also shown in Figure 5-3.

The justification for removing the low values of creep data is that a significantly higher percent experimental error exists in the measurement of these very low creep strains, and that the standard error of estimate can be dominated by these large observation errors. It should be noted that a weighted least squares analysis could also be performed which would account for the large variance in the low strain regime (Reference 15). However, the complexity of such an approach is greater.

5-11

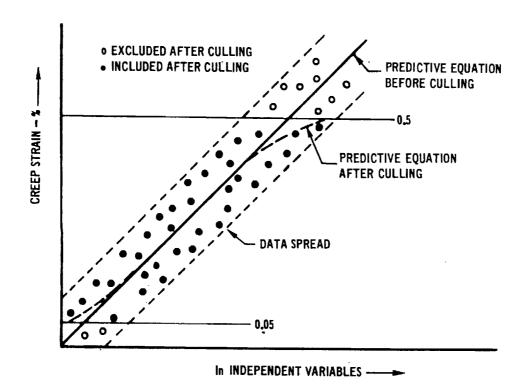


FIGURE 5-3 EFFECT OF CULLING LOW AND HIGH STRAIN DATA ON PREDICTIVE EQUATION DEVELOPMENT

Creep Accumulation Theories

The applicability of creep accumulation theories appears to be the most significant limitation in the analysis for TPS panel creep deflections. During the Reference 1 studies tests were conducted to provide data for evaluation of the hardening theories. An outline of the test profiles used are shown in Figure 5-4. The objective in these tests is to vary the load as a function of cycle to simulate the increasing or decreasing stress which will occur in a panel due to stress redistribution. Additional tests could also be conducted where temperature would be changed as a function of cycle since both temperature and load level change within a cycle is the analysis due to the varying profiles as well as the stress distribution. Predictions of these tests results can be made using empirical equations developed from constant stress and temperature cycle test data, allowing assessment of the various hardening theories.

Additional Factors Influencing Creep

Assessment of other factors affecting creep may also be important. These factors may include material gage, rolling direction, and possibility of material creep recovery. Evaluation of the effects of atmospheric pressure on creep was also investigated during the Phase I work but was found to have an insignificant effect on the materials investigated. Tensile creep tests can be conducted to assess these effects, if necessary. Steady state tests of specimens at replicate conditions should generally be sufficient to determine any significant variations due to material gage or material rolling direction. No recovery effects were determined for the materials studied based on cyclic tensile testing in Phase I (Reference (1)).



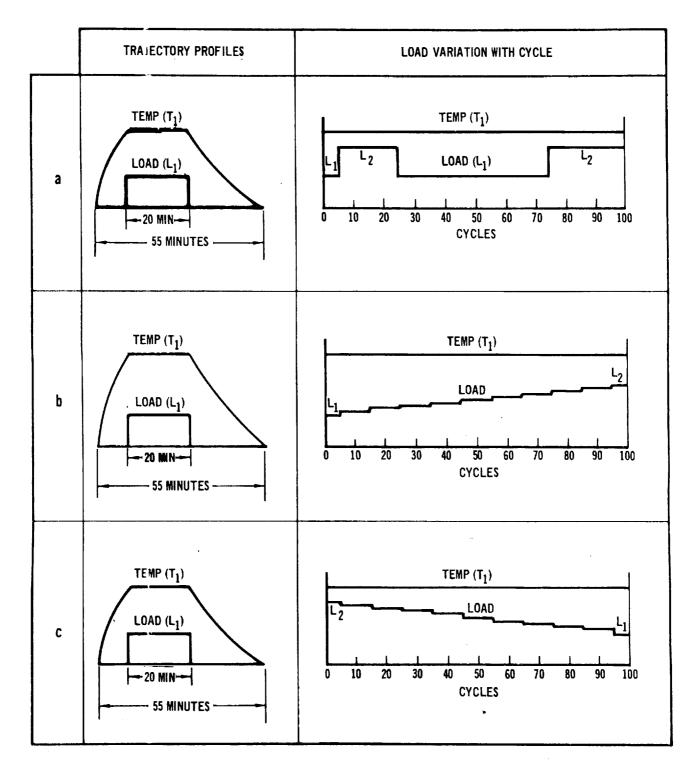


FIGURE 5-4 TESTS FOR EVALUATION OF CREEP ACCUMULATION THEORIES



Sensitivity of Creep Strains to Test Accuracy

In conducting tests to assess creep response characteristics of materials, particular attention should be given to maintaining accuracy, since predictions of creep deflections have been demonstrated to be sensitive to variations in temperature and load. Examples of these variations for the empirical equations of L605, Rene' 41, and TDNiCr are presented in Table 5-1 at a time of 20 hours. Based on results of Phase II (Reference 2) and Phase III, prediction accuracy within a factor of 2 should be attainable.

5.4 CREEP DEFLECTION ANALYSIS

Procedures developed for prediction of creep deflections in Thermal Protection System panels are presented in Reference 2 and Appendix B. Included in these references are the approaches and assumptions made in modeling the thin gage panel structures and in performing the analysis to obtain creep deflections. Steps in the analysis are (a) the development of a linear equation describing the logarithm of strain as a function of stress, temperature, and time, (b) idealize the selected loading and temperature profiles into constant steps, and (3) determine deflections using analysis capabilities of the TPSC computer program. Required input in terms of panel temperature distributions, panel geometry definition, and program control parameters are presented in Appendix B. The time hardening theory of creep accumulation has been found to provide the best predictions for subsize panel test results (Reference (2)) and is, therefore, recommended for use in the analysis.



TABLE 5-1. SENSITIVITY OF CREEP STRAINS TO TESTING ACCURACIES

MATERIAL		RAMETERS IN IN CALCULATION STRESS TIME		CREEP STRAIN %	STRAIN VARIATION DUE TO 1% TEMP. CHANGE	STRAIN VARIATION DUE TO 1% STRESS CHANGE
L605	1144K (1600°F)	55 MPa (8 KSI)	20 HR.	.615	14.4	3.0
RENE' 41	1089K (1500°F)	138 MPa (20 KSI)	20 HR.	.270	25.8	2.2
TDNiCr	1478K (2200°F)	35 MPa (シ :おエ)	20 HR.	.076	5.8	2.0

Selection of "Typical" Profiles

The sensitivity of creep predictions to the temperature profile selection will be illustrated in this section. The curve of creep strain vs. temperature shown in Figure 5-5 is calculated based on the L605 empirical creep equation generated from cyclic tensile tests (Reference Table 2-1). Specific stress and time for the calculated curve are 55 MPa (8.0 ksi) and 20 hours, respectively. The table included in the figure shows resulting creep strains at several temperatures. Also included in the table are the average creep strains over 110K (200°F) temperature increments (i.e. average of strains at T+55K and T-55K) and the percentage errors in creep strain which could result from using the median temperature in each 110K temperature spread. Thus, for example, for a temperature range of 1033 K (1400°F) to 1144K (1600PF) the average strain would be .362 which is 35%higher than the value .269 predicted at the median temperature of 1089K (1500°F). This example illustrates the sensitivity of creep strain to temperature and demonstrates that factors such as this should be considered in selecting typical trajectory profiles for analysis. Generally, temperatures higher than the median over the desired range will need to be used in order to arrive at average creep strains and deflections.

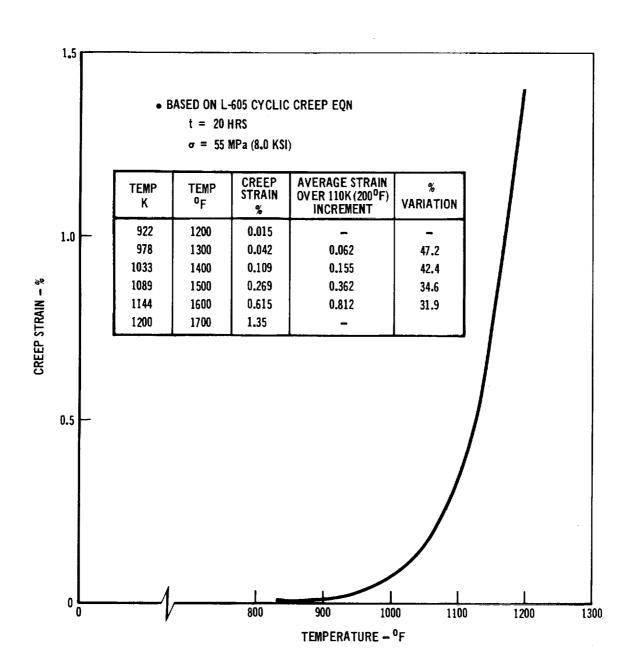


FIGURE 5-5 VARIATION OF CREEP STRAIN WITH TEMPERATURE



Idealization of Load and Temperature Profiles

Some observations related to idealization of load and temperature profiles into constant steps have been noted during the program. Observations, based on comparison of tensile test results in Phase I (Reference 1) and subsize panel data analysis in Phase II (Reference 2) have indicated that a rather simple representation of four time steps in these studies resulted in successful analysis. It was shown that a large number of time steps would not improve prediction accuracy. An example of the steps used is shown in Figure 5-6.

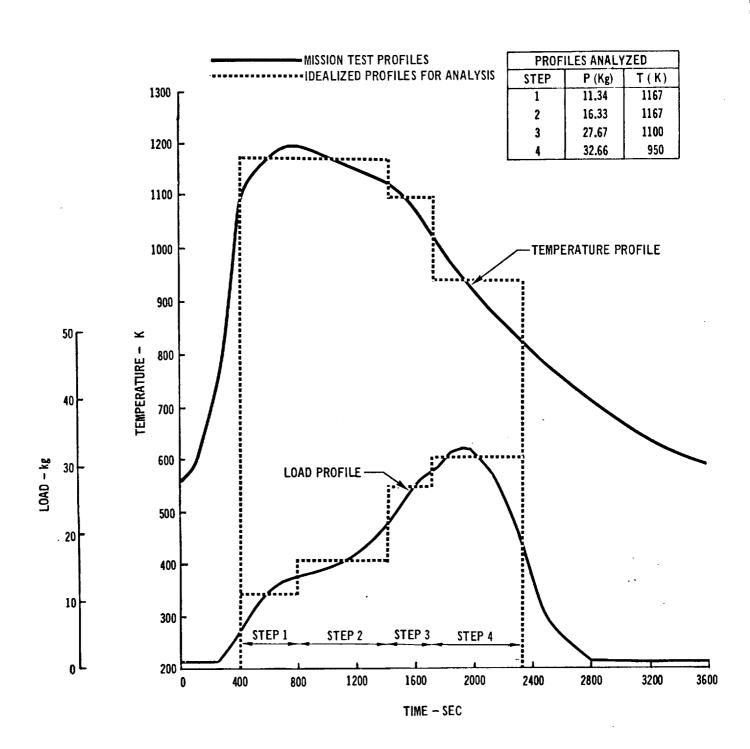
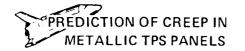


FIGURE 5-6 PROFILE IDEALIZATION FOR ANALYSIS

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6.0 REFERENCES

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APPENDIX A

CONVERSION OF U.S. CUSTOMARY UNITS TO SI UNITS

CONVERSION OF U.S. CUSTOMARY UNITS TO SI UNITS

The International System of Units (designated SI) was adopted by the Eleventh General Conference on Weights and Measures in 1960. The units and conversion factors used in this report are taken from or based on NASA SP-7012, "The International System of Units, Physical Constants and Conversion Factors - Revised, 1969".

The following table expresses the definitions of miscellaneous units of measure as exact numerical multiples of coherent SI units, and provides multiplying factors for converting numbers and miscellaneous units to corresponding new numbers of SI units.

The first two digits of each numerical entry represent a power of 10. An asterisk follows each number that expresses an exact definition. For example, the entry "-02 2.54*" expresses the fact that 1 inch = 2.54×10^{-2} meter, exactly, by definition. Most of the definitions are extracted from National Bureau of Standards documents. Numbers not followed by an asterisk are only approximate representations of definitions, or are the results of physical measurements.

ALPHABETICAL LISTING

To convert from	to	multiply by
atmosphere (atm) Fahrenheit (F)	pascal (Pa) kelvin (K)	$t_k = (5/9) (t_f + 459.67)$
foot (ft)	meter (m)	-01 3.048*
inch (in.)	meter (m)	-02 2.54*
mil	meter (m)	-05 2.54*
millimeter of mercury (mm Hg)	pascal (Pa)	+02 1.333
nautical mile, U.S. (n.mi.)	meter (m)	+03 1.852*
pound force (1b _f)	newton (N)	+00 4.448*
pound mass (1b _m)	kilogram (kg)	-01 4.536*
torr (0°C)	pascal (Pa)	+02 1.333



APPENDIX A - Continued

PHYSICAL QUANTITY LISTING

Ar	e	a
	_	_

To convert from	to	multiply by	
foot ² (ft ²)	meter ² (m ²)	-02 9.290*	
inch ² (in ²)	meter ² (m ²)	-04 6.452*	
inch ² (in ²)	cemtimeter ² (cm ²)	+00 6.452	
	Density		
pound mass/foot ³ (pcf,1b _m /ft ³)	$kilogram/meter^3 (kg/m^3)$	+01 1.602	
pound mass/inch ³ (lb _m /in ³).	$kilogram/meter^3 (kg/m^3)$	+04 2.768	
pound mass/inch 3 ($1b_{ m m}$ /in 3)	$gram/centimeter^3 (g/cm^3)$	+01 2.768	
	<u>Force</u>		
kilogram force (kg _f)	newton (N)	+00 9.807*	
pound force (1b _f)	newton (N)	+00 4.448*	
round letter (Log,			
	Length		
foot (ft)	meter (m)	-01 3.048*	
inch (in.)	meter (m)	-02 2.54*	
micron	meter (m)	-06 1.00*	
mil	meter (m)	-05 2.54*	
mile, U.S. nautical (n.mi.)	meter (m)	+03 1.852*	
	Mass		
pound mass $(1b_m)$	kilogram (kg)	-01 4.536*	
	Pressure		
atmosphere (atm)	pascal (Pa)	+05 1.013*	
millimeter of mercury (mm Hg)	pascal (Pa)	+02 1.333	
newton/meter	pascal (Pa)	00 1.00*	
pound/foot ² (psf, lb _f /ft ²)	pascal (Pa)	+01 4.788	
pound/inch ² (psi, lb_f/in^2)	pascal (Pa)	+03 6.895	
	Temperature		
Fahrenheit (F)	Kelvin (K)	$t_k = (5/9)(t_f + 459.67)$)



APPENDIX A - Continued

Volume

To convert from	<u>to</u>	multi	ply by
foot ³ (ft ³)	$meter^3$ (m^3)	-02	2.832*
$inch^3$ (in^3)	$meter^3$ (m ³)	-05	1.639*
$inch^3$ (in^3)	centimeter 3 (cm 3 , cc)	-01	1.639

PREFIXES

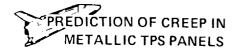
The names of multiples and submultiples of SI units may be formed by application of the prefixes:

Prefix	
micro (µ) milli (m) centi (c) deci (d) kilo (k) mega (M) giga (G)	

APPENDIX B

USERS INFORMATION THERMAL PROTECTION SYSTEM CREEP (TPSC)

COMPUTER PROGRAM



B.1 INTRODUCTION

The computer program described herein, Thermal Protection System Creep (TPSC), uses iterative techniques and numerical integration to predict creep strains, residual stresses, and permanent deflections in stiffened panel structures. This program was developed jointly under internal MDAC funding and NASA Langley Research Center contractual funding. Initiated at MDAC in 1971, the program has been continually modified to increase its capability. Although the TPSC Computer Program was developed for analysis of creep deflections in thermal protection system panels, it is applicable to creep analysis in any beam or stiffened plate structure subjected to bending loads. The TPSC program is written in CDC Fortran IV and is operational on the MCAUTO/CDC 6000 series computers using KRONOS operating systems.

A flexible, user oriented input format is used. Input data include panel geometry and definition of loading and temperature profiles. Panel temperature distributions along the panel length and through the depth can be input using either polynomial equation coefficients or tabular input. Temperatures at each location in the panel are based on these distributions and the input temperature-time profile data. Also, input are equation coefficients to define material creep response as a function of time, stress, and temperature.

Program output includes a record of input data and calculated geometrical data (elastic moment of inertia), trajectory load and temperature data, and creep equation definition as well as the calculated deflections, creep strains, and residual stresses.

The program was developed specifically for analysis of thermal protection system panels. Therefore, definition of leading structural concepts, corrugation



TPSC program. Modeling of the specific panel structural concept for analysis is accomplished automatically based on overall section input definition. Appropriate use of input parameters also allows analysis of rectangular and I-beam sections. An option is provided for including a beaded skin into any of the cross sections since beads are frequently required in thermal protection system panel designs.

Bending moments are internally defined based on uniform pressure load input or two point load input. In addition, the moments can be calculated as a function of panel edge support stiffness and the ratio of panel stiffness in the longitudinal and transverse directions. This option is based on combining solutions for an isotropic plate with two sides simply supported and two sides elastically supported as offered by Timoshenko (Reference 4) and the solution for an orthotropic plate with four sides simply supported as offered by Lekhnitskii (Reference 5). This option provides a first order approach to account for Poisson's effects in orthotropic plate structures.

Sensitivity of predicted results to the number of elements defining panel cross section and the number of stations defining panel length has been investigated with the goal of providing guidelines for minimizing required computer time.

Computer time increases almost linearly with number of analysis steps specified.

The minimum number of stations along the length and elements through the depth which can be used to maintain good prediction accuracy have been defined.

The TPSC computer program provides needed capability for prediction of permanent deflections, due to creep, in entry vehicle metallic thermal protection system panels. Application is also envisioned in other structures where creep deflections may be important such as in missile structures and nuclear reactors.



B.2 METHOD OF ANALYSIS

Within the TPSC program the panel length is divided into i stations over which bending moments are assumed constant and the panel depth is divided into j elements over which stresses are assumed constant as indicated in Figure B-1.

Using the assumption of a linear total elastic plus creep strain distribution through the depth, the neutral axis and structural rotation are systematically varied at each station and time step to determine the unique stress distribution which satisfies both force and moment balance requirements. At each point in the panel the creep component of total strain is determined based on either the time hardening or strain hardening theory of creep accumulation applied in conjunction with input analytical expressions defining material tensile creep response as a function of stress, temperature, and time. Residual stresses are calculated at each time step by subtracting the elastic stress from the total calculated stress. These residual stresses are used at initiation of analysis for the next time step. Analysis proceeds through all the time steps at each designated station along the panel length, accumulating and storing structural rotations, creep strains, and residual stresses. At the completion of analysis, rotations are numerically integrated to determine creep deflections.

The following assumptions are made in the analysis:

(a) Only bending stresses are considered in the analysis. Deflections due to shear are assumed negligible.

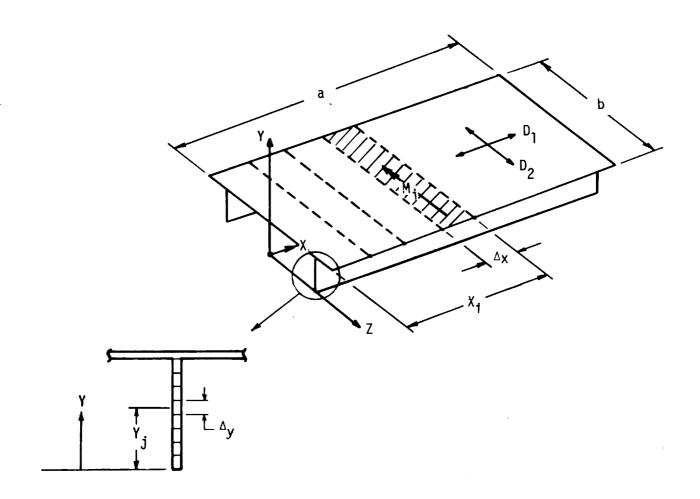


FIGURE B-1. PANEL REPRESENTATION FOR ANALYSIS



- (b) Strain distributions through the panel depth are linear.
- (c) Creep response equations, defined by the user, are assumed to be applicable for both tensile and compressive stresses.
- (d) Load and temperature distributions and calculated deflections are assumed symmetrical with respect to the panel centerline (X = a/2).
- (e) Panels are thin gage. (Although the analysis is not restricted to thin gages, the approach for modeling specific section geometries incorporated into the program has been based on this assumption.)

Approaches used for important program calculations are presented in this section. The general analysis flow is shown in Figure B-2 for reference purposes.

B.2.1 Geometry Definition

Analysis capability for three thermal protection system structural concepts; rib stiffened (INDGEO = 1), corrugation stiffened (INDGEO = 2), and zee stiffened (INDGEO = 3), is incorporated into the TPSC program. The number of stiffeners across the panel width are defined by NRIB, NCOR, and NZEE for the rib, corrugation, and zee stiffened concepts, respectively. A skin bead in either the positive y or negative y direction can be included in the cross sections at the user's option (INDBD = 1). The direction of the skin bead is specified by the sign of the input bead radius (BRAD) where a + sign designates the bead in the + y direction from the skin. Geometry of the TPS cross sections and skin bead, defining program input variables, are shown in Figure B-3.

The approach for modeling the rib stiffened, corrugation stiffened, and zee stiffened subsize TPS panels is shown in Figure B-4. The number of stations in half the panel length are defined by input variable NSTAT. This is defaulted to 6 when not input by the user. The number of elements through the panel depth is defined by input variables NSECT and SEC. These are both defaulted to 10

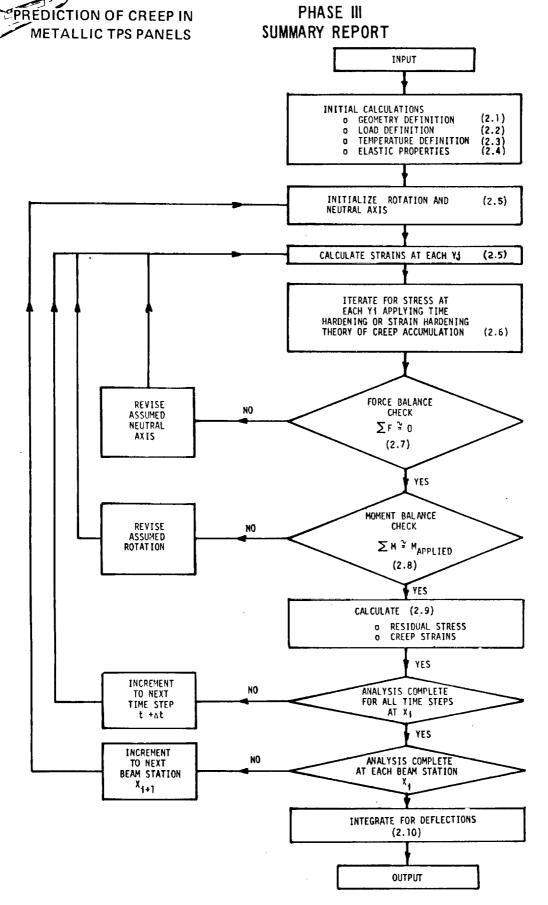
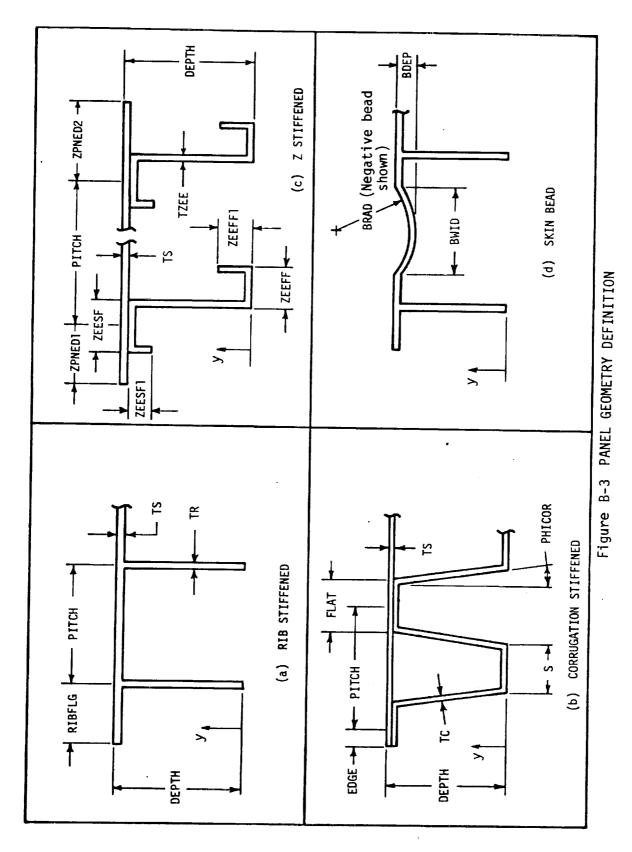
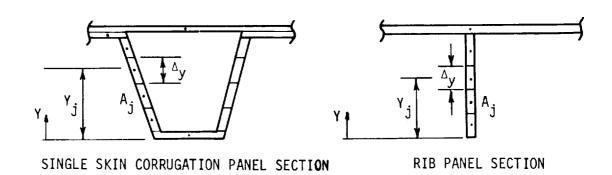


FIGURE B-2 TPSC PROGRAM ANALYSIS FLOW





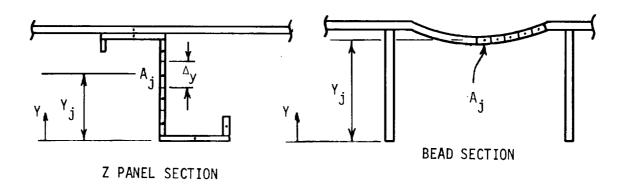


FIGURE B-4 STRUCTURAL MODELING OF PANEL AND CROSS SECTIONS



when not input by the user. Two variables (fixed point (integer) and floating point (real)) are used in order to make the program as machine independent as possible. The assumption of thin gages allows skin and horizontal stiffener sections (e.g., skin) to be defined as individual elements. Vertical portions of the stiffeners (e.g., ribs) are divided into ΔY elements based on the input total number of elements (NSECT, SEC) minus the number of horizontal elements. Therefore, for example, the calculation for ΔY for the corrugation concept is ΔY = [DEPTH-TS-2(TC)]/(NSECT-3). For beaded skins five additional elements are added into the cross section as shown in Figure B-4. Centroids and areas of the cross section increments are used in all subsequent program calculations.

B.2.2 Load Definition

Panel bending loads are calculated based on input pressure (PRESS) or point loads (PLOAD) for each time step in the mission profile. These are selected by inputting INDLOD=0 for pressure load and INDLOD=1 for point loads. Calculations of beam bending moments under the pressure and point load options are shown in Figure B-5. Input XLGTH and PANWID values correspond to a and b respectively. All applied loads are assumed symmetrical about the panel centerline. Units for PLOAD are Lbs or Kg where the input value is the total panel load. Input pressure units are Pa/cm² or Lbs/in². The panel width is included in the pressure loading calculations to yield the total panel bending moment at each beam station. The option for applying point loads to the panel, was specifically included to allow analysis of subsize panel test data (Reference 2). For this type of loading the distance (ALEN) from the support to the point of load application is input. Analysis for a single midspan point load can be implemented by making ALEN equal to one half of the panel length.

For panels loaded with a uniform pressure, an option is included for modifying the bending distribution (INDPLA=1) to account for plate effects. The plate option provides a first order approach to account for Poisson's effects and edge stiffness

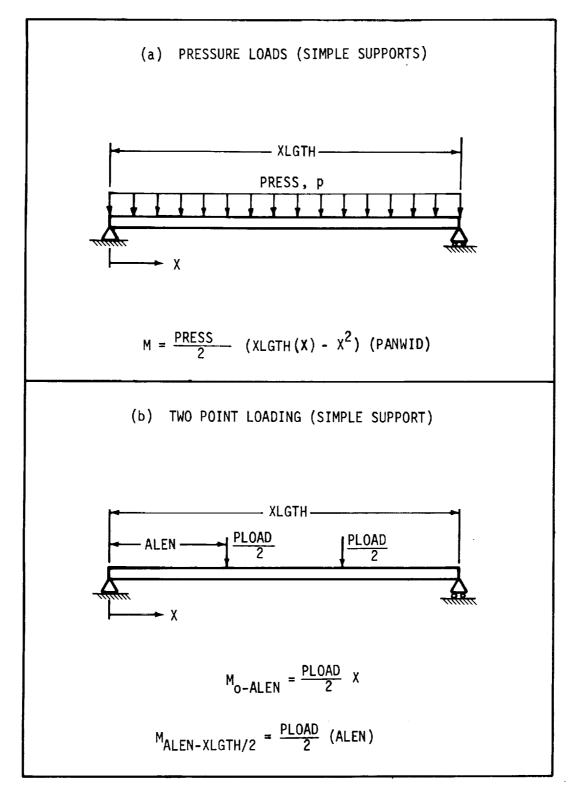


Figure B-5. LOAD OPTIONS

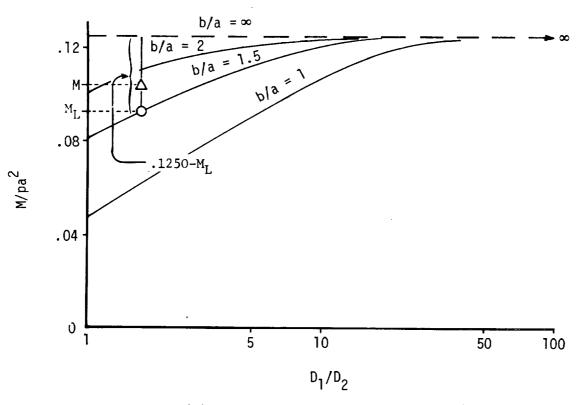
effects in orthotropic plate structures by combining solutions for an isotropic plate with two sides simply supported and two sides elastically supported as offered by Timoshenko (Reference 4) and the solution for an orthotropic plate with four sides simply supported as offered by Lekhnitskii (Reference 5). This option is restricted to panels where b>a and $D_1>D_2$ (Figure B-1). The value D_1 is calculated in the program. Stiffness in the transverse direction (D_2) can be input (using the variable DETWO) or calculated, based on skin thickness as $(TS)^3/12(1-v)^2$. The parameter λ defining the relative stiffness of the edge support and the panel is calculated as $\lambda = ESTIFF/aD_1$ where ESTIFF is the input support stiffness along the edges $Z = \frac{1}{2} b/2$.

Panel midspan (Z=0, X = a/2) bending moments for typical b/a values are shown in Figure B-5(a) and B-5(b) as functions of the quantities λ and D_1/D_2 respectively. These solutions are combined in the analysis by assuming that the variation of moment as a function of λ , will be applicable at all D_1/D_2 values. This assumption is felt to be justified because it is exactly applicable at $D_1/D_2 = 1$ (isotropic panel) and any variations at other D_1/D_2 will be a small portion of the total moment since values are constrained in a narrow range (Figure B-5(b)).

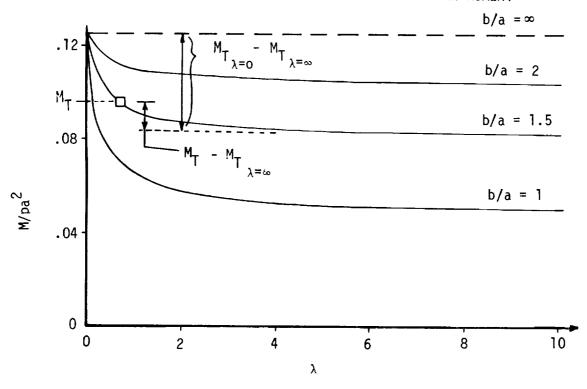
In computing the midspan moment M, the moment M_L for the orthotropic plate with four sides simply supported (Figure B-6(b)) is first calculated. This moment is then increased based on the degree of edge support using the calculated moment M_T for an isotropic plate (Figure B-6(a)). The solution for M (Figure B-6(b)) is then calculated based on the relationship that the increase in moment (M-M_L) toward .125 pa² will be proportional to the increase ($M_T - M_{T_{\lambda=\infty}}$) due to panel edge stiffness.

This results in the equation

$$\frac{\text{M} - \text{M}_{\text{L}}}{\text{.1250 - M}_{\text{L}}} = \frac{\text{M}_{\text{T}} - \text{M}_{\text{T}}_{\lambda=\infty}}{\text{M}_{\text{T}} - \text{M}_{\text{T}}_{\lambda=\infty}}$$







(a) TIMOSHENKO SOLUTION - MIDSPAN MOMENT FIGURE B-6 PLATE BENDING MOMENT SOLUTIONS

B - 13



which yields

$$M = M_{L} + (.1250 - M_{L}) \frac{M_{T} - M_{T}}{M_{T} - M_{T}}$$

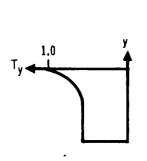
$$M_{T} - M_{T}$$

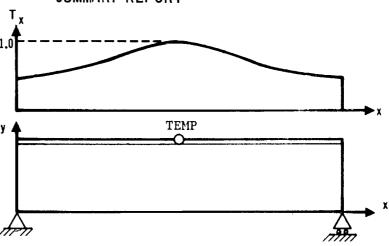
Moments along the panel length are calculated based on ratioing the beam bending moment distribution (Figure B-5(a)), using the equation B-1 value at midspan.

B.2.3 Temperature Definition

Panel temperature distributions are defined by input of the panel midspan skin temperatures at each mission time step, the distribution of temperature through the panel depth, and the distribution of temperature along the length. Normalized temperature distributions, referenced to the midspan skin temperature, are input, as indicated in Figure B-7(a). The midspan skin temperature (TEMP) is input for each trajectory time step (DXTIME) up to the number of steps (NTIME). Distributions through the panel depth and along the length are defined by either of the following approaches.

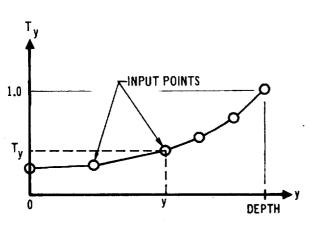
- (1) A table lookup routine is included in the program to calculate T_x and T_y as functions of X and Y, respectively, based on tabular input. The distribution along the panel length (INDTFL = 1) and through the panel depth (INDTFD = 1) are input using the variables XTEMP and YTEMP, respectively. Temperatures (normalized to 1.0 at the midspan skin) are input to define these distributions as shown in Figure B-7(b). The distribution T_y is assumed to be the same at each location along the panel length. Temperature is calculated, at each point in the panel, as the product of TEMP (function of time), T_x (function of length), and T_y (function of depth). T_x and T_y are determined using linear interpolation between input points as shown in the figure.
- (2) Temperature can be defined by the input of coefficients (C and D) to the following polynomial equations.

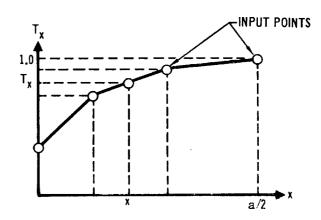




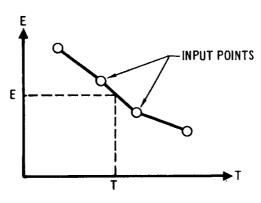
$$T = TEMP (T_x) (T_y)$$

(a) Temperature Defined as Function of Panel Length and Depth





(b) Linear Interpolation for Temperatures



(c) Linear Interpolation for Elastic Modulus

FIGURE B-7 PANEL TEMPERATURE CALCULATIONS

$$T_X = C_1 + C_2 X + C_3 X^2 + C_4 X^3$$
 (B-2)

$$T_{Y} = D_{1} + D_{2}Y + D_{3}Y^{2} + D_{4}Y^{3}$$
 (B-3)

For this option the control variables INDTFL and INDTFD are defaulted to 0.

For temperatures defined by either of these options the control variable ITCON must be set equal to 0.

Elastic modulus data, for use in the analysis, are defined as a function of temperature by either of the same two approaches described for defining temperature distributions.

- (1) For using the table lookup routine, modulus and temperature data are input in tabular form using the input variable ETEMP, as shown in Figure 2-7(c). For this option the control variable INDMOD is input as 1.
- (2) The modulus can also be defined by equation coefficients (ECOEFF) to the equation:

$$E = ECOEFF_1 + ECOEFF_2(T) + ECOEFF_3(T^2) + ECOEFF_4(T^3)$$
(B -4)

B.2.4 Elastic Calculations

Elastic stresses (σ_e) , strains (ϵ_e) , and rotations (θ_e) at each station as well as the section neutral axis (\overline{Y}_e) and moment of Inertia (I) are calculated as follows, where the subscript j represents element location in the cross section (Figure B-4)

$$\frac{\sum_{j=1}^{NSECT} A_{j} Y_{j}}{\sum_{j=1}^{NSECT} A_{j}}$$
(B-5)

$$I = \sum_{j=1}^{NSECT} A_j Y_j^2 - \overline{Y}^2 \sum_{j=1}^{NSECT} A_j$$
(B-6)

$$\sigma_{e_{j}} = \frac{M_{i} (\overline{Y}_{e} - Y_{j})}{I}$$
(B-7)

$$\epsilon_{e_{j}} = \sigma_{e_{j}}/E$$
 (E = elastic modulus) (B-8)

$$\theta_{e,i} = \frac{M_i \Delta X}{E I}$$
 (B-9)

In the moment of inertia calculation, the moments of inertia of individual j elements, about their own neutral axes, have been found to be negligible and have not been included.

B.2.5 Iteration for Stress

At each beam station (X) the incremental rotation due to creep (θ_c) and neutral axis (\overline{Y}) are initialized as

$$\theta_{c} = \theta_{e} \tag{B-10}$$

$$\overline{Y} = \overline{Y}_{e}$$

Based on these values, the initial total strain assumed at each Y element (Y $_{\bf j}$) is calculated, using the linear total strain assumption

$$\varepsilon_{T_{j}} = (\theta_{c} + \theta_{e}) (\overline{Y} - Y_{j})/\Delta X$$
 (B-11)



For each j element through the cross section there is a unque value of stress (σ_j) which satisfies the equation:

$$\varepsilon_{T_{j}} = \varepsilon_{c_{j}} + \frac{\sigma_{j} + \sigma_{RESIDUAL_{j}}}{\varepsilon}$$
(B-12)

where $\sigma_{RESIDUAL}$ is the residual stress based on results from calculations in the previous time step (zero for the first step) and E is the material elastic modulus at the element temperature.

The incremental creep ($\epsilon_{\rm c}$) is a function of stress, temperature, time, and incremental time step based on the input creep strain equation (Section B.3.7) applied in conjunction with the hardening theories. Calculations of $\epsilon_{\rm c}$ as a function of stress, strain, temperature, and time for the strain hardening and time hardening creep accumulation theories are discussed in Section B.2.6.

In determining the value of stress at each element which satisfies Equation B-12, assumed stresses (designated by the subscript ℓ) are systematically varied and corresponding strains (ϵ_{ℓ}) are calculated. The subscript ℓ has been added in this section to designate stresses and strains calculated in the iteration process. The subscript j is applied to the final stresses determined at each element. The initially assumed value of stress σ_{ℓ} (ℓ = 1) is that obtained from analysis in the previous time step (elastic stress for the first time step). The assumption for the second value of σ_{ℓ} (ℓ = 2) is dependent on the value of σ_{ℓ} and the relationship between ϵ_{ℓ} and the calculated strains ϵ_{ℓ} (ϵ_{ℓ} for ℓ = 1) as follows:



(a)
$$\sigma_2 = -100$$
. psi. for $(\sigma_1 = 0$. and $\epsilon_{T_j} < \epsilon_1)$

(b)
$$\sigma_2 = +100$$
. psi. for $(\sigma_1 = 0$. and $\epsilon_{T_j} > \epsilon_1)$

(c)
$$\sigma_2 = 2 (\sigma_1)$$
 for $(\sigma_1 < 0.$ and $\varepsilon_1 > 0.$ and $\varepsilon_{T_j} < \varepsilon_1)$

$$(\sigma_1>0. \text{ and } \epsilon_1>0. \text{ and } \epsilon_T>0 \text{ and } \epsilon_T>0$$

$$(d) \quad \sigma_2=\sigma_1+|\sigma_1| \text{ for } \frac{\epsilon_1}{\epsilon_T}<.1 \text{ and } \epsilon_T>0$$

$$(B-13)$$

(e)
$$\sigma_2 = \sigma_1 - |\sigma_1|$$
 for $\frac{\epsilon_1}{\epsilon_T}$ <.1 and ϵ_{T_j} <0

(f)
$$\sigma_2 = \sigma_1 \frac{\varepsilon_T_j}{\varepsilon_1}$$
 for $\frac{\varepsilon_1}{\varepsilon_T_j} > .1$

Subsequent values of $\boldsymbol{\sigma}_{\varrho}$ are calculated by applying the equation

$$\sigma_{\ell} = \sigma_{\ell-1} + (\varepsilon_{T_j} - \varepsilon_{\ell-1}) \text{ SLOPE}$$
 (B-14)

where SLOPE = $(\sigma_{\ell-1} - \sigma_{\ell-2})/(\varepsilon_{\ell-1} - \varepsilon_{\ell-2})$

The process which is representative in Figure B-8 is continued until the stress is determined such that

$$\frac{\varepsilon_{\text{Tj}}}{\varepsilon_{o}}$$
 - 1. <.001

An analysis proceeds through each time step the neutral axis and rotation are initialized as equal to those calculated in the previous time step.

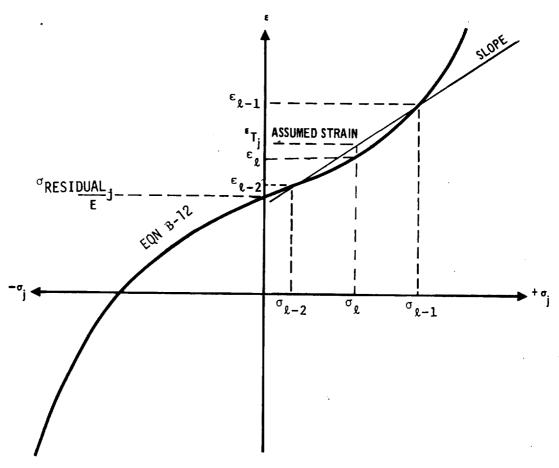


FIGURE B -8 ITERATION APPROACH FOR STRESS CALCULATION

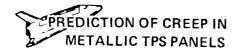


B.2.6 Hardening Theories

The time hardening and strain hardening theories of creep accumulation are provided in the TPSC program. These are selected through input of the control variable HARDOP = 1 and HARDOP = 2 respectively.

The time hardening theory of creep accumulation is based on the assumption that the creep rate is dependent upon the total time under load. This approach for calculation of incremental creep strains is shown in Figure B-9(a). Stresses are iteratively determined at each time step based on input creep strain equations.

The strain hardening theory of creep accumulation is based on the assumption that the creep rate is dependent upon total accumulated creep strain. This approach for calculation of incremental creep strains is shown in Figure B-9(b). Additional calculations are required under this option to determine the effective time, for which the given value of strain applies, at a new stress and/or temperature. Therefore, this option requires more computer time (Reference Section B.6). To facilitate analysis of mission profiles, a maximum time cutoff (TMAX) is input to prevent application of the creep equation beyond its range of applicability. For times beyond this time cutoff, the equation creep rate is assumed constant for each stress and temperature as indicated in the figure.



B.2.7 Force Balance Requirements

Having solved for stresses at each of the j element locations, the check for a zero force balance on the cross section is calculated as

$$F = \sum_{j=1}^{Notice} \sigma_{j} A_{j}$$

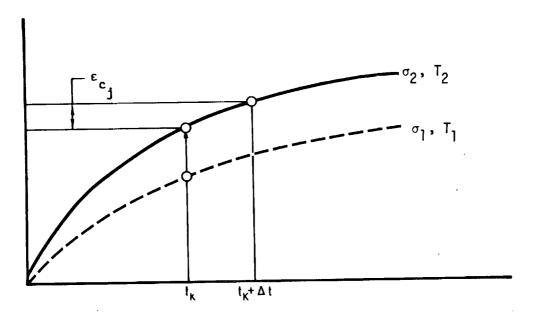
$$(B-15)$$

Based on the resulting sign (plus or minus) of F the neutral axis location is changed by $\overline{+}$ ΔY . That is, for example, if the neutral axis is located toward the tension side of the panel, resulting in an overall net compression load (F = negative), then the neutral axis must be moved toward the compression side (+Y direction). Strains and stresses are then recalculated. This process is continued until the sign of F changes, at which time the neutral axis location is calculated by linear interpolation using the equation

$$\overline{Y} = \overline{Y}_{m} - \frac{|F_{m}| (\overline{Y}_{m} - \overline{Y}_{m-1})}{|F_{m}| + |F_{m-1}|}$$
(B-16)

where m is a subscript used to designate the final two axis locations and associated force summations in calculating \bar{Y} . This process is indicated in Figure B-10. It should be noted that the neutral axis location is not constrained to coincide with the Y_{i} element centroids.





(a) Time Hardening

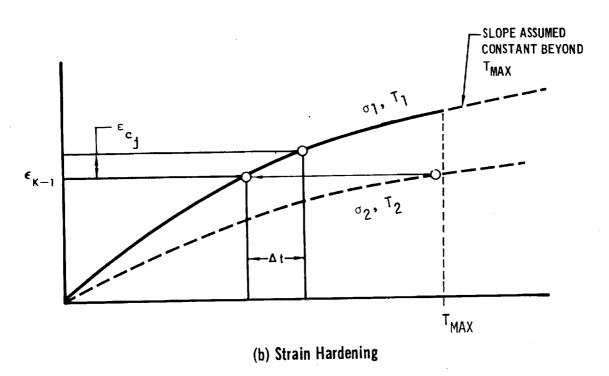
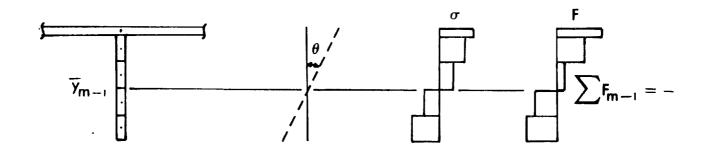
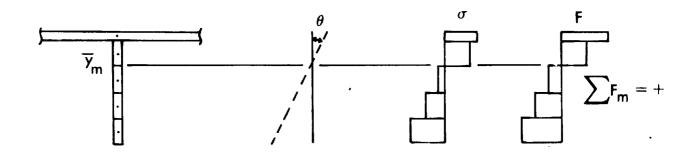


FIGURE B-9 HARDENING THEORIES FOR CREEP ACCUMULATION.







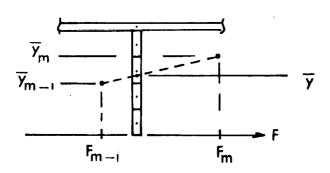


FIGURE B-10 FORCE BALANCE ITERATION APPROACH

B.2.8 Moment Balance Requirements

After force balance is attained at the cross section the check for moment balance at the station is calculated as

$$M_{1} = \sum_{j=1}^{NSECT} |\sigma_{j} A_{j} (\overline{Y} - Y_{j})|$$
(B-17)

The second estimate of θ is

$$\theta_2 = \theta_1 \binom{\text{Mapplied}}{M_1} \tag{B-18}$$

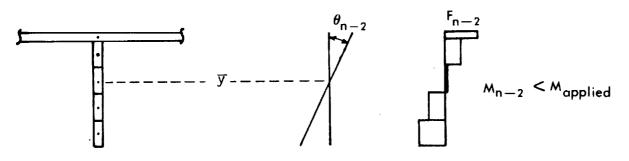
Subsequent assumed rotations are calculated based on the equation

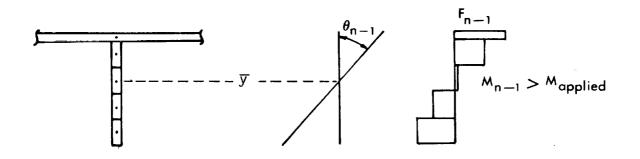
$$\theta_{n} = \theta_{n-1} + (M_{\text{applied}} - M_{n-1}) \frac{(\theta_{n-1} - \theta_{n-2})}{(M_{n-1} - M_{n-2})}$$
(B-19)

as depicted in Figure B-ll where n is a subscript used to designate the assumed rotations and associated moments calculated. Each M $_{\rm n}$ is compared to M $_{\rm applied}$ ' Balance is established when

$$\frac{\left|\frac{M_{n} - M_{applied}}{M_{applied}}\right|}{M_{applied}} < .001$$

The value of .001 for moment balance covergence was established to provide good solution accuracy within reasonable computer run times.





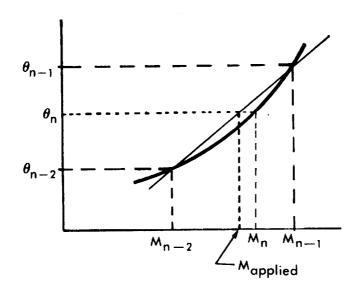


FIGURE B-11 MOMENT BALANCE ITERATION APPROACH

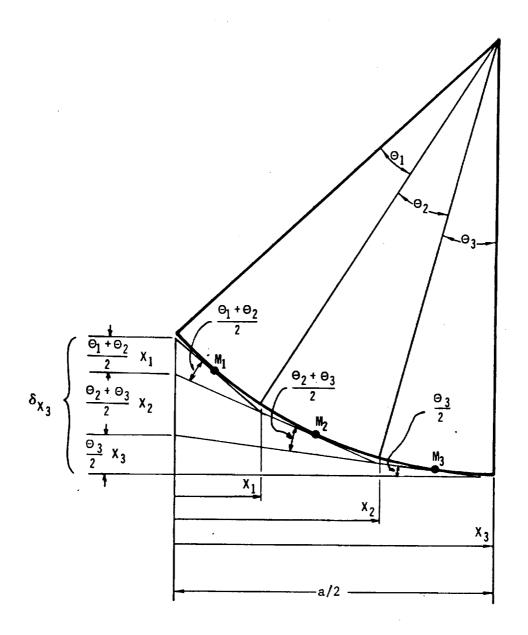


FIGURE B-12 APPROACH FOR CALCULATION OF DEFLECTIONS



B.2.9 Calculation of Creep Strains and Residual Stress

Once force balance and moment balance have been established the residual stresses and creep strains are calculated at each j element as

$$\sigma_{\text{RESIDUAL}_{i}} = \sigma_{e_{i}} - \sigma_{j}$$
 (B-20)

and

$$\varepsilon_{c_{j}} = \varepsilon_{T_{j}} - \varepsilon_{e_{j}} = \theta_{c} \frac{(\overline{Y} - Y_{j})}{\Delta X} - \frac{\sigma_{RESIDUAL_{j}}}{E}$$
(B-21)

In addition to calculation of residual stresses and creep strains for output purposes, these values are retained for use in subsequent analysis. Creep strains are required for use in strain hardening analysis and residual stresses are added to elastic stresses for initiation of the next analysis time step.

B.2.10 Deflection Calculations

Structural creep rotation (θ_c) and elastic rotations (θ_e) are calculated as a function of time and stored for use in numerical integration calculations for deflections.

These deflections are calculated at each station (subscript i), according to the following equations where NSTAT is the total number of beam stations in half the beam length and n is a dummy variable used to designate the beam stations

(i = 1 to
$$\delta_{X_i} = \sum_{n=1}^{\theta_n + \theta_{n+1}} X_n + \frac{\theta_{i+1}}{2} X_i + X_i = \frac{\theta_n}{\theta_n}$$
(B-22)

(1 = NSTAT-1)
$$\delta_{X_1} = \sum_{n=1}^{1} \frac{\theta_n^{+}\theta_{n+1}}{2} X_n + \frac{\theta_{NSTAT}}{2} X_{NSTAT-1}$$
 (B-23)

$$(i = NSTAT)^{\delta} X_{i} = \sum_{n=1}^{i} \frac{\theta_{n}^{+\theta} + \theta_{n}^{-1}}{2} X_{n}^{-1} + \frac{\theta_{NSTAT}}{2} X_{NSTAT-1}^{-1}$$
(B-24)

Values of θ are either elastic rotations or creep rotations for calculation of elastic deflections and creep deflections respectively. Shown in figure B-12 is a sketch of the rotations and midspan deflection (EQN B-24) for a beam with NSTAT = 3.



B.3 PROGRAM INPUT

The TPSC deck consists of control cards, the TPSC source deck, and input cases. End of record (EOR) cards terminate the control card deck and source deck and an end of information (EOI) card terminates the job deck. Deck setup is shown in Figure B-13. The program requires 102K of core to load and 72K to run under the KRONOS 2.1 operating system.

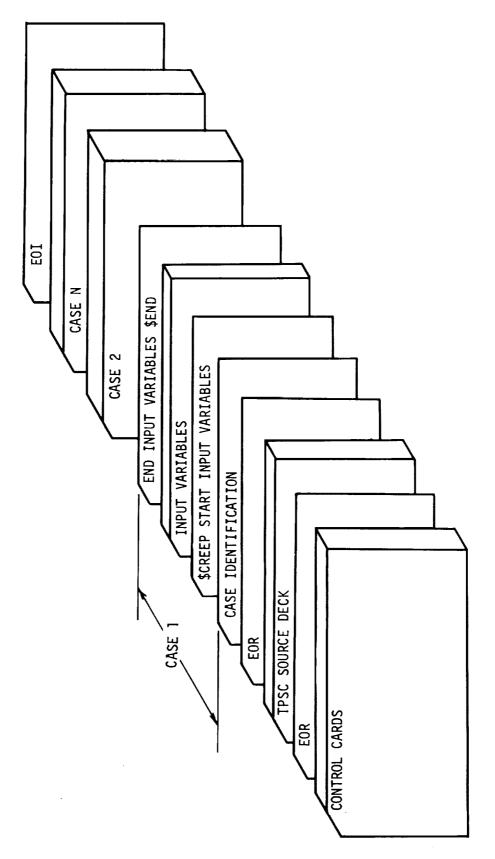
Input cases are stacked behind the source deck in the deck setup. The first card of each case must be a case identification card. Information listed in columns 1 through 50 on this card will be printed as a heading in the output for that case.

The remainder of data is input using a user oriented "namelist" format. This input follows the identification card for each case. The first card following the identification card must have a \$ in column 2 followed immediately by the name CREEP with no embedded blanks. Succeeding variables are read until a second \$ is encountered. Input variables are defined following the first \$. All except the last variable must be followed by a comma and the first column of each card is ignored. Constant fields may not include imbedded blanks. Blanks, however, may appear elsewhere in data records.

Examples of the input data are shown in figure B-14. Values for variable names beginning with the letters I, N and K are input without decimal points. Commas must immediately follow these values. Subscripted variables such as PRESS(N) are input as PRESS(1) = followed by the values for PRESS (1), PRESS (2), PRESS (3), etc (see example problem 2).

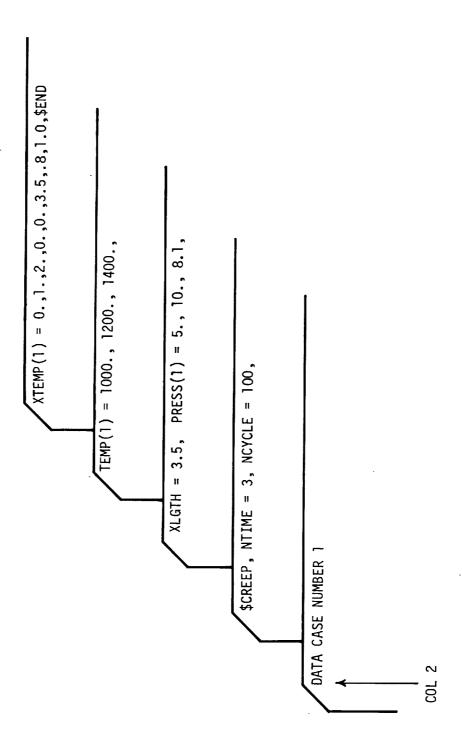
The general table lookup routine used in defining temperature distributions (XTEMP(N) and YTEMP(N)) and elastic modulus data (ETEMP(N)) requires special input considerations. Example input for XTEMP(N), is shown in figure B-14. This is typical also for YTEMP(N) and ETEMP(N). The values 0., 1., K, 0., X_1 , X_2 ,.... X_k , T_1 ,

Figure B-13 TPSC PROGRAM DECK SETUP



B-31







 T_2, \ldots, T_k are input following the variable name XTEMP(1) where K is the number of sets of location-temperature data (section 2.3), X_1, \ldots, X_k are the corresponding locations along the panel length, and T_1, \ldots, T_k are the associated normalized temperatures. The first, second, and fourth values (0., 1., 0.) are required input.

Listings of the input variables for the TPSC program are given in Tables B-1 through B-7. For variables where default values are provided, no input need be made except to use options other than those provided for by the default. Example problem inputs are given in Section B-8.



Table B.1 INPUT FOR ANALYSIS CONTROL

DEFINITION	INPUT VARIABLE NAME	INF	PUT VALUE
Option for Elastic Analysis (Ref. Section B.2.5) ° Creep and Elastic Analysis ° Elastic Analysis Only	INDELA	0 1	(Default)
Number of Analysis Cases (Input in First Case Only)	NEWCAS	1	(Default)
Option for Creep Strain Accumulation Theory (Ref. Section B.2.4) ° Time Hardening ° Strain Hardening	HARDOP	1. 2.	(Default)
Maximum Time (Hours) This Input Required When HARDOP = 2. (Ref. Section B.2.4)	TMAX		
Option for Linear Creep Stress- Strain Below Stress = 1.	INDSTR	_	
° Creep Equation Used ° Linear Stress-Strain EQN Override		0 1	(Default)
Option for TPS Panel Cross Section Geometry (Ref. Section B.2.1) ° Rib. ° Corrugation ° Zee	INDGEO	1 2 3	·
Option for Incorporating Beaded Skin into Geometry (Ref. Section B.2.1) ° No Bead ° Bead Included	INDBD	0 1	(Default)
Number of Stations Along Panel Length Used In The Analysis (Ref. Section B.2.1)	NSTAT	6	(Default)
Number of Sections Through Panel Depth Used in The Analysis (Ref. Section B.2.1)	SEC NSECT	10. 10	(Default) (Default)



INPUT FOR ANALYSIS CONTROL (Continued)

DEFINITION	INPUT VARIABLE NAME	IN	PUT VALUE
Option for Units Of Time In Input Creep Equation	ITIME		
° Hours ° Minutes		0	(Default)
Option for Units of Temperature In Input Creep Equation	IEQNTP		
° °K/1000. ° °F/1000.		0	(Default)
Option for Units of Stress In Input Creep Equation	IEQNST		
° MPa ° KSI		0	(Default)
Option for Temperature Input Units	IINTP		
° °K ° °F		0	(Default)
Option for Pressure And Load Input Units	ILOAD		
° Pa, KILOS ° psi, Lbs.		0 1	(Default)
Option for Dimension Input Units	IDIMEN		
° cm. ° in.		0 1	(Default)
Option for Input of Initial Residual Stresses	IRESID		
° Initial Values = 0. ° Values Input		0 1	(Default)
Initial Residual Stress Values	RESSIN (I,J)		7.10



Table B-2 INPUT FOR OUTPUT CONTROL (Ref. Section B.1)

DEFINITION	INPUT VARIABLE NAME	INPUT VALUE
Option For Printing Creep Deflections at Each Trajectory Step In First Cycle	INCYC	
° Print Not Req'd. ° Print Req'd.		0 l (Default)
Total Number of Cycles at Which Creep Deflection, Creep Strain, and Residual Stress Output Are Desired	NUMCYC	
Cycle Numbers at Which Output Is To Be Printed.	KCYCLE (N)	



Table B-3 INPUT FOR PANEL GEOMETRY DEFINITION (REF. SECTION B.2.1)

DEFINITION	INPUT VARIABLE NAME	INPUT VALUE
Panel Unsupported Length	ХLGТН	
Panel Width	PANWID	
Panel Cross Section	DEPTH	
Stiffener Spacing	PITCH	
Panel Skin Thickness	TS	



INPUT FOR RIB-STIFFENED CROSS SECTION (REF. SECTION B.2.1) (INDGEO = 1)

DEFINITION	INPUT VARIABLE NAME	INPUT VALUE
Rib Thickness	TR	
Number of Ribs Across	NRIB	
Distance From Outer Panel Rib to Panel Edge	RIBFLG	

INPUT FOR CORRUGATION STIFFENED CROSS SECTION (REF. SECTION B.2.1) (INDGEO = 2)

DEFINTION	INPUT VARIABLE NAME	INPUT VALUE
Corrugation Thickness	тс	
Number of Corrugations Across Panel Width	NCOR	
Corrugation Angle	PHICOR	
Corrugation Length in Contact With Skin	FLAT	
Edge Distance in Excess of Normal Pitch Length	EDGE	

PHASE III

INPUT FOR ZEE STIFFENED CROSS SECTION (REF. SECTION B.2.1) (INDGEO = 3)

DEFINITION	INPUT VARIABLE NAME	INPUT VALUE
ZEE Thickness	TZEE	
Number of Zee Stiffeners Across Panel Width	NZEE	
ZEE Stiffener Flange Dimensions	ZEESF ZEESF1 ZEEFF ZEEFF1	
Panel Edge.Distance	ZPNED1 ZPNED2	



INPUT FOR SKIN BEAD GEOMETRY (REF. SECTION B.2.1) (INDBD = 1)

DEFINITION	INPUT VARIABLE NAME	INPUT VALUE
Bead Width	BWID	
Bead Depth	BDEP	
Bead Radius (Sign of BRAD Indicates Positive or Negative Bead Direction)	BRAD	



PHASE III

INPUT FOR TRAJECTORY AND LOAD DEFINITION Table B-4 (REF. SECTION B.2.2)

DEFINITION	INPUT VARIABLE NAME	INPUT VALUE
Option For Type of Applied Load ° Uniform pressure ° Point loads	INDLOD	O (Default) l
Number of Time Steps in Trajectory Idealization	NTIME	
Time at End of Each Trajectory Time Step	DXTIME (N)	
Pressure Load at Each Trajectory Time Step (INDLOD = 0)	PRESS (N)	
Point Load at Each Trajectory Time Step (INDLOD = 1)	PLOAD (N)	
Distance from Beam Support to Applied Load (Input for INDLOD = 1)	ALEN	
Number of cycles to Be Analyzed	NCYCLE	
Option for Plate Bending Moment Calculations ° Analysis based on beam loads ° Plate moments used in analysis	INDPLA	O (Default) l
Stiffness of Panel Edge Support. (Moment of inertia). Input for INDPLA = 1.	ESTIFF	

INPUT FOR TRAJECTORY AND LOAD DEFINITION (Continued)

DEFINITION	INPUT VARIABLE NAME	INPUT VALUE
Option for Inputing Panel Stiffness in Transverse Panel Direction (Moment of Inertia Per Inch Of Panel Length) I = TS ³ /12 (1-v) ² ° I is input	INDD2	0 (Default) 1
Value of Input Transverse Panel Stiffness	DETWO	



TABLE B-5 INPUT FOR PANEL TEMPERATURE DISTIRBUTION (REF. SECTION B.2.3)

(REF. SECTION D.2.3)			
DEFINITION	INPUT VARIABLE NAME	INPUT VALUE	
Midspan Panel Skin Temperature At Each Trajectory Time Step	TEMP (N)		
Option for Temperature As A Function of Panel Length ° Temperature constant along the panel length ° Temperature variation along the panel length defined by equation coefficients ° Temperature variation along the panel length defined by Table lookup	INDTFL	O (Default) O	
Equation Coefficients for Temperature Distribution along Length	C(1)		
Temperature Distribution along Length Defined by Table Lookup k = number of points in Table	XTEMP(1) = 0.,1.,k,0., X1,k, Tx1,k		
Option for Temperature As A Function of Panel Depth Temperature constant through the panel depth Temperature variation through the panel depth defined by equation coefficients Temperature variation through the panel depth defined by Table lookup	INDTFD	O (Default) O	
Equation Coefficients for Temperature Distribution Through the Panel Depth	D(1)		



INPUT FOR PANEL TEMPERATURE DISTRIBUTION (Continued)

DEFINITION	INPUT VARIABLE NAME	INPUT VALUE
Temperature Distribution Through Depth Defined By Table Lookup k = Number of points in Table	YTEMP (1) = 0.,1.,k,0., Y1,k, Ty1,k	
Temperature Variation in Panel ° Constant over Panel ° Variation defined by equation or Table	ITCON	l (Default) O
Temperature Variation in Trajectory ° Constant ° Variable	NTCON	l (Default) O



PHASE III

TABLE B-6 INPUT FOR MATERIAL PROPERTY DEFINITION (REF. SECTION B.2.3)

DEFINITION	INPUT VARIABLE NAME	INPUT VALUE
Poisson's Ratio (Req'd. if INDPLA = 1)	XNU	
Option for Definition of Elastic Modulus Data ° Constant modulus ° Modulus defined by equation ° Modulus defined by table lookup	INDMOD	O (Default) O
Equation Coefficients for Elastic Modulus as Function of Temperature	ECOEFF (1)	
Tabular Data for Elastic Modulus as A Function of Temperature	ETEMP (1) = 0., l., k, 0., Tl,k, El,k	



TABLE B-7 INPUT FOR CREEP PROPERTY DEFINITION

Material creep properties are defined through the input of coefficients (Z) to the linear equation

In
$$\varepsilon = Z_1 X_1 + Z_2 X_2 + Z_3 X_3 + \dots + Z_N X_N$$

or

$$\varepsilon = \exp (Z_1 X_1 + Z_2 X_2 + Z_3 X_3 + \dots + Z_N X_N)$$
(B-25)

In this equation, the value of X_1 is defined as 1 and X_2 through X_N are terms in time (t), stress (σ), and temperature (T) listed in table B-7 section. Only the terms required need to be input.



TABLE B-7 INPUT FOR CREEP PROPERTY DEFINITION (CONTINUED)

	CREEP EQUATION TERM	
COEFFICIENT NAME	LOGARITHMIC FORM	EXPONENTIAL FORM
Z(1)	z ₁	e ^Z 1
Z(2)	Ζ ₂ σ	e ^Z 2 ^σ
Z(3)	z ₃ T	e ^{Z3T}
Z(4)	Z ₄ t	e ^{Z4t}
Z(5)	Z ₅ (¹ / _T)	e ^Z 5/ ^T
Z(6)	Z ₆ Int	t ^Z 6
Z(7)	Z ₇ lnσ	σ ^Z 7
Z(8)	Z ₈ lnT	T ^Z 8
Z(9)	Z9σ ²	e ^{Zg_o2}
Z(10)	Z ₁₀ σ ³	е ^Z 10 ^{σ3}

INPUT FOR CREEP PROPERTY DEFINITION (Continued)

	CREEP EQUATION TERM	
COEFFICIENT NAME	LOGARITHMIC FORM	EXPONENTIAL FORM
Z(11)	$Z_{11}\left(\frac{1}{T}\right)^2$	e ^Z 11/ ^{T2}
Z(12)	$z_{12}(\frac{1}{T})^3$	e ^{Z12} / ^{T3}
Z(13)	Z ₁₃ σT	e Z13ªT
Z(14)	Z ₁₄ ([⊙] †)	e ^Z]4 ^(σ/Т)
Z(15)	Ζ ₁₅ (σΤ) ²	e ^Z 15(σT) ²
Z(16)	Z ₁₆ (σΤ) ³	e ^Z 16(σT) ³
Z(17)	Z ₁₇ (^σ / _T) ²	e ^Ζ 17 ^{(σ/Τ)²}
Z(18)	$z_{18}(\frac{\sigma}{\Gamma})^3$	e ^Ζ 18 ^{(σ/Τ)³}
Z(19)	Z ₁ g (lnσ) ²	σ ^Z 19 ^{lnσ}
Z(20)	Z ₂₀ (1nσ) ³	_σ Z ₂₀ (1n _σ) ²

PHASE III

INPUT FOR CREEP PROPERTY DEFINITION (Continuad)

	CREEP EQUATION TERM	
COEFFICIENT NAME	LOGARITHMIC FORM	EXPONENTIAL FORM
Z(21)	Z ₂₁ σ1nT	T ^Z 21σ
Z(23)	Z ₂₃ lnσlnT	_σ Z ₂₃ lnT
Z(22)	Z ₂₂ Tlnσ	_σ Z ₂₂ T
Z(24)	Z ₂₄ toT	e ^Z 24toT
Z(25)	Ζ ₂₅ (tσT) ²	e ^Z 25(tσT) ²
Z(26)	Z ₂₆ (tgT) ³	e ^Z 26(toT) ³
Z(27)	Z ₂₇ t ²	e ^Z 27t ²
Z(28)	z ₂₈ t ³	e ^Z 28 ^{t³}
Z(29)	Z ₂₉ (lnt) ²	t ^Z 29 ^{1nt}
Z(30)	Z ₃₀ (lnt) ³	t ^{Z₃₀(lnt)²}



INPUT FOR CREEP PROPERTY DEFINITION (Continued)

	CREEP EQUATION TERM	
COEFFICIENT NAME	LOGARITHMIC FORM	EXPONENTIAL FORM
Z(31)	z ₃₁ τ²	_е ^Z 31 ^{T²}
Z(32)	Z ₃₂ T ³	_е ^Z 32 ^{T3}
Z(33)	Z ₃₃ (1nt) ²	T ^{Z33} lnT
Z(34)	Z ₃₄ (1nT) ³	T ^{Z34(lnT)²}
Z(35)	Z3501nt	t ^Z 35σ
Z(36)	Z ₃₆ Tlnt	t ^{Z36^T}
Z(37)	Z ₃₇ tln _σ	₀ Z ₃₇ t
Z(38)	_ Z38tlnT	T ^Z 38t
Z(39)	Z ₃ 9lnolnt	_σ Z ₃₉ lnt
Z(40)	Z _{4O} lnt lnT	t ^Z 40lnT



INPUT FOR CREEP PROPERTY DEFINITION (Continued)

	CREEP EQUATION TERM	
COEFFICIENT NAME	LOGARITHMIC FORM	EXPONENTIAL FORM
Z(41)	Ζ ₄₁	z ₄₁ /Τ
Z(42)	Z ₄₂ lnt	t ^Z 42 ^{/T}
Z(43)	Z ₄₃ T	σ ^Z 431nt/T
Z(44)	Z ₄₄ to	e ^Z 44 ^t σ
Z(45)	Z ₄₅ tT	e ^Z 45tT



B.4 PROGRAM OUTPUT

Program output includes a listing of input variables, calculated elastic stresses at each panel station and trajectory step, panel geometry definition, trajectory load and temperature definition, creep strain equation definition, elastic deflections, creep deflections, creep strain distributions, and residual stress distributions. Creep deflections are printed at times within the first cycle and at the end of each requested cycle (KCYCLE). The example problems in Section 8 show typical program output.

Generally the output is automatic and not controlled by the user. The following items are, however, at the option of the program user.

- (a) Printout of calculated creep deflections at the end of each trajectory time step in the first cycle are controlled by the variable INCYC. These deflections are printed as a default unless INCYC = 0 is input.
- (b) The cycles at which calculated creep deflections, creep strain distributions, and residual stress distributions are printed, are controlled by the input variables NUMCYC and KCYCLE(N). The variable NUMCYC is the total number of cycles at which printout is required (maximum = 10) and KCYCLE(N) is the designated cycle number for printout.
- (c) Both analysis and output are controlled by the number of panel length increments and depth increments defined by the input variables NSECT, SEC, NSTAT, and NBSECT (ref. Section B.3). Output of stresses, deflections, and strains are calculated and printed at locations along the panel length and through the panel depth as defined by these input variables in conjunction with the panel geometry (Section B.2.1).



B.5 PROGRAM DIAGNOSTICS

Three types of diagnostic statements are included in the TPSC program to provide user information where problems may be occurring in the analysis.

(1) "CORRUGATION INPUT DATA YIELDS A NEGATIVE S LENGTH"

This information is printed out and the analysis terminated when the calculated corrugation flat length dimension S (Ref. Section B.2.1) is negative

The geometry definition (PHICOR, DEPTH, FLAT, PITCH) should be checked for input error.

(2) "ERROR IN TABLE-LOOKUP ROUTINE AT
$$\left\{\begin{array}{c} XIN \\ YIN \\ TIN \end{array}\right\} = \underline{A}$$
."

A is the panel station X(XIN), the panel depth increment (YIN), or the temperature (TIN) which exceeds the bounds of the appropriate input table for temperature as a function of length, temperature as a function of depth, and elastic modulus as a function of temperature, respectively. The table lookup input data should be checked to insure that the range of data in the table extends over the range needed for analysis.

(3) "WARNING - TWENTY ITTERATIONS ON STRESS IN THE HARDENING ROUTINE

BEAM STATION = _____, SECTION (J) = _____, CYCLE = _____, STEP = _____

ANALYSIS PROCEEDING WITH STRESS UNCHANGED."

This diagnostic message indicates that the iteration process for stress (Reference Section B.2.6) did not converge. The stress is defined as that at the enc of the previous time step and analysis continues. When this occurs, the form of the input empirical equation should be checked.

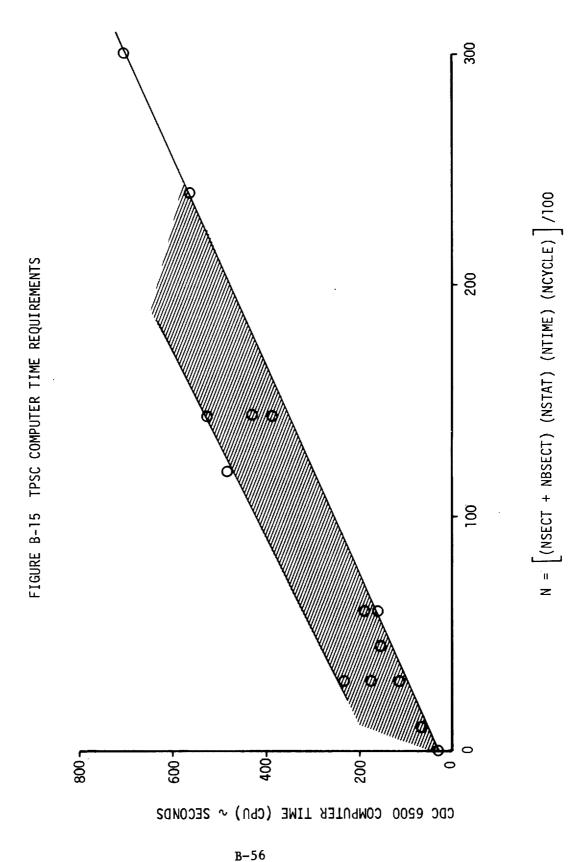


B.6 COMPUTER TIME REQUIREMENTS

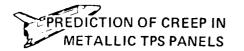
Computer (CPU) time data compiled for analysis cases using the TPSC program are shown in Figure B-15. These data points are plotted against a value N which is the product of the number of increments through the panel depth (NSECT + NBSECT), the number of segments along the panel length (NSTAT), the number of time steps in the load-temperature trajectory (NTIME), and the number of cycles being analyzed. Data, shown in the figure are for analysis conducted using the time hardening theory of creep accumulation program option.

Because additional iterations are required in analysis using the strain hardening theory of creep accumulation, a factor of 1.8 (factors for specific cases typically range from 1.3 to 2.4) should be applied to the range shown in Figure B-15 for this option. In addition, the data plotted are for separate runs. Running of multiple cases results in a somewhat lower per case computer time.

Variations in required computer time are expected from run to run depending on times required to converge on stresses, load balances, and moment balances in the program. The data, obtained in analysis for prediction of creep deflections in subsize and full size panels, are presented to provide computer time guidelines for the TPSC program user.



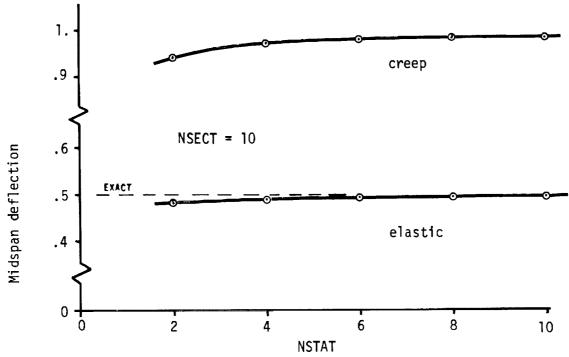
MCDONNELL DOUGLAS ASTRONAUTICS COMPANY . EAST

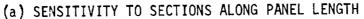


B.7 ANALYSIS SENSITIVITY TO PANEL ELEMENT SIZE

Limited studies have been conducted to investigate the sensitivity of the TPSC program prediction capability to the number of sections along the panel length (NSTAT) and increments through the panel depth (NSECT). Shown in Figure B-16 are typical midspan elastic and creep deflection predictions as a function of these variables. This example is based on an 11-inch titanium panel subjected to a uniform pressure load. These studies have demonstrated that a minimum of these sections are needed to maintain prediction precision and, based on study results, the values NSTAT = 6 and NSECT = 10 are default values in the program. Because more sections are required to define horizontal sections and flange sections for the Z stiffened TPS and corrugation stiffened TPS than for the rib stiffened concept, a minimum value for NSECT is recommended as 8 for the rib, 10 for the corrugation, and 12 for the Z stiffened concepts. Also the effects of NSECT on creep deflection prediction capability will be somewhat dependent on the degree of nonlinearity of the input creep strain equation with respect to stress. Therefore, more sections should be included for equations which are very nonlinear in stress.







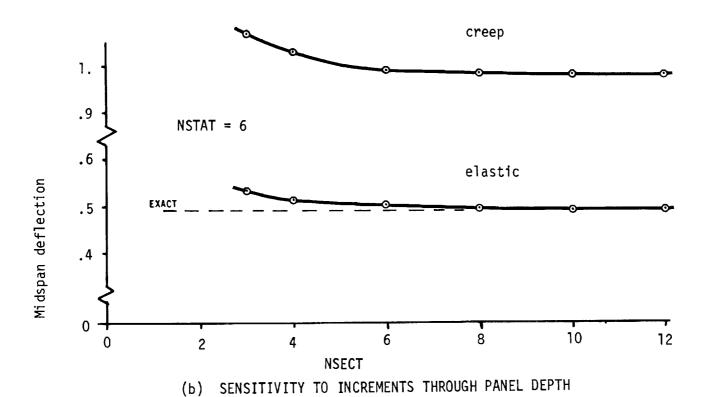


FIGURE B-16 TYPICAL SENSITIVITY OF PREDICTION TO ELEMENT SIZE



B.8 EXAMPLE PROBLEMS

The following two example problems are provided to demonstrate the input for the major programs options. Section B.3 should be consulted for default values for variable means not included in the input. These default values apply when the variable is not input.

EXAMPLE PROBLEM 1

Example problem 1 demonstrates analysis capability for the rib stiffened panel shown in Figure B-17(a). This simply supported panel is loaded with two point loads located 3.62 inches from the panel supports as shown in Figure B-17(b). In the example, the panel is subjected to ten constant load and temperature cycles of 20 minute duration each (Figure B-17(c)) and the time hardening theory of creep accumulation is used. The panel temperature is a function of panel length as shown in Figure B-17(d). Elastic modulus is defined as a function of temperature as 12.3×10^6 psi at 725° F and 11.8×10^6 psi at 825° F (note this covers panel temperature range of 769° F (.932 x 825, Figure B-17(d)) to 825° F). U.S. Customary units are used in the input data. The following creep equation for Titanium (Reference 2) is used:

 $ln\epsilon = -26.22982 + 26.2485T + .000126\sigma^2 + 1.40406 ln\sigma + .46894 lnt$

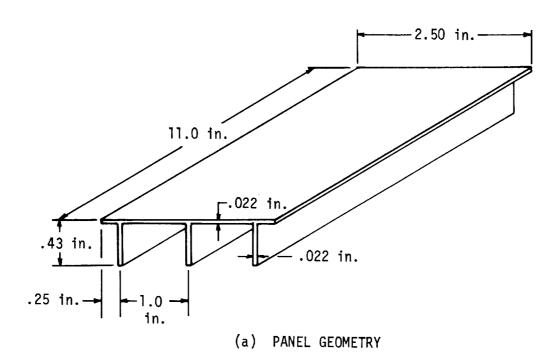
where t = time, hours

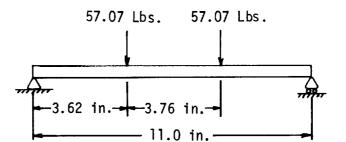
T = temperature, °F/1000

 σ = stress, ksi

Deflection, strain, and stress outputs are requested after 1, 3, and 10 cycles are data given through the panel depth and along its length are output according to the default values of NSECT (10) and NSTAT (6), respectively.

Input and output for example problem 1 follows.







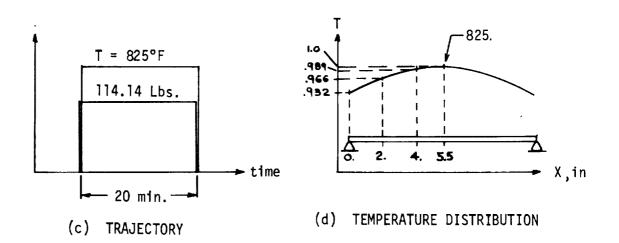
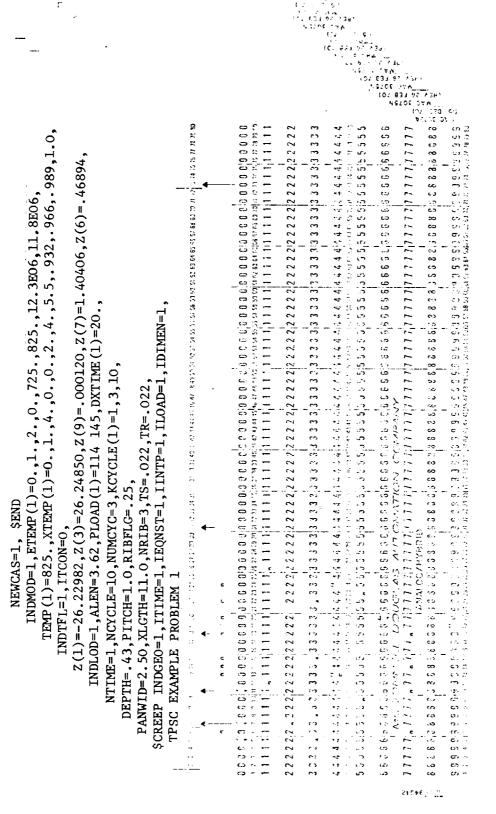


FIGURE B-17 EXAMPLE PROBLEM 1 B-60



EXAMPLE PROBLEM 1 OUTPUT

```
SCREEP
DEPTH
   = 0.43E+00.
PHICOR
PITCH
FIAT
     0.0.
EDGE
NCOR
TC
     0.0.
XLGTH
     0.11E+02,
     0.226-01.
TR
NRI9
RIBFLG =
     0.25E+80,
ZPNED1 = 0.0.
ZPNEO2 =
NZEE
TZEE
ZEESF =
ZEESF1 =
ZEEFF
ZEEFF1 =
BHID
BRAD
     PRESS
   TEHP
ALEN
    = 0.362E+01,
XNU
    = 0.G,
PANHID = 0.25E+01.
    = 0.1E+01, 0.0, 0.0, 0.0,
     0.1E+31, 0.0, 0.0, 0.0,
```



EXAMPLE PROBLEM 1 OUTPUT

```
NTIME
NEWCAS
YTEMP
EHOD
ETEMP
             0.118E+38, 3.0, 0.0, 0.0, 0.0,
INDGEO
INDBO
INDLOD
INDSUP
INDPLA
INDTFL
INDTFD
KOYOLE
INCHOC
NCYCLE =
NUMCYC
ITCON
NTCON
HARDOP
THAX
      = 0.0.
INCYC
ITIME
IEONTP
IDIMEN
TLOAD
IEONST
NSTAT
        0.1E+02.
NSECT
NBSECT =
IRESID
RESSIN
```



EXAMPLE PROBLEM 1 OUTPUT (Continued)

ESTIFF = 0.0.
INDO2 = G,
INDSTR = G,
DETMO = 0.0.

END

EXAMPLE PROBLEM 1 OUTPUT (Continued)

CASE 1 ANALYSIS ELASTIC STRESSES AT X= .917

	TRAJECTORY T	INE STEP 1	
J	AREA (SQ. IN)	Y(IN)	STRESS (PSI)
123456 789 0	2. 9920000000000000000000000000000000000	2.86607EE-021 6.8134617EE-011 1.5846133EE-011 2.9466133EE-011 2.9466133EE-011 3.865033E-011 4.190003E-011	7.087373333776.087374460.44003373333333333333333333333333333333

CASE 1 ANALYSIS ELASTIC STRESSES AT X= 1.333

	TRAJECTORY TIME	E STEP 1	
J	AREA (SO. IN)	Y(IN)	STRESS (PSI)
1234567890	2. 999222333 2. 9992223333 2. 9992223333 2. 9992223333 2. 9992223333 2. 999223333 2. 999223333 2. 999223333	2.02 6.03 6.03	21.626666 18.536599 18.536599 18.536599 18.536599 19.444969 44.636 19.444969 19.444969 19.444969 19.444969 19.444969 19.4465

CASE 1 ANALYSIS ELASTIC STRESSES AT X= 2.750

	TRAJECTORY TE	ME STEP 1	
J	AREA (SQ.IN)	Y(IN)	STRESS (PSI)
12345678990	99920000000000000000000000000000000000	2.26603 6.86707 1.586708 1.586708 2.04003 2.0403578 2.0403578 2.040358 3.493578 3.85338 4.1900	444443233 674166443233 18741792164 5157677921792 5157677921792 515767474792 5157674792 5157674777777777777777777777777777777777



EXAMPLE PROBLEM 1 OUTPUT (Continued)

CASE 1 ANALYSIS ELASTIC STRESSES AT X= 3.667

	TRAJECTORY TIME	E STEP 1	
J	AREA (SQ.IN)	Y(IN)	STRESS(PSI)
1234567 67 10	2006 100	2.020 6.01337E-01 11.504003E-01 2.0493600E-01 2.0493600E-01 2.0493600E-01 3.85900	5.044 5.044 5.044 5.044 5.047 5.

CASE 1 ANALYSIS ELASTIC STRESSES AT X= 4.583

	TRAJECTORY TIME	STEP 1	
J	APEA(SQ.IN)	Y(IN)	STPESS(PSI)
1274567898	2.992000E-033 22.992000E-033 22.992000E-033 22.992000E-033 22.992000E-033 22.992000E-033	2.667EE-022 6.63237EE-021 1.56337EE-011 2.049337EE-011 2.049337EE-011 2.946003EE-013 3.485033EE-01	5.4.0444 5.8.0315684 6.03575681 6.03575681 6.03575681 6.03575681 6.03575681 6.03575681 6.03575681 6.03575681 6.03576881 6.03575881 6.03575881 6.03576

CASE 1 ANALYSIS ELASTIC STRESSES AT X= 5.500

	TRAJECTORY TI	HE STEP 1	
J	AREA (SQ.IN)	Y(IN)	STRESS(PSI)
1234567 89G	2.9992000 2.99920000 2.99920000 2.99920000 2.99920000 2.99920000 2.99920000 2.99920000 2.99920000 2.99920000	2.26667E-02 6.80000E-02 1.13367E-01 1.594667E-01 2.4937E-01 2.94667E-01 2.946633E-01 3.8503E-01	54.04444 54.044444 57.21.26.26.21.26.26.21.26.21.26.21.26.21.26.21.26.21.26.21.26.21.26.21.26.21.26.26.21.26.26.21.26.21.26.21.26.21.26.21.26.21.26.21.26.21.26.21.26.21.26.26.21.26.26.21.26.20.20.20.20.20.20.20.20.20.20.20.20.20.

EXAMPLE PROBLEM 1 OUTPUT (Continued)

CREEP PREDICTION COMPUTER PROGRAM
TPSC EXAMPLE PROBLEM 1

RIS STIFFENED TPS FANEL

SKIN GAGE = .022 INCHES
PIR GAGE = .022 INCHES
NUMBER OF RIBS = 3
PITCH LENGTH = 1.000 INCHES
PANEL EDGE LENGTH = .250 INCHES
PANEL DEPTH = .430 INCHES
PANEL DEPTH = .430 INCHES
CALCULATED MCMENT OF INERIA = .0012046 IN**4
ELASTIC NEUTRAL AXIS = .346 INCHES

PANEL LENGTH = 11.00 INCHES PANEL WIOTH = 2.50 INCHES

APPLIED LOADS THO POINT LOADS , DISTANCE FROM SUPPORT TO LOAD = 3.62 INCHES

TRAJECTORY DATA

TIME (SECONDS) LOAD (LBS) TEMPERATURE (DEG F)

START END TOTAL LOAD MICSPAN SKIN TEMPERATURE

0.00 20.00 114.145 825.0

CREEP PREDICTION COMPUTER PROGRAM

CYCLIC CREEP EQUATION DEFINITION

LN(STRAIN)= -2.62298E+01 2.62485E+01 *(TEMP) 4.68940E-01 *LN(TIME) 1.40466E+03 *LN(STRESS) 1.20000E-04 *(STRESS)**2

> WHERE TIME = PINUTES TEMPERATURE = DEG K/1000. STRESS = KS1

> > CREEP PREDICTION COMPUTER PROGRAM ELASTIC DEFLECTION SUMMARY

CREEP PREDICTION COMPUTER PROGRAM
FIRST CYCLE CREEP DEFLECTION SUMMARY

TIME .92 1.83 2.75 3.67 4.58 5.50 20.00 .00874 .01718 .02468 .03020 .03249 .03373

EXAMPLE PROBLEM 1 OUTPUT (Continued)

CHEEP PREDICTION COMPUTER PROGRAM CREEP DEFLECTION SUMMARY

CYCLE 1 10	BEAM STAT	TION (INCHES) 1.83 374 01718 660 02869 542 04995	2.75 .G2468 .G3C2 .G4121 .G5G4 .G7174 .G877	4.58 5.50 0 .03249 .03373 2 .05425 .05631 6 .09443 .09801
				DICTION COMPUTER PROGRAM EEP STRAINS (PERCENT) CYCLE 1
HE 12377330	358 055 055 055 055 055 055 055 055 055 0	BEAM STATION (1.07 27	2.75 .0266634 .0622175 .0259521 .0634040	5.58 .0699768 .0757375 .0757375 .0757375 .0757375 .0757375 .0757375 .0757375 .0757375 .0757375 .0757375 .0757375 .0757375 .0757476
				OICTION COMPUTER PROGRAM SIDUAL STRESSES (PSI) CYCLE 1
T7037037030 170370370370 1703170494059 10011222334	4.30E+01 1.88E+01 -1.51E+01 -1.76E+01 -2.97E+01 -3.31E+01 -3.54E+01 -3.54E+01	8EAM STATICN 1 783 - CC	7.0375+02 7.0375+02 7.0375+02 7.0375+02 7.0375+02 7.0375+02 7.0375+033	5.50 + 0.3 2.50 +
				DICTION COMPUTER PROGRAM EEP STRAINS (PERCENT) CYCLE 3
T703377330 C265349497330 G265349497330 HE C31422734	856732153310 85992275524 4047349524 22074750348 22074110000 000000000000000000000000000000	BEAM . 88 ± 157	2.75 .0446756 .1050202	4.58 .11f8295 .11274215 .1160093 .1258215 .127425 .107287 .07299223 .04527946 .04527946 .0452744 .045274 .045274 .045274 .045274 .045274 .045274 .0452744 .045274 .045274 .045274 .045274 .045274 .045274 .045274 .045274 .045274 .045274 .045274 .045274 .045274 .0452744 .045274 .045274 .045274 .045274 .045274 .045274 .0452744 .045274 .045274 .045274 .045274 .045274 .045274 .0452744 .045274 .045274 .045274 .045274 .045274 .045274 .0452744 .045274 .045274 .045274 .045274 .045274 .045274 .0452744 .045274 .045274 .045274 .045274 .045274 .045274 .0452744 .045274 .045274 .045274 .045274 .045274 .045274 .0452744 .045274 .045274 .045274 .045274 .045274 .045274 .0452744 .045274 .045274 .045274 .045274 .045274 .045274 .0452744 .045274 .045274 .045274 .045274 .045274 .045274 .0452744 .045274 .045274 .045274 .045274 .045274 .045274 .0452744 .045274 .045274 .045274 .045274 .045274 .045274 .0452744 .045274 .045274 .045274 .045274 .045274 .045274 .0452744 .045274 .045274 .045274 .045274 .045274 .045274 .0452744 .045274 .045274 .045274 .045274 .045274 .045274 .04527

EXAMPLE PROBLEM 1 OUTPUT (Continued)

CPEEP PREDICTION COMPUTED PROGRAM
RESIDUAL STRESSES (PSI)
CYCLE 3

T70337337030 H2037337337030 G2041504949481 H6031112223334	6.72FE+011 -1.83FE-011 -1.83FE-011 -5.87FE-011 -5.44FE-011 -7.34FE-011	BEAM STATIC 1.875-122 1.875-1122 -2.775-1222 -2.777-1222 -3.777-1222 -3.777-1222 -3.777-1222	N (12.75E-0.75E	3.5241EEEEEEEEEEEEEEEEEEEEEEEEEEEEEEEEEEEE	3.4.4.5.5.6.6.00 	3323333322 666633333333322 6766444400000 5766444440000 576447866126644 57647866126644 57647866126644 57647866126644 57647866126644 57647866126644 57647866126644 57647866126644 5764786612664 576478661 57647861 5764
					EDICTION COR	MPUTER PROGRA
					CYCLE	10

CPEEP PREDICTION COMPUTER PROGRAM
RESIDUAL STRESSES (PSI)
CYCLE 10

HEIGHT	.92	BEAM STATIC	N (INCHES)	3.67	4.58	E
.0227 .0680	1.18E+02 6.60E+01	7.02E+02 3.15E+02	1.83E+03 7.09E+02	5.25E+03 2.05E+03	5.518+03	5.50 5.73E+03
1133	-1.44E+01 -5.48E+01	-3.478+01	-1.60E+72	-4.90E+C2	2.20E+03 -4.72E+02	2.31E+03 -4.57E+02
2345	-8.62E+31	-2.95E+02 -4.75E+02	-8.33E+02 -1.27E+03	-2.332+03 -3.46E+03	-2.43E+33 -3.66E+03	-2.52E+03 -3.82E+03
2943 2493 2947	-1.02E+02 -9.42E+01	-5.61E+02	-1.46E+03 -1.37E+03	-3.86E+03 -3.61E+33	-4.10E+03	-4.31E+03
.3403 .3853	-6.04E+01 -2.61E+00	-3.44E+C2 -7.8CE+00	-8.88E+02	-2.37E+03	-2.57E+03	-2.74E+63 -2.49E+02
.4190	1.26E+01	7.13E+01	1.87E+02	4.94E+02	5.26E+02	5.54E+02



EXAMPLE PROBLEM 2

Example problem 2 demonstrates analysis for the 45.7 cm. long and 51.6 cm. wide beaded single skin corrugation stiffened panel shown in figure B-18(a). This panel is loaded with a uniform pressure and temperature where the pressure and temperature vary with time in each cycle as shown in figure B-18(c). The plate option is used in this problem and therefore the panel edge stiffness and Poisson's ratio are required input. The strain hardening theory of creep accumulation is applied in this example. SI units are used and the empirical creep equation is that for L605 (obtained in Phase I) as follows.

 $ln\epsilon = -2.89413 - .01743t + .54892 lnt +1.31015 ln\sigma -6.66548 (1/T) + .19131 lnT + .00021(Tot)$

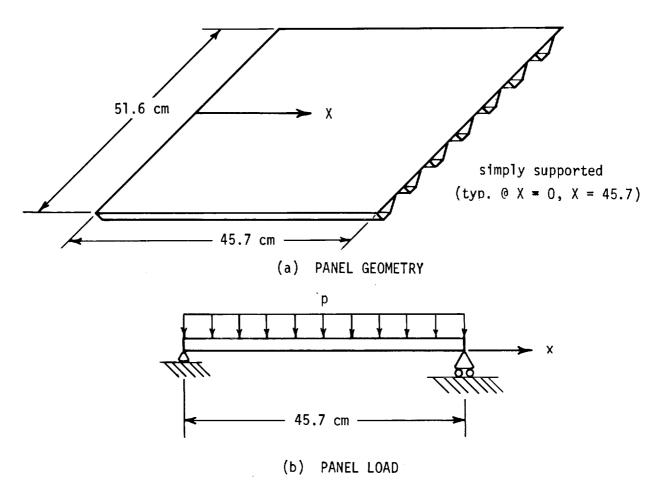
where t = time, hours

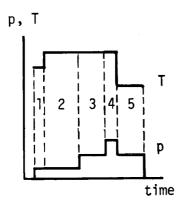
T = temperature, °K/1000

 $\sigma = stress, MPa$

Deflection, strain, and stress output are requested after 1, 2, 3, 4 cycles and output are provided at 23 locations through the panel depth (NSECT + NBSECT) and 8 locations along the length (NSTAT).

Input and output for example problem 2 follows.





TRAJECTORY STEP	TIME (Min.)	TEMP (°K)	PRESSURE (Pa)
. 1	0-1.33	1122	758
2	1.33-4.67	1231	758
3	4.67-7.50	1231	1655
4	7.50-8.50	1225	2482
5	8.50-11.33	1014	1655

(c) TRAJECTORY

figure B-18 EXAMPLE PROBLEM 2

```
5,55555
```

EXAMPLE PROBLEM 2 INPUT

TPSC EXAMPLE PROBLEM 2 TIME HARD

\$CREEP INDGEO=2,

HARDOP=1., TMAX=20., NSTAT=8, SEC=15., NSECT=15

INDPLA=1, ESTIFF=.5078, XNU=.3, ECOEFF(1)=13.79E10, NTCON=0,

NTIME=5, NCYCLE=4, NUMCYC=4, KCYCLE(1)=1, 2, 3, 4,

DEPTH=1.852, PITCH=3.63, EDGE=.36, FLAT=.711, PHICOR=12.63,

PANWID=51.6,XLGTH=45.7,NCOR=14,TS=.0216,TC=.0140,

INDBD=1, BRAD=-3.18, BDEP=.279, BWID=2.62, NBSECT=8

Z(1) = -2.89414, Z(4) = -.01743, Z(6) = .54892, Z(7) = 1.31015,

TEMP (1)=1122.,1231.,1231.,1225.,1014.

DXTIME(1)=1.33,4.67,7.50,8.50,11.33, PRESS(1)= 758.,758.,1655.,2482.,1655.,

Z(5) = -6.66546, Z(8) = .19131, Z(24) = .00021,

NEWCAS=1.

PHASE III SUMMARY REPORT EXAMPLE PROBLEM 2 OUTPUT

```
SCREEP
          0.18528+01,
DEPTH
PHICOR
          0.1263F+02
PITCH
          0.363E+01,
FLAT
          0.711F+0D-
EDGE
          0.36E+00.
NCOR
TS
          0.216E-01.
TC
          0.14E-01.
XL GTH
          0.457E+02.
TR
NRIB
RIBFLG
ZPNED1
ZPNE02
NZEE
TZEE
ZEESF
ZEESF 1
ZEEFF
          0.0
ZEEFF1
          0.0.
RHID
          0.262F+01.
          0.279E+00.
BDEP
       = -0.318E+01.
RPAD
                     0.758E+03, 0.1655E+04, 0.2482E+04, 0.1655E+04, 0.0,
PRESS
          0.758E+03.
                                  0.1231E+04, 0.1225E+04, 0.1014E+04, 0.0, 0.0, 0.0,
TEMP
                    0.467E+01, 0.75E+01, 0.85E+01, 0.1133E+02,
                                                                0.0,
                                                                      0.0, 0.0, 4.0,
DXTIME
                     0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0,
ALEN
          0.0.
XNU
          0.3E+00,
PANHID =
          0.516E+JZ.
          0.1E+01, 0.0, 0.0, 0.6.
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                                0.0.
                                      0.0.
XTEMP
                     0.0.
                           0.0.
NEWCAS
                                                                                              0.0.
                                                                             0.0.
                                                                                  0.0.
                                                                                        0.0.
                                            0.0,
YTEMP
          0.0,
                0.0, 0.0,
                                                 B - 73
EM00
          0.0.
                    MCDONNELL DOUGLAS ASTRONAUTICS COMPANY . EAST
```



EXAMPLE PROBLEM 2 OUTPUT

```
INDGEO
INDLOD
INDSUP
INDPLA
INDTFL
INDTFO
KCYCLE
INDELA
NCYCLE
NUHCYC
ITCON
NTCON
ECOEFF ≠
HARDOP
       0.2E+02.
THAX
INCYC
ITIME
IFONTP
IDIMEN
ILOAD
IEQNST
NSTAT
SEC
       0.15E+02,
NSECT
NRSECT =
IRESID =
                                                   RESSIN
                               000000
                                                   8:8:
                       B:8:
                                                8:8:
                   B:3:
                           8:8:
                   0.0
                                   8:8:
                               0.0;
                                                                    8:8;
           0.0.
                                                            0.5078E+00.
ESTIFF
INDOS
INDSTR
DETWO
SEND
```

EXAMPLE PROBLEM 2 OUTPUT

ELGASTE STRESSESSAT x= 2.856

	• · · · · · · · · · · · · · · · · · · ·		
j .	TRAJECTORY AREA (SQ.CM)	V/C41	STRESS (MPA)
	4.1033334649472222222222222222222222222222222222	6.99994E900000000000000000000000000000000	7.1662761 - 011 6.7662761 - 011 5.76264 - 011 5.7626 - 01
123456789011234567890	6.03385E-05	2.39300E-01 3.89499E-01 5.39699E-01	5.75206E-01 4.84141E-01 3.93077E-01
7 8	6.03182E-02 6.03182E-02 6.03182E-02	6.89899E-01 8.40099E-01 9.90298E-01	3.02012E-01 2.10948E-01 1.19883E-01
10 11	6.03382E-02 6.03382E-02 6.03382E-02	1.14050E+00 1.29070E+00 1.44090E+00	2.06184E-02 -6.22462E-02 -1.53311E-01
12 13 14	6.03382E-02 6.03382E-02 1.49435E-01	1.59110E+00 1.74130E+00 1.82340E+00	-2.44375E-01 -3.35440E-01
15 16 17	3.22271E-01 1.63320E-01 1.63320E-01	1.64120E+00 1.78820E+00 1.69826E+00	-3.96008E-01 -3.63879E-01
18 19 20	1.63320E-01 1.63320E-01 1.63320E-01	1.63023E+00 1.58460E+00 1.56170E+00	-2.68095E-01 -2.40435E-01
			- 2.209925-01
J	TRAJECTORY AREA (50.CH)	A (CH)	STRESS (HPA)
2	4-12574E-01 6-03382E-02	6.999995+03 8.90998E-02	7.16047E-01 6.65271E-01
3 5	6.03382E-02 6.03382E-02 6.03382E-02	2.39300E-01 3.89499E-01 5.39639E-01	5.75206E-01 4.84141E-01 3.93077E-01
7 .	6.03382E-02 6.03382E-02 6.03382E-02	6.89899E-C1 8.40098E-01 9.90298E+01	3.02012E-01 2.10948E-01 1.19883E-01
10 11	6.03382E-02 6.03382E-02 6.03382E-02	1.14050E+00 1.29070E+00 - 1.44093E+00	2.88184E-02 -6.22462E-02 -1.53311E-01
12 13 14	6.03382E-02 6.03382E-02 1.49435E-01	1.59110E+00 1.74130E+00 1.82340E+00	-2.44375E-01 -3.35440E-01
15 16 17	3.22271E-01 1.63327E-01 1.63327E-01	1.84120E+00 1.78820E+00 1.69826E+00	-3.96008E-01 -3.63879E-01
12345678901234567890	10000000000000011111111111111111111111	5.38996299799999999999999999999999999999999	7667477287421011 1674772874210011 1674772874210011 1674772874210011 1674772874210011 1674772874210011 16754772874210011 16754772874210011 16754772874210011 16754772874210011 16754772874210011 167547741001
	TRAJECTORY		
J	ÀREA (SO.CH)	(F3) Y	STRESS (HPA)
12345678901234567890	10000000000000000000000000000000000000	6.99999E-03 8.90998E-02 2.39300E-01	1.56340E+00 1.45472E+00 1.25589E+00
5	6.03382E-02 6.03382E-02 6.03382E-02	3.89499E-01 5.39699E-01 6.89899E-01	1.05706E+00 8.58235E-01 6.59406E-01
7 6 9	6.03382E-02 6.03382E-02 6.03382E-02	8.4009AF-01. 9.9029AE-01 1.1405CF+00	4.60578E-01 2.61750E-01 6.29214E-02
10 11 12	6.03382E-02 6.03382E-02 6.03382E-02	1.29070E+00 1.44090E+00 1.59113E+00	-1.35907E-01 -3.34735E-01
13 14 15	6.03382E-02 1.49435E-01	1.74133E+00 1.82340E+00	-7.32392E-01 -8.41073E-01
1 <u>6</u>	1.63320E-01 1.63323E-01	1.7820E+00 1.69826E+00	-7.94485E-01 -6.75419E-01
19 20	1.63320E-01 1.63320E-01	6.909998E - 001 6.90998E - 001 7.399499E - 001 7.3994998E - 001 7.3994998E - 001 7.3994998E - 000 7.3994998E - 000 7.399498 - 000 7.3994	11.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1
	TRAJECTORY		
J	ASSA ISO CHI	Y (CH)	STRESS (HPA)
į	4.12574E-01 6.03182E-02	6.99999E-03 8.90998E-02	2.34463E+00 2.18164E+00
5	6.03182E-02 6.03182E-02	3. 69494E-01 5. 39699E-01	1.58528E+00 1.58528E+00 1.28709E+00
9 8	6.03382E-02 6.03382E-02	6.89899E-01 8.40098E-01 9.90298E-01	9.88911E+D1 6.90728E-01 3.92546E-01
10 11	6.03382E-02 6.03382E-02	1.14050E+00 1.29070E+00 1.44090E+00	9.43631E-02 -2.03819E-01 -5.02002E-01
12 13 14	6.03382Ē-02 6.03382Ē-02 1.49435Ē-01	1.59110E+00 1.74130E+00 1.7436E+00	-0.00184E-01 -1.09837E+00
15 16 17	3.2271E-01 1.63320E-01	1.84125E+09 1.78825E+00	-1.29669E+00 -1.19149E+00
12345678901234567890	4.0 0 0 0 0 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1	5.9099999999999999999999999999999999999	346884-000 34688-000 481342091111 4813420911111 4813420911111 4813420911111 4813420911111 4813420911111 48134209111111111111111111111111111111111111
٠.	1.63320E-01	B -75 1.56170E+00	-7.41824E-01

EXAMPLE PROBLEM 2 OUTPUT TRAJECTORY TIME STEP 5

J	AREA (SO.CH)	Y (CM)	STRESS (HPA)
125.45.67.89.01177111118	12222222 12222222 12222222 1222222 122222	998566698666666666666666666666666666666	1

ELASTIC STRESSES AT X= 5.712

			•
	TRAJECTORY TI	ME STEP 1	
J	AREA (SO.CH)	Y (CH)	STRESS (MPA)
123456759911234567899	12222222222222222222222222222222222222	6.99945 000 6.99945 000 6.99945 000 6.999945	2.000000000000000000000000000000000000
	TRAJECTORY TI	HE STEP 2	
J	AREA (SC.CM)	A (CH)	STRESS (HPA)
12345678961234567890	4.0022222222222222222222222222222222222	9 - 10 - 11 - 10 - 10 - 10 - 10 - 10 - 1	2.0099200000000000000000000000000000000
•	TRAJECTORY TI	HE STEP 3	
J	AREA (SO.CH)	Y (CH)	STRESS (HPA)
*2345678901234567890	10222222222222222222222222222222222222	6.9999EE-001 9999EE-001 5.39999EE-001 5.39999EE-001 5.39999EE-001 6.49099EE-000 1.49999EE-000 1.49999EE-000 1.49999EE-000 1.49999EE-000 1.49999EE-000 1.599199EE-000 1.599199EE-000 1.599199EE-000 1.599199EE-000	4.000 7.26.6000 7.26.6

EXAMPLE PROBLEM 2 OUTPUT

	TRAJECTORY TIME STE	EP 4	
J	AREA (SQ.CH)	A (CH)	STRESS (HPA)
1234567890	4.125748 - 01 6.03382 - 02 6.03382 - 02 6.03382 - 02 6.03382 - 02 6.03382 - 02 6.03382 - 02 6.03382 - 02	6.9998E-03 8.9998E-01 8.9998E-01 8.9998E-01 8.9998E-01 8.9998E-01 8.998998E-01 9.988998E-01	6.125000 5.125000 5.125000 5.125000 3.125000 3.125000 3.125000 3.125000 3.125000 3.125000 3.125000 3.125000 3.125000 3.125000
1234567890111111111111111111111111111111111111	4 • • • • • • • • • • • • • • • • • • •	032 	66.14679468888888888888888888888888888888888
	TRAJECTORY TIME STE		
J	40F4/50 CH1	Y (CH)	STRESS (MPA)
1234567890111111111111111111111111111111111111	1 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	9998EEE 001 9998EEE 001 9998EEE 001 9998EEE 001 9998EEE 000 9998EEE 000 9998EE	4.0500000000000000000000000000000000000
12 13 15 16 16 17 18	6.03382E-02 6.03382E-02 1.42271E-01 3.2220E-01 1.63320E-01 1.63320E-01 1.63320E-01	1.44690E+00 1.59110E+00 1.84130E+00 1.842340E+00 1.8426E+00 1.6430E+00 1.63026E+00 1.56460E+00	-9.394742E+000 -2.49548E+000 -2.4956E+000 -2.42956E+000 -1.47327E+000 -1.47327E+000
	ELASTIC STRESSES AT	X= 8.569	
	•		
	TRAJECTORY TIME STE	P 1	
J	AREA (SO.CH)	Y (CH)	STRESS (HPA)
127456769011274567690	4.103222222222222222222222222222222222222	6.99099001 6.99090001 6.990900001 6.9909000000000000000000000000000000000	10000001 10000001 100000001 100000001 100000000
	TRAJECTORY TIME STER	•	
j	AREA (SO.CH)	Y (CH)	STRESS (MPA)
•			
12745678901274567890	4.1257 REPORT OF THE PORT OF T	32 	3.9517119.6.0000001 3.9517119.6.0000001 3.9517119.6.00000001 3.9517119.6.0000000000000000000000000000000000

EXAMPLE PROBLEM 2 OUTPUT TRAJECTORY TIME STEP 3 AREA (SQ.CH) A (CH) STRESS (HPA) TRAJECTORY TIME STEP 4 AREA (SO.CM) YICHI STRESS (MPA) TRAJECTORY TIME STEP 5 AREA (SO.CH) Y (CH) STRESS (HPA) CASE 1 ANALYSIS ELASTIC STRESSES AT X= 11.425 TRAJECTORY TIME STEP 1 i) .

	AREA (SO.CM)	Y (CH)	STRESS (MPA)
12745678984234567898	4.123388822222 6.0333888222222 6.03338882222222 6.03338882222222 6.03338822222222 6.03338822222222 6.033388222222222 6.0333838882222222222 6.0333838882222222222 6.033383888822222222222222222222222222222	321111100000000000000000000000000000000	+ + + + + + + + + + + + + + + + + + +

EXAMPLE PROBLEM 2 OUTPUT

	TRAJECTORY TIME	STEP 2	
J	AREA (SO.CH)	Y(CH)	STRESS (HPA)
42745678904094567890	11222222222222222222222222222222222222	6.99998E-001 8.99998E-001 8.99998E-001 5.98999E-001 5.88999E-001 5.8899999999999999999999999999999999999	00000000111 +++++++++++++++++++++++++++
J	TRAJECTORY TIME	STEP J	
•	AREA (SQ.CM) 4.12574F-01	Y (CH) 6. 99999F-03	STRESS (MPA)
127456789011234567890	4.0 0 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	921111111111000000000000000000000000000	STREEDER HE
	TRAJECTORY TIME	STEP 4	
J	AREA (SO.CH)	, A (CH)	STRESS (HPA)
127456769012734567890	12222222222222222222222222222222222222	6.99966 000 999866 001 9999666 001 9999666 001 999966996 000 999969966 000 999969966 000 11.5966 -	11.00000000000000000000000000000000000
	TRAJECTORY TIME S	STEP 5	
J .	AREA (SO.CH)	Y(CH)	STRESS (HPA)
1234567 8901234567898	4.1037374 E-012 6.003738 822E-02 6.003738 822E-02 6.003738 822E-02 6.0037378 822E-02 6.0037378 822E-02 6.0037378 822E-02 6.0037378 822E-01 6.00374 825E-01 1.66333220E-01 1.66333220E-01 1.66333220E-01	9.000000000000000000000000000000000000	ST R 52124-000 8 - 2000 8 - 2000

EXAMPLE PROBLEM 2 OUTPUT ELASTIC STRESSES AT x= 14.281

	TRAJECTORY	TIME STEP 1	
J	APEA (SO CH)	A (CH)	STRESS (HPA)
12545678901234567890	4.103336600000000000000000000000000000000	32111111111111111111111111111111111111	197524472000000000000000000000000000000000
20	1.63320E-01 1.63320E-01	1.58460E+00 1.56170E+00	-1.60548E+00 -1.5127 cE+00
	TRAJECTORY		
J	APEA (SO.CM)	V / 6 US	STRESS (HPA)
123456789011234567890	12000000000000000000000000000000000000	0 0 2 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	T 000 000 000 000 000 000 000 000 000 0
	TRAJECTORY 1		
J	AREA (SG.CM)	Y (CH)	STRESS (HPA)
123456789991111111112	4.0.02222222222222222222222222222222222	0.999999999999999999999999999999999999	19 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
	TRAJECTORY T		
J	AREA (SO.CH)	Y (CH)	STRESS (HPA)
12345676901234567890	4.12322222222211111111111111111111111111	99999999999999999999999999999999999999	11.00000000000000000000000000000000000
		B-80	

EXAMPLE	PROBLEM	1 2	OUTPUT
TRAJECTO	DRY TIME S	TEP	5

AREA (SO.CH)	Y(CH)	STRESS (HPA)
12000000000000000000000000000000000000	32211111111111111111111111111111111111	1.01149EE+000 3.78EE+000 3.78EE+0000 3.78EE+0000 3.78EE+00000000000000000000000000000000000

CASE 1 ANALYSIS ELASTIC STRESSES AT X= 17.133

ELASTIC ST	ANALYSIS RESSES AT X= 17.137	
TRAJECTORY	TIME STEP 1	
ADEA (CO CH)	V (CM)	STRESS (MPA)
11222222222222222222222222222222222222	68736799988EEE0000000000000000000000000000000	5 + 400 5 + 400 5 + 400 7 9 + 7 9 + 7 9 + 7 9 + 7 9 9 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
1.63320E-01	1.56170E+00	-1.79163E+00 -1.68818E+00
TRAJECTORY		
AREA (SO.CM)	Y (CH)	STRESS (MPA)
4.12578225550 4.12578225550 6.025788225550 6.025788225550 6.025788225550 6.025788225550 6.025788225550 6.025788225550 6.025788225550 6.025788225550 6.025788225550 6.025788225550 6.02578822550 6.02578822550 6.02578822550 6.02578822550 6.02578822550 6.02578822550 6.02578822550 6.02578822550 6.025788822550 6.025788822550 6.0257888822550 6.0257888888888888888888888888888888888888	6.99996	S 3 9 2 6 9 2 5 7 3 7 4 3 6 9 2 5 7 7 2 7 5 9 7 8 8 9 7 9 7 9 7 7 6 8 9 7 7 9 7 8 8 9 7 9 7 9 7 8 9 7 9 7 9
TRAJECTORY	ITHE STEP 3	
AREA (SQ.CH)	A (CH)	STRESS (HPA)
1 122222222222222222222222222222222222	68.9998E001 9998E001 9998E001 9998E001 9998E001 9998E001 9998-998E001 9998-998-98E001 11.35-88-88-88-88-88-88-88-88-88-88-88-88-88	1.000000000000000000000000000000000000

EXAMPLE	PROBLEM	2	OUTPUT
TRAJECTOR	Y TIME STE	P	4

12345678901234567890 1234567890 111111111111111111111111111111111111	EXAMPLE PROBLE P	Y(C) 9999000000000000000000000000000000000	## 110000000000000000000000000000000000
·		LYSTS ES AT X= 19.994	,
J 1234567 8901234567890	ARE A 100000000000000000000000000000000000	9960499968888889999999999999999999999999	STRESSON STREET
J	TRAJECTORY TIM	E STEP 2	
12345678901234567890	4.123742 	6.99910011 6.99910011 6.99910011 7.99910011 7.99910011 7.99910011 7.99910011 7.99910011 7.99910011 7.999100011 7.999100011 7.9991000011 7.9991000011 7.9991000011 7.9991000011 7.9991000011 7.9991000011 7.9991000011 7.9991000011 7.99910000000000000000000000000000000000	T C 506 T 5 T 1 C 5 C 7 C 7 C 7 C 7 C 7 C 7 C 7 C 7 C 7

EXAMPLE PROBLEM 2 OUTPUT TRAJECTORY TIME STEP 3

	TRAJECTORY T	IME STEP 3	
J	AREA (SQ.CM)	Y (CH)	STRESS (HPA)
12345678901234567890	4.13338822EE0022 4.1333882EE0022 6.033382EE0022 6.033382EE0022 6.033382EE0022 6.033382EE0022 6.033382EE0022 6.033382EE0022 6.033382EE0022 6.033882EE0022 6.038882EE0022 6.038882EE0022 6.038882EE0022 6.038882EE0022 6.038882EE0022 6.038882EE0022 6.038882EE0022 6.03888	99994999499949999999999999999999999999	\$ 111
	TRAJECTORY T		•
J	AREA (SQ.CH)	. Y (CH)	STRESS (HPA)
12745678904274567890	12222222222222222222222222222222222222	99999999999999999999999999999999999999	1.00111 6.0
	TRAJECTORY T		
J	AREA (SQ.CH)	Y(CH)	STRESS (HPA)
1234567 8761234567898	12222222222222222222222222222222222222	99809886 - 000 99809986 - 001 99809986 - 001 99809986 - 000 99809986 - 000 99809986 - 000 99809986 - 000 99809999999999999999999999999999999	11100000110000000000000000000000000000
	ELASTIC STRE		
j	TRAJECTORY T Area (So.ch)	INE STEP 1 Y(CH)	STRESS (MPA)
	4.12574E-01	6.99999F+03	5.89006F+00
1274567890127456780	12222222222222222222222222222222222222	999469988888888888888888888888888888888	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0

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EXAMPLE PROBLEM 2 OUTPUT

	TRAJECTORY T	IME STEP 2	
J .	AREA (SO.CH)	A (CH)	STRESS (MPA)
123456789311234567898	4.000000000000000111 1.00000000000000000	321111111111000000000000000000000000000	5 - 4 - 9 - 9 - 9 - 9 - 9 - 9 - 9 - 9 - 9
9 10 11	6.03142E-02 6.03182E-02 6.03182E-02	1.14050E+00 1.29070E+00 1.44090E+00	2.37054E-01 -5.12025E-01 -1.26111E+00
13 14 15	6.03382E-02 1.49435E-01 3.22271E-01	1.74130E+00 1.74130E+00 1.82340E+00	-2.01018E+00 -2.75926E+00 -3.16871E+00 -3.25746F+00
16 17 18	1.63320E-01 1.63320E-01 1.63320E-01	1.78823E+03 1.69826E+00 1.63023E+00	-2.99320E+00 -2.54462E+00 -2.20533E+00
19 20	1.63320E-01	1.58460E+00 1.56170E+00	-1.97777E+00 -1.66358E+00
	TRAJECTORY T	INE STEP 3	
J	AREA (SQ.CH)	A(CH)	STRESS (MPA)
12345678904234567890	12222222222222222222222222222222222222	321111110000000000000000000000000000000	11-10-10-10-10-10-10-10-10-10-10-10-10-1
9 8 9	6.03382E-02 6.03382E-02 6.03382E-02	6.89899F-01 8.40698E-01 9.90298E-01	5.42415E+00 3.78863E+00 2.15310E+00
10 11 12	6.03382E-02 6.03382E-02 6.03382E-02	1.29070E.00 1.44090E.00 1.5911CE.00	-1.11794E+00 -2.75347E+00 -4.38899E+00
13 14 15	6.03382E-02 1.49435E-01 3.22271E-01	1.74130E+00 1.82340E+00 1.84120E+00	-6.02452E+00 -6.91850E+00 -7.11232E+00
17 18 19	1.63320E-01 1.63320E-01 1.63320E-01	1.69826E+00 1.69826E+00 1.63023E+00	-5.55567E+00 -5.55567E+00 -4.81507E+00
20	1.63320E-01	1.561706+00	-4.06889E+00
	TRAJECTORY TI	ME STEP 4	•
J	AREA (SO.CM)	A (CH)	STRESS (HPA)
3,	4.12574E-01 6.03382E-02 6.03382E-02	6.99999E-03 8.90938E-02 2.39309E-01	1.92865E+01 1.79458E+01 1.54930E+01
5 6 7	6.03182E-02 6.03182E-02 6.03182E-02	5.39699E-01 6.39699E-01 6.39699E-01	1.30402E101 1.05574E+01 8.13459E+00
	6.03382E-02 6.03382E-02 6.03382E-02	9.9029AE-01 1.14050E+00 1.29070E+00	3.22900E+00 7.76212E-01 -1.67658E+00
1274567 89012745678	4	6.999E-001 6.999E	\$ 5 5 6 6 7 7 7 7 8 7 8 7 8 7 8 7 8 8 6 7 8 8 6 7 8 8 8 7 8 8 8 7 8 8 8 7 8 8 8 7 8 8 8 7 8 8 8 7 8 8 8 7 8
15 16 17	3.22271E-01 1.63320E-01 1.63320E-01	1.84120E+00 1.78820E+00 1.69826E+00	-1.06653E+01 -9.80095E+00 -8.33213E+00
19 20	1.63320E-01 1.63320E-01 1.63320E-01	1.630236+00 1.58460E+00 1.56170E+00	-7.22115E+00 -6.47602E+00 -6.10210E+00
	TRAJECTORY TI		
J	AREA (SO.CH)	A (CH)	STRESS (HPA)
1 2	4.12574E-01 6.03382E-02	6.99999E-03 8.90998E-02	1.28602E+01 1.19662E+01
5	4.12574E-012 6.03382E-02 6.03382E-02 6.03382E-02 6.03382E-02 6.03382E-02	3.89499E-01 5.89699E-01 6.89899E-01	1.03307E+01 8.69520E+00 7.05967E+00
8	6.03362 E- 02 6:03382E-02	8.40098E-01 9:94898E-01	3.78863 8 +88 8:15358 8 +88
1234567 8901234567890	6.0022111 73734825EEE-0011 73734825EE-0011 737374825EE-0011 737374825EE-0011 737374825EE-0011 737374825EE-0011 7374825E	1.29070E+00 1.44090E+0J 1.59110E+00	-1.11794F+00 -2.75347E+00 -4.38899E+00
14 15	1.49435E-02 3.2271E-01	1.82340E+00 1.82340E+00 1.84120E+00	-6.02452E+00 -6.91850E+00 -7.11232E+00
4.9			
17 18 19	10222222222222222222222222222222222222	6.99999494 6.99994994 6.999949949 6.999949949 7.999499949998 8.99949998 8.99949998 8.999949998 8.999949998 8.999999 7.99999999999999999999999999999	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1



EXAMPLE PROBLEM 2 OUTPUT
CREEP PREDICTION COMPUTER PROGRAM
TPSC EXAMPLE PROBLEM 2 TIME HARD

SINGLE FACED CORRUGATION TPS

SKIN GAGE = .0216 CH COPRUGATION GAGE = .0140 CH NUMBER OF CORRUGATIONS = 14 PITCH LENGTH = 3.630 CM FLAT LENGTH = .711 CM FANEL EDGE LENGTH = .360 CM COPRIGATION ANGLE = 12.630 DEGREES PANEL DEPTH = 1.852 CM CALCULATED MOMENT OF INERTIA = 1.2036087 CH*+4 ELASTIC NEUTRAL AXIS = 1.188 CM

PANEL LENGTH = 45.70 CM PANEL WIDTH = 51.60 CM

NEGATIVE BEAD RADIUS = -3-180 CM WIDTH * , 2.620 CM

APPLIED LOADS UNIFORM PRESSURE (PLATE OPTION)

BENDING MOMENT DISTRIBUTION

	BEAM ST	ATION (CH)						
TIME	2.86	5.71	8.57	11.42	14.28	17.14	19.99	22.85
1.33 4.67 7.50 8.50 11.33	7.44 7.44 16.25 24.37 16.25	20.88 20.88 45.60 68.38 45.60	32.41 32.41 70.75 106.11 70.75	42.01 42.01 91.72 137.55	M KILOS) 49.69 49.69 108.49 162.70 108.49	55.45 55.45 121.07 181.57 121.07	59.29 59.29 129.45 194.14	61.21 61.21 133.65 200.43 133.65

TRAJECTORY DATA

TIME (MINUTES)
PRESSURE (PA)
TEMPERATURE (DEG K)

TIME START	ENO	PRESSURE	MIOSPAN SKIN Temperature
0.00 1.33 4.67 7.50 8.50	1.33 4.67 7.50 8.50 11.33	759.000 759.000 1652.000 1652.000	1122.0 1231.0 1225.0 1014.0

GYCLIC CREEP EQUATION DEFINITION

LN(STRAIN) = -2.89414E+00 -1.74300E-02 *(TIHE) -6.65548E+00 *(1.7TEMP) 5.48920E-01 *LN(TIHE) 1.31015E+00 *L(STRESS) 1.9131CE-01 *LN(TEMP) 2.10000E-04 *TIME*STRESS*TEMP

WHERE

TIME = HOURS TEMPERATURE = DEG K/1800. STRESS = MPA

EXAMPLE PROBLEM 2 OUTPUT ELASTIC DEFLECTION SUMMARY

				4					
TIME (HQ 1.33 4.67 7.57 8.50 11.33	BEAM STATI 2.86 .0016 .0016 .0051 .0034	ON 15.033.57 .000.66.07	8.57 • 0044 • 0049 • 0145	.0056	14.28 .0066 .0146 .01214	.0073 .0159 .0239	19.99 .0077 .0077 .0169 .0269	22.65 .0079 .0079 .0178 .0178	
			FIRST CYCL	E CREEP DE	FLECTION S	SUMMARY			
TIME 1.357 1.550 1.533	BEAM STATION 2.86 .000016 .00032 .00045	1CH) 5.71 .00011 .00063 .00068	8.57 .00017 .000452 .00117 .00128	11.42 .00021 .00058 .0018 .00149 .00163	14.28 -0002 -0005 -0017 -0017	17.14 5 .000 19 .000 19 .000 2 .000	19.5 28 .6 76 .6 96 .6	99 100 30 100 81 101 64 102 05 102 27	22.85 .00030 .00082 .00168 .00232
			CREE	EP DEFLECTI	ON SUMMAP	Y			
CYCLE 12 3	BEAM STATION 2.86 .00045 .00069 .00105	(CH) 5.71 .00088 .00136 .00206	6.57 .00128 .00198 .00253	11.42 .00163 .00253 .00323	14.28 .001 .003 .004	17.14 92 .003 96 .003 61 .005	19. 14 31 24	99 00227 00352 00450 00534	22.85 -00232 -00459 -00545
				CREEP P	REDICTION	COMPUTER P	ROGRAM		
•						AINS (PERCE	NT)		
					•		•		-
HEIO 1357 - 00 89957 - 00 8999 - 23 8999 - 34 995 -	80005011050006199999115 95691843497905184343888 6776665134790500395000 8000000000000000000000000000000000	BEAN 5 132759987 26635232487 84407098 8759987 26575987 5987 5987 5987 5987 5987 5987 598	777673164711987468734198 727057316471198768498 755544387219619766498 7555443872196197878722221 86000000000000000000000000000000000000	10000000000000000000000000000000000000	98745-42-00-00-00-00-00-00-00-00-00-00-00-00-00	10000000000000000000000000000000000000	6923 6923 6923 6923 6923 6923 6923 6923	06766 06879 06452.	2 0011164311595372 00111663911475725066 0010166969144757256672 00101669691447577596672 0010169691447577596672 0010169691447577596672 0010169691444
				CREEP !	PREDICTION	COMPUTER F	POGRAM		
						STRESSES (S	1P4)		
110 v # =		uedā Živiti	יא (נֻא <u>)</u> _		4			20	
1008794990113579134223267	7.67167.411.772071208	23,22,22,23,33,24,43,32,22,00,000,000,000,000,000,000,000,0	7	9.07.6.00.00.00.00.00.00.00.00.00.00.00.00.0	79 05 5 5 6 6 6 10 30 0 30 0 30 0 30 0 30 0 30 0	957666990706324745	9	20000000000000000000000000000000000000	202211111111222223322222 00000000000000000000000000



EXAMPLE PROBLEM 2 OUTPUT

CREEP STRAINS (PERCENT)

CYCLE :	2
---------	---

HE 0023569991577747474725326	286457 286467 286467 286467 286467 28666666 286666666 2866666666 2866666666	BEAM STATIC 5000445529 0000445529 00000000000000000000000000000000000	800000460000000000000000000000000000000	1 10011 9956 2 8 8 9 5 5 6 7 3 4 4 4 9 9 6 7 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9	19619997778841 2849778997778841 2849778987778841 2849778987778841 284978987789117	7.001148777889944974	19050968954557729394 9977995245677478394 99779952457677478394 997799524578478394 9977997678787878787878787878787878787878	0417168472776186526 668872872976476476476 69867877647776471020 5986787776477764711020 598678777774111020 598678777774111020 6986777774111020 6986777774111020
1.5846	0000464	0001781 0001666	6003159	0004244	0005537	0006394	0007694 0006971 0006599	0[08022 0007268 0006880

CREEP PREDICTION COMPUTER PROGRAM RESIDUAL STRESSES (MPA)

CYCLE 2

T013579-13579-1342281 F799999-13579-1342281 G289899-25579-1342424-2489 G287875779-12447-2489 F792875779-12447-2887-2887-2887-2887-2887-2887-2887-	57.44 EEEE 0004 F	BE 27-25-7-76-42-11-19-22-22-22-22-22-22-22-22-22-22-22-22-22	222221111232224332 212221111232224332 212221111232221112 21222111121211112 21222111121211112 2122211112 2122211112 2122211112 212221112 212221112 212221112 212221112 212221112 212221112 212222 21222	2	2021111111322233222 00000000000000000000000000000	120111111112000030000000000000000000000	99 E E E E E E E E E E E E E E E E E E	20001111111110000000000000000000000000
1.7882	1.44E-033 2.434E-033 4.66E-033	-2.59 E - 03 2.59 E - 02 1.50 E - 02 1.51 E - 02 1.61 E - 02	7.00E-03	1.76E-02 2.98E-02 3.71E-02 3.96E-02 4.01E-02	1.28E-02 3.65E-02 4.56E-02 4.87E-02 4.93E-02	1.60E-02 1.60E-02 4.25E-02 5.64E-02 5.71E-02	1.4.55E-022 4.55E-022 5.65E-022 6.12	1.45E-022 1.471E-022 5.69E-022 6.37E-032

CREEP PREDICTION COMPUTER PROGRAM CREEP STRAINS (PERCENT)

CYCLE 3

H0135791757913422326 H7999900 - 11117122326 H0999900 - 111774792888 H0023568494040488826 H1117474774774778826	2000011120AC6127 137 4425 8011121AC6127 137 425 8011121AC6127 137 425 8011121AC6127 137 425 8011121AC6127 137 437 437 437 437 437 437 437 437 437 4	8EAH 500000 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	8.57 7.734499 6.57 7.734499 6.57 6.57 6.57 6.57 6.57 6.57 6.57 6.57	11030100000000000000000000000000000000	888799890335719897120 2188989035775757575868 88889911655775575368 91165575757575757575757575757575757575757	170021694201010759444444444444444444444444444444444444	19057558 99220564498873666160896494965964949659649649659659659659659659659659659659659659659	730694614325531570 96259497510375477462 55314651470572509257477462 6202214170522509257477462 8202214170522509257477462 8202214170525747462 8202214170525747462 8202214170525747462 8202214170525747462 820221417052574747462 82022141705257474747474747474747474747474747474747
1.6302 1.5846 1.5617		0002507 0002272 0002151		0006262 0005671 0005367			0009803 0008878 0008403	



EXAMPLE PROBLEM 2 OUTPUT

CREEP PREDICTION COMPUTER PROGRAM
RESIDUAL STRESSES (MPA)

CYCLE 3

HEIGHT		BEAM STATIC	IN (CM)					
.0070	2:86	5.71		11.42	14.28	17.14	19.99	22.85
.J891	9.528-03	2.885-02	5.37E-02	8.7CE-02	1.08E-01	17.14 1.13E-01	1.186-01	1.22É-01
.2393	2.45E-03 -6.86E-03	1.09E-02	1.94E-02	1.95E+0Z	2.92E-02	3.54E-02	4 89E-02	5 09E-02
3 8 9 5	-1.348-02	-2.49E-32 -5.01E-02	-3.00E-02	-5.47E-02	-6.87E-02	-8.04F-02	4.89E-02 -7.76E-02	-8.07E-02
.5 397	-1.95E-02	-7.30E-02	-8.49E-02 -1.26E-01	-1.25E-01	-1.56F-01	-1.81E-01	-1.88F-01	-1.96E-01
6899	-2.355-02	-8.808-02	-1.52E-Di	-1 . 10E - 01	-2 -2 5E -01	-2.59E-01	-2.74E-01	-2.85E-01
.3461	-2.645-02	-9.335-32	-1.62E-01	-2.29E-01	-2.69E-01	-3.10E-01	-3.31E-01	-3.45E-01
.99.3	-2.49E-02 -2.25E-02 -1.50E-02	-6.528-02	-1.486-01	-2.10E-Ci	-2.85E-01 -2.59E-01	-3.26F-01	-3.52E-01	-3-67E-01
1.14.5	-1.508-02	-5.81E-02	-1.028-01	-1.468-01	-1.82E-01	-2.98E-01 -2.10E-01	-3.21E-01 -2.25E-01	-3.34E-01
1.2917	-6.31F-04	-3.98E-03	-6.928-03	-1.15E-02	-1.49E-02	-1.71E-02	-1.756-02	-2.35E-01 -1.82E-02
1.4439	4.89E-03 5.84E-03	1.65E-02	2.86E-02	3.918-62	4.81E-02	5.56E-02	6.005-02	£.34E-02
1.5911	5.846-03	1.99E-02 1.15E-02	3.41E-02 1.90E-02	4.78E-02	5.91E-02	6.656-02	6.09E-02 7.37E-02	7.678-02
1.8234	2.335-03	1-156-02	1.90E-02	2.82E-02	3.476-02	4.07F-02	4.226-02	4.40E-02
1.8412	5.56E-04 -1.02E-03	-8.61E-04	-3.09E-03	-6.25E-03	-4.76E-03	-2.23E-03 -1.27E-02 1.28E-02	5.49F-04	5.54E-04
1.7862	1.21E-03	5 105 - 03	-9.03E-03	-8.55E-03	-1.408-02	-1.276-02	-1.30E-02	-1.36E-02
1.6983	2.54F-03	1.405-03	2.51E-02	-8.55E-03 8.19E-03 3.62E-02	1.308-02	1.285-02	1.04E-02	1.09E-02
1.6332	2.54E-03 5.54E-03	1.875-02	3.196-02	4.51E-02	4.47F-02 5.57E-02	5.21E-02	5.50E-02 6.92E-02	5.73E-02 7.20E-02
1.5846	5.87E-03 5.94E-03	2.008-02	3.44E-02	4.41F-02	5.948-02	6.886-02	0.45F-05	7.20E-02
1.5617	5.948-03	-2.165 -995 -022 1.475 -022 2.035	3.49E-02	4.81E-02	6.01E-02	6.968-02	7.41E-02 7.51E-02	7. 72E-02 7. 02E-02
						04 705 -05	14976-05	1.065-85

CREEP PREDICTION COMPUTER PROGRAM CREEP STRAINS (PERCENT)

CYCLE 4

TE -PENDAGANA TE ANDROG TO PENDAGANA TE ANDROG GO BERBER DE ANDROGANA TE ANDROG GO BERBER DE ANDROGANA TE ANDROGANA TO DENNEGATE ANDROGANA TE ANDROGANA TO DENNEGATE ANDROGANA TE ANDROGANA TO DENNEGATE ANDROGANA TE	2.00167334 0.00167336 0.00167336 0.00167336 0.001673736 0.0016737376 0.0016737776 0.001677776 0.00167777777777777777777777777777777777	BE A 57 0 B 0 0 1 1 1 1 5 7 6 1 2 2 7 0 6 5 6 7 1 1 7 1 5 7 6 1 2 2 7 0 6 5 6 7 1 1 7 1 5 7 6 1 2 2 7 0 6 5 6 7 1 1 7 1 5 7 6 1 2 2 7 0 6 5 6 7 1 1 7 1 5 7 6 1 2 2 7 0 6 7 1 1 7 1 5 7 6 1 2 2 7 0 6 7 1 1 7 1 5 7 6 1 2 2 7 1 7 1 7 1 7 1 7 1 7 1 7 1 7 1 7	8.57 7.282465 000109370 000109370 00010937410 0001093741475 0001093741475 0001093741475 0001093741475 0001093741475 0001093741475 0001093741475 0001093741475 0001093741475	11019999999999999999999999999999999999	1402245483 -000197483 -000197483 -000197483 -0001477033 -000147763 -000147763 -000147763 -000147763 -000147763 -000147763 -000147763 -000167763 -0001	17.0022277366 469476883185567244 46947687587567424 46947687768758756776877687768767676767676767	9987445246 9987445246 9987445246 190022155246 19002215576 19000000000000000000000000000000000000	1197 81200 7 1 1 1 1 9 7 8 1 2 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
1.5846	0000776 0000704 0000666	0002965 0002686 0002542	0004769 0004515	- 0007433 - 0006729 - 0006368		0010684 0009672 0009152	0011626 0010526 0009962	0012122 0010975 0010386

CREEP PREDICTION COMPUTER PROGRAM RESIDUAL STRESSES (MPA)

CYCLE 4

		BEAM STATIO	N (CH)					
HEIGHT	2.86	5.71		11.42	14.28	17.14	19.99	22.85
•0070	9.10E-03	3.68E-02	6.24E-02	1.036-01	1.25E-01	1.45E-01	1.52E-01	1.58E-01
.0891	2.55E-03 -9.85E-03	1.07E-02	2.56E-02	1.96E-02	3.67E-02	4.342-92	\$. 55E	5 705-02
• 2 3 9 3	-9.855-33	-2.78E-02	-2.08E-02	-6.72E-02	-8.16E-02	-9.51F-12	-9. 11F-02	-0.706-02
3895	-1.656-02	-5.79E-02	-9.80E-02	1.03E-01 1.96E-02 -6.72E-02 -1.48E-01	-1.82E-01	-2.108-01	-2.19F-ñi	-3.28F-01
.5397 .6899	-2.31E-02	-8 . 45E-02	-1.45E-01 -1.76E-01	-2.11E-D1	-2.61E-01	-9.51E-32 -2.10E-01 -3.00E-01	5.55E-02 -9.33E-02 -2.19E-01 -3.18E-01	5.78E-02 -9.70E-02 -2.28E-01 -3.31E-01
.3401	-2.77E-C2	+1.02E-31	-1.76E-01	-2.53E-01	-3.13E-01	-3.59E-01	-3.84E-01	-4.00E-01
:3333	-2.93E-02 -2.65E-02	-1.06E-01	-1:08E-61	-2.68E-01	-3.32E-01	-3.81E-01	-4.09F-31	~4.25F-01
1.1475	-1.78E-02	-9.89E-32 -6.85E-32	-1.19E-01	* 2 • 45t = U1	-3.02E-01	-3.44E-01	-3.71E-01	-3.86F-01
1.2907	-8.78E-14	-4.94E-03	-7.38E-03	-1.72E-01 -1.40E-02	-2.13E-01	-2.46E-01	-2.64E-01 -2.11E-02	-2.75E-01
1.4469	5.656-03	1 805-09	7.415-02	4.568-02	-1.88E-02	-2.07F-02	-2.11E-DZ	-2.19E-02
1.5911	5.65E-03 6.81E-03 2.81E-03	2.285-15	3.41E-02 4.05E-02	5.616-02	6.79E-02	6.416-02	7.035-02	7.32E-02
1.7413	2.816-03	1.318-02	2.325-02	3.38E-02	3.996-02	7.92E-02	8.55E-02	8 • 90F - 05
1.8234	1.555-03	-2.20E-03	-2 93F-03	-6.11F-03	-4.51E-03	-1.48E-03	-3.975-02	5.18E-02
1.5412	-1.32E-03	-4.07E-33	-8.77E-03	-9.26E-03	-1.1 CF-02	+1.316-02	-1.705-02	-2-105-03
1.8412 1.7882 1.6983	-1.35 -1.35	2.20E-03 -2.20E-03 -2.20E-03 -4.89E-03 1.70E-02	2.32E-02 -2.93E-03 -0.77E-03 1.38E-02	-9.26E-03 4.70E-03 4.30E-02	-1.1CE-02 1.37E-02 5.14E-02	8.098-03	4.97E-02 -2.07E-03 -1.39E-02 6.77E-03	7.075-03
1.0403	2.51E-73	1.705-02	3 • 0 7E - 0 2	4.30E-02	5.14E-02	8.09E-03 6.05E-02	5 43F-02	6-695-02
1.63C2 1.5846 1.5617	6.476-03	2 x 1 4F = 11 2	3.80E-02	5.31E-02	6.40E-02	7.48F-02	8.04E-02	8.37E-02
1.5513	6.85 - 03	2.32E-02	4.08E-02	5.645-02	6 - 83E - 02	7.96E-02	8.60E-02	8.95E-02
4.3011	6.91E-03	C . 32E-02	4.14E-02	5.70E-02	6.90E-02	8.04E-02	8.04E-02 8.60E-02 8.71E-02	165EE - 022 165EE - 022 165EE - 022 165EE - 022

APPENDIX C

TPSC

PROGRAM LISTING

```
PROGRAM TPSC(INPUT, OU FUT, TAPES=INPUT, TAPE6=OUTPUT)

DIMENSION PRESS (10) , (200 (10) , 0X1 (Mc (10) , X72 (20) (10) , 0X1 (Mc (10) , X72 (20) (10) , 0X1 (Mc (10) , X72 (20) (10) , 0X1 (Mc (10) , X72 (10) (10) , 0X1 (
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               IPSC
IPSC
IPSC
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              20
                                    12345
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                30
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150
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                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      230
230
240
250
                                                                                                                                                , ICCON , NICCON
, INCYC , ITIME
, NSTAT , SEC
, ESTIFF , INDD2
                                                                                                                                                                                                                                                                                                                                       LINTP,
NASECI,
DETWO
                                                                                                                                                                                                                                                                             · ECOMPP
· IEONTP
· NSECI
· INDSTR
                                                                                                                                                                                                                                                                                                                                                                                                                   IDIMEN .
                                                                                                      TEDAST
                                   CIRESID , RESSIN
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     С
                      NEWCAS=1
10 DO 20 II=1.75
20 Z(II)=0.
0000
                                         DEFAULT VALUES
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     1420
1420
1420
1420
                  IRESID=0
DO 30 J=1.60
RESSIR(J)=0.
30 CONTINUE
DO 40 LL=1.10
PLOAD(LL)=0.
PRESS(LL)=0.
40 FEMP(LL)=0.
ITIME=0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     TPSC
TPSC
TPSC
TPSC
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      4 30
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    450
                                         I FON FP = 0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     480
                                          I IN TP=0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     490
                                          ID IMEN=0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     500
                                        ILDAD=0
IEDMST=0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   520
                                       NICON=1
                                         IFCON= [
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    540
                                      D(1)=1.
IND[FD=0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   560
```

		C(1)=1.						IPSC	570
		MO TEL = 0 MOLOD = 0			•	•		TPSC TPSC	580
		INDSUP=0						TPSC	590 600
		TOLO A C = 1 TOLO A C = 1						TPŠČ TPŠC	610 620
		HARDÜP=1			•			TP SČ	530
		1MDS TR = 0 Tri0.4(H) = 0			-			1230 1230	640 550
		S=1.		-	_	•		IPSC	660
		INDPLA=0 INDPLA=0						TH SC	670 680
		DEPIH=0.		**** * * * * * * * * * * * * * * * * *				 IPSC	690
		PĪ TCH=0. FLAΓ=0.			-		•	TPSC	700 710
		EDGE=0.			•	•		 _JP SC	720
		[S=0. TC=0.			_			TPSC TPSC	7.30 7.40
		XÚGÍH=0. TR=0.			-			TPSC	150
		RIBFLG=O.			•		•	TPSC TPSC	760 770
		ZPNED1=0. ZPNED2=0.	•		•••		-	0241 0241 0241	780 790
		TZEE=O.			_	•		IPSC	800
		ZEESE1=0. ZEESE1=0.		•				15 2C	820
		ZEEFF=O.			-			IPSC	8 30
		ZEEFF1=0. BW10=0.			-			TPŠČ TPSC	8 4() おり()
		BDEP=0.		•	-	•		TPŠČ	860
		BRAD=0. ALEN=0.						THSC	870 880
		PÁNWID=0. IMDD2=0			•			- IPSC	890
		[NDPLA=0		•	-		-	[PSC	900 910
		D(2)=0. D(3)=0.			•	•		1225	920 930
_		D(4) = 0.			_	•		IPSČ IPSČ	9 40
C C								-TPŠČ TPŠC	950 960
•		DUMLGE = 0.0						FPSC.	970
		NSFAT=6 NSFCT=10			-	•	•	1620	980 990
		SEC=10.			-	•		1P.S.C	1000
		NBSECT=6 READ (5,1760) AMI,AM2,AM3,AM	14.AM5				•	IPSC IPSC	
		READ (5.0REEP)			-		-	IPSC:	1030
		WRITE(6,ČŘĚĚP) NSECTI=NSECT+5		•	•			 125C	1040 1050
		NSEC T1=NSECT+1			-	•		IP S C	1060
		TÉ(ÎLÛADÎNÊ.OĴGU FO 6) DO 50 LL=1.NTIME	•					TPSC:	
		PLNAD(([])=PLNAD([])/.45359 PRESS([[])=PRESS([[])/6894.8						[PSC]	1090
		CUNTINUE			-		•	1620	
	60	CONTINUE IF(IDIMEN.NE.O)60 (U 70	•			•		LD S C :	1120
		DEP TH=DEP TH /2.540005						TPSC:	
		PICH=PICH /2.540005						IPŠČI	

FLAF = FLAF EDGE = FDGE (S = TS TC = TC TR = TR XLG TH = XLG TH RIBFLG = RIBFLG ZPNED1 = ZPNED1 ZPNED2 = ZPNED2 TZEES = TZEE ZEES F1 = ZEEFF ZEEFF = ZEEFF BWEDEP = BDEP BRAD = BRAD ALEN = ALEN PANTID = PANWID ZEES F = ZEES SE	/2.540005 /2.540005 /2.540005 /2.540005 /2.540005 /2.540005 /2.540005 /2.540005 /2.540005 /2.540005			IPSC1140 IPSC1140 IPSC1140 IPSC1140 IPSC1120 IPSC1220 IPSC1220 IPSC1240 IPSC1240 IPSC1240 IPSC1240 IPSC1240 IPSC1260 IPSC1260 IPSC1260 IPSC1340 IPSC1340
70 COMITABLE 1F(XLGTH.EQ.D) DX=XLGTH/[2.* DU 80 I=1.NSf 80 X(I) = I*0X DUMLGT = XLGT DO 90 II=1.NS 1PRINT(II) = 90 XPRINT(II) = 100 CALL GEOM(1RIBELG , IS 2TZEE , NZEE 4 MSECT , SEC IF(S.UI.ATION O IF(INDBD.ED.O HI = SURT(BRA ANGLE = BWIO/ ALPHA = ATAN(A I H I A T I I I PRINT(I()*0)X	ZEEFF1 , ZEESF1	, PITCH , , FLAT , , ZEEFF ,	PSC1350 PSC1340 PSC1340 PSC1340 PSC1440 PSC1440 PSC1440 PSC1440 PSC1440 PSC1440 PSC1440 PSC1440 PSC1440 PSC1450 PSC1550 PSC1550
C RIB SUPPORT G C CORRUGATION S C CORRUGATION S TELEMOREO - 2 110 ALMSECT = ALMS DOT 120 I = ASEC 120 ALT = AREABD*(GO FO 170 130 ALMSECT = ALMS DOT 140 I = ASEC 140 ALT = AREABD*N GO FO 170 150 ALMSECT = ALMS DOT 160 I = ASEC 160 ALT = AREABD*E 170 DOT 180 J = ASEC	NRIB-1)*2. ECT)-TS*BWID*NCUR I1.NSECFF CUR*2. ECT)-TS*BWID*(NZEE-1) I1.NSECFT NZEE-1)*2. [1.NSECFT -(J-NSECT)*.20)*ALPHA	<u> </u>		PSC1560 TPSC1540 TPSC1540 TPSC1540 TPSC1610 TPSC1650 TPSC1650 TPSC1650 TPSC1650 TPSC1650 TPSC1650 TPSC1650 TPSC1650 TPSC1650 TPSC1730 TPSC1730 TPSC1740

XX2=435(334 <u>0</u> 0)	FPSC1750
XX1=Y(NSECT)+H1 DO 190 K=NSECT1+NSECTF	1PSC1760
190 Y(K)=XX1-XX2*COS(BETA(K))	1PSC1770 1PSC1780
60 [0 220]	[PSC1740]
200 XX1=Y(NSEC1)-H1 00 210 L=NSEC1,NSECT 210 Y(L)=XX1+BRAD*COS(BETA(L))	- TPSC1800 - TPSC1810
210 Y(L)=XXI+BRAD*COS(BETA(L))	JPSC1820
C CALCULATION DE SECTION PROPERTIES DE BEAM 220 MAREA=NSECT	1PSC1830 1PSC1840
IF(INDBD.NE.O) NAREA=NSECTT	F SC 1850
$\begin{array}{lll} AYT()T &=& () \bullet () \\ ATOT &=& () \bullet () \end{array}$	IPSC1860
AYYIOI = 0.0	TPSC1870 TPSC1880
D0 230 J=1.NAREA $AY[0] = AY[0] + A(J)*Y(J)$	0081329] 1821390
$\Delta(1) = \Delta(1) + \Delta(1)$	16201410
230 AYYTO $T = AYYFOT + A(J)*(Y(J)**2)$ YBAR = AYFOT/A TOT	JPSC1920
XI = AYY[0] - A[0]*(YBAR**2)	PSC1930 TPSC1940
On 1550 I=1,NSCAT	128C1950
CC BEAM STATION LUOP	TPŠČÍ96Ő TPŠČÍ970
	. IPSC1980
∙ΠΟΡΩΛ=\(B)P+1 IF([O]MEN.EO.O)GO TO 250	- IPSC1990 IPSC2000
WR1FE(6,1770)LOOPCA,X(I)	1PSC291a
GO TO 260 250 SUBSIX=X(I)*2.54	TP \$62020
250 SUBSTX=X(I)*2.54 WRITE(6:1770)LOUPCA.SUBSTX	[PSC2030 [PSC2040
260 CONFINUE TECTRESID.NE.01GO TO 280	[PSC2050 [PSC2060
DO 270 J=L.NAREA	1PSC2070
270 RESSTR(J)=RESSTN(I,J) 230 CONFINUE	PŠČŽŮŠŮ PSCŽŮŠŮ
IIntE1 = 0.0	, TPSC2100
C ÇALÇULA TION OF TEMPERATURE AS A FUNCTION OF BEAM LENG	TH' [PSC2110]
16(18D) (60-1) GO 10 300	(ロじごうしえの
C TEMPERA DIRE CALCULATED VIA EQUATION: INDTEL = 0 C EQUATION METHOD IS ALSO USED TO TEMPERATURE IS CONSTA	NI 12802140 VI 12802150
X 12(1) = [[1] + [[2]*X[]) + [[3]*X[]]**2 + [[4]*X[])*	*3' IPSC2160
60 + 0.310	TPSC21/0
300 XIN = X(I)	. TPSC2180 TPSC2190
CALL TRIKP(XTEMP,1,XIN,0.0,XTMP,IE) XTP(I) = XIMP	Tr SC2200
IF(IE.NE.O) WRITE (6.1780) XIN	PSC2210 TPSC2220
310 CONTINUE	[PSC2230
C CALCULATION OF TEMPERATURE AS A FUNCTION OF BEAM DEPT LE(INDIED.EN.1) GO [U 330]	TUCCETION
C TEMPERATURE CALCULATED VIA EQUATION; INDTED = 0 C EQUALION METHOD IS ALSO USED TO TEMPERATURE IS CONSTA	JPSC2260
DO 320 J=1.NAREA	NT
320 $Y[P(J) = O(1) + O(2) * Y(J) + O(3) * Y(J) * *2 + O(4) * Y(J) *$	*3 IPSC2290
GO ID 350 C LEMPERATURE CALCULATED VIA LABLE-LOOKUP; INDIED = 1	TPSC2300 TPSC2310
330 DO 340 J=1, NAREA XIN = Y(J)	PSC2 320
XIN = Y(J)	TP\$C2330

	CALL [BL <p(yfemp,1,x[4,0,0,y[mp,[e])< th=""></p(yfemp,1,x[4,0,0,y[mp,[e])<>
17.	THE AND A STATE OF THE STATE OF
45	CONTINUE - CALCULATION OF CUTAL IN INCOMPANIES AT MARKET AND A STANDER
(DO 370 K = 1 MICHAEL PROPERATORES AT X AND AT ANY TIME IN THE CYCL
2.	f(x,t) = femp(x) * x fp(t) * x fp(t)
376	CONCINUÉ -
 -	- CALCULATION OF MUDULUS OF ELASTICITY AS A FUNCTION OF TEMPERATURE - IF(INDMO), EQ. () GO (O 400 - MODULUS OF FLASTICITY CALCULATED VIA FOLIATION: INDMOD =: 0
C	- EQUATION METHOD IS ALSO OSED THE MODULUS IS CONSTANT
2	DU 390 K=1,NT[ME
.,	1ECOFFF(4) \$1(K,t) **2 +
	60 10 722
400	MODULUS OF ELASTICITY CALCULATED VIA TABLE-LOOKUP; INDMOD = 1
	The state of the s
6.17	TIN = (((,)) CALL THLKP(FIEMP,1,TIN,0.0,EMOD,IE) E((,)) = EMOD) DIF((F,NE.O) WRITE (6.1800) TIN
420	$E(K_{11}) = EM(1)$ $E(K_{11$
43(CONTINUE : NOLUD = 1 (POI
	IF(ILOAD.EQ.1)GO TO 450 DO 440 K=1.NIME DO 440 L=1.NAREA E(K,1)=E(K,1)/6894.8 CONTINUE PLATE SULUTION
440	00 440 [=1,NAREA
. C C C	PLATE SOLUTION
Ç	CONTINUE PLATE SULUTION IF(INDEDO.ED.1) GO TO 630 IF(INDEDO.ED.0) GO TO 560 DEOWF=XI/PANWID IF(INDO.ED.1) GO TO 420 DETGO= IS *IS*IS*IS*IS*IS*IS*IS*IS*IS*IS*IS*IS*IS*
	IF(IND_DD.EQ.1) GQ_TQ_630 IF(INDPL4.EQ.0)GQ_CQ_560 DEOMF=XI/PANWID
	DETMINERAL/PANWID
460	TE(TND 2. EU. O GU TU 560
•	IF(DECMO.GI.DECME)GO TO 560
C C C	SOLUTION FOR LEKHNITSKII MAX MOMENT
U	DRA(=0)=0NE/DEINO IELDRA(-GT-26 NG) ID 520
	ELEK=(PANWID)/X/GTH)*(GEH)*(GEH)*(GEH)**
	IF(ELEX-GE-1.AND-ELEX-LT-1-5)GO TO 470 IF(ELEX-GE-1.5-AND-ELEX-LT-2-0)GD TO 480 IF(ELEX-GE-1.5-AND-ELEX-LT-2-0)GD TO 480
	IF(ELEX-6E-2-5-AND-ELEX-1[-22-5]60 10 490
	- \$\frac{1}{2}\frac{1}
	1 F (E (E X • G E • D • G) G G F G D 5 Z G

				In carron an
4/0	XMU11=.0368-(ELEK-1.0)*(.03680230)/.5 XMU22=.0728-(1.5-ELEK)*(.07280368)/.5	<u></u> -	•	12502930 12502940 12502950
480	GD (U 530 XMU11=+0280-(ELEK-1+5)*(+0280-+0174)/+5 XMU22=+0964-(2+0-ビビビベ)*(+0364-+0723)/+5			12802960 12802970
490	G(1 10 530 XMIII = .0174-(ELEK-2.0)*(.01/40099)/.5 XMU22=.1100-(2.5-ELEK)*(.11000964)/.5	-	•	12502980 12502990 12503000
	co 10 530	-		15203010 15203010
500	XMU11=.0099-(ELEK-2.5)*(.00990055)/.5 XMU22=.1172-(3.0-ELEK)*(.11/21100)/.5 GD TO 530	_		TP SC 30 30 TP SC 30 40
510	XMU11=.0055-(ELEK-3.0)*(.00550004)/2.0 XMU22=.1245-(5.0-ELEK)*(.12451172)/2.0	- -	•	12803050 12803050 12803070
520	GO FO 530 XMU11=0.0 XMU22=.1250		•	12503040 12503040 12503090
530	CONTINUE XUEXH=(X4U2Z+XMU11*XNU*(DEUNE/DE(4U)**•5)	ӿҳҵ҈ӹӖҥ҂ҳҵӫҬ	н _	1PSC3100 1PSC3110 . TPSC3120
	\$UMPRX=0. \$UMPRY=0.		•	TPSC 31 30 TPSC 31 40
	\$1)MX I N=(). \$1).4Y I N=0.	-	•	TPSC 3150
	SUMXZR=0.		•	18503160 18503170
	SUMY 7 R = () . XMM = 1 .	_	•	18SC3180
540	CONTINUE	-		12 SC 3190 12 SC 3200
	ÄLSUBM=XMM*3.14159*PANWID*.5/XLGTH XLAMDA=ES(IFF/(XLGIH*)=UNE)_	1 		TPSC 3210
	- HCTN= 1ANALALSHRM1//SORF(1TANALALSUBM)*1	ANH (AL SUBM)	}}	TP SC 3220
	HCOS= 1./(SORT([fANH(ALSUBM)*) P11=XHU*(1.+XNU)*HSIM	ANHIALOUDMI	11.	TP SC 32 40
	Pf2=XNU*(1XNU)*HCO\$*AUSUBM	-	•	TP SC 3250 TP SC 3260
	P T3= 2.*ACOS+ALSUBA*HSIA P[4=(3.+XAU)*(1XAU)*HSIA*HCUS			THSC 3270
	PT5=(1XNU)\$*2.*ALSUBM	-	•	[PSC 3280 [PSC 3290
	P[6=2,*x4d4*3,14159*411A*HC(IS**2. P17=xMJ*(1,-XGI))*HSIN		•	IB 2C 3 300
	PFR=XMM*3.14159*XLAMIN*HIUS	_	•	TP SC 3310 TP SC 3320
	PT9=4./(XMM*3.14159)**5. AM=PT9*(PT1-PT2-XMM*3.14159*XLAMDA*PT3)/(P『4-P『5+P『6	·)	1480,3330
	-BM=PT9÷(PT7+PT8)/(PT4-PT5+PT6)	-	•	12 SC 3 340 12 SC 3 350
	P(10=(XM4×3.14159/XLGTH) P(1=P1)0*P(10		•	TP SC 3 360
	PARTX=PTT1*(PT9+AM)*S[N(PT10*XLGTH/2.) PARTY=(PT11*AM+2.*BM*PT11)*SIN(PT10*XLGTH	/2.1		12 ŠČ 3370 12 ŠČ 3380
	SUMPRX=SUMPRX+PAR[X	, , , ,	٠	TP 50 3390
	SUMPRY=SUMPRY+PARTY AMZERD=P19*(P11-P12)/(P14-PT5)	•		12 S C 3400 12 S C 3410
	BMZERO=P79*PT//(P14-P75)	_	•	IPSC 3420
	AMINEN=-P[9*P[3/(2.*HIUS*HIUS) HMINEN=P[9/(2.*HCUS)		·	12 SC 3430 12 SC 3440
	- カメガス 1パキカミナナギ(ちとひもひをひばつっぴ)かとじが(ちしょりみだ) ピチリンス	. LOAN STU		IPSC 3450
÷	- PARYIN=(PT11*AMINEN+2.**BMINEN*PT11)*SIN(P - PARX7R=PT11*(PT9+AM/FXII)*SIN(PT1()*XUG1H/2	11()*XLG1H/2		12503460 12503470
	PARYZR=(PT11*AMZERU+2.*HMZERO*PT11)*SIN(P	T10*XLGTH/2	2.)	TPSC 3480
	SUMXIN=SUMXIN+PARXIN SUMYIN=SUMYIN+PARYIN	•	•	12503490 12503500
	SUMXZR=SUMXŽR+PARXZR	-		TP \$C 35 10

SUMYZR=SUMYZR+PARYZR	TPSC 3520
IF(XMM.FO.7.)GO TO 550 XMM=XMM+2.	1PSC 35 30 1PSC 35 40
GO 10 540 550 X[[30]=(X\STH\&\alpha\	1PSC 3550
TIMOIN=(XCGTH**4.)*(+SD-XCG-XND*SUMYIN)	1880,3570 1880,3530
C MIMEN IS FOR PRECEIPE LOADS	. [PSC3500
	1P.S.C.36.20
DO 580 M=1.NTIME 580 XMOM(M) = (PRESS(M)*XUGTH*(X(I) - DX/2.0)/2.0 - PRESS(1((X(I) - DX/2.0)**2)/2.0)*PANWID IE(INDPLA.ED.0)GU (U 560)	1) *
IF (X:G IH-GI-PANWID) GO TO 660	12 SC 36 70 12 SC 36 70 12 SC 36 80
DO 590 M=1,NIME XMIDM=PRESSAMANT CORRECT CORRESPONDED AND CORRECT CORRESPONDED AND CORRECT CORRESPONDED AND CORRECT CO	12 SC 3590 12 SC 3700
TF(\(\text{T} \) \(IPSC 3710 IPSC 3720 IPSC 3730
600 PR TMOM(I, M)=XMUM(M) GD (U 660 -	1256.37.40
C BEAM WITH FIXED SUPPORTS XX1=(XLGiH/2.)*(X[[)-(X[[])**2)/XLGiH-4LGiH/6.0)*PANWID DD 620 M-1 NITHE	. [PSC3750 TPSC3760 IPSC3770
DD 620 M=1,NTIME 620 XM(M(M)=PRESS(M)*XX1 GD 30 660	TP\$03780 IP\$03790
C MOMENTS FOR POINT LUADS 630 DO 650 K=1.NTIME	- IPSC 3800 IPSC 3810
IF(X(I).U.ALEN) GU T) 640 XMUM(K) = PLOAD(K)*ALEN/2.0	TP SC 38 20 TP SC 38 30 TP SC 38 30
$640 \times MIM(K) = PL(IAI)(K)*(X(I)+IX/2-1/2-1/2-1/2-1/2-1/2-1/2-1/2-1/2-1/2-1$	TPSC 38 40 PSC 3450 TPSC 3860
660 CONTINUE	. 10 36 38 70 TP 5C 38 80
CALL ITIMUM(C , D , NAREA , XMOM , Y	# P S C 33 9 O B AR • TP S C 39 O O
ANGECT TICHE, STRESE, THE INDIED . A	TCON : [PSC 39 10]
[HE[AC=0]	. IPSC 3930 IPSC 3940 IPSC 3950
00 670 J=1.NAREA 670 CS[RAN(J)=0.0	TPSC3960 TPSC3970
ĬĔ(ĬĬŨĂĎ,EŐ,Ĭ]ĠD TO 700 DO 690 Kl=l,NĬIME WRIJE(6,1820)Kl	16 23 34 9 16 23 34 9 16 23 34 9
WRITE(6,1830) DO 680 J=1,NAREA	1PSC4000 IPSC4010 IPSC4020
SUBA=A(J)*2.54*2.54 SUBY=Y(J)*2.54	12 SC 40 30
SUBS[R=S[RESE(K1,J)+6.8943/1000. WRITE(6.1840)J.SUBA.SUBY.SUBSTR	TP\$C4646 PSC4050 TP\$C4060
690 CONTINUE	12 50 40 60 12 50 40 70 12 50 40 80
GO FO 730 700 CONTINUE 00 730 FL 1 NETHE	14 \$ \(\) 40 9 \(\) 14 \$ \(\) 6 41 00
00 720 K1=1,NIME	IPSC4tio

```
WRITE(6,1820)(L

WRITE(6,1850)

DO 710 J=1.NAREA

710 WRITE(6,1840)J+A(J),Y(J),STRESE(K1,J)

720 CONTINUE

730 CONTINUE
                                                                                                                                                                                                     TPŠC4130
                                                                                                                                                                                                     12304140
12304150
                                                                                                                                                                                                     12504150
12504170
                DO 1540 KK=L-MCYCLE
      --- CYCLE LOOP
                DO 1530 KI=L,NFIME
      --- TRAJECTORY STEP LODE
          [] ME] = [] ME
TIME = ((KK - 1)*DXTIME(NTIME) + DXTIME(K1))/6Q.
IF(KK.+0.1.AMO.<1.+0.1) OF [U /50]
IF(INDLOD.EQ.1) GO TO 740
THE TAT(K1) = SAV [HE*PRESS(K1)*T(K1,1)*([4E-i[ME])
1/(SAVPRS*SAV TMP*TIMBER)+THE TAE([,K1)
    1/(SAVPRS*SAV TMP*TIMBFR)+THETAE(I,KI)
GO [O 750
740 THEFA T(KI) = SAVTHE*PLUAD(KI) * T(KI,I) * (TIME-TIMEI)
1/(SAVE(B) * SAVEMP * F[MBFR] + EHETAE(I,KI)
750 CONTINUE
GO [O 780
CONTINUE
AYNAC=YNA(KI)
THETA T(KI) = 2. * THE TAE(I,KI)
0)0 770 J=1.NAREA
770 STRESS(J) = STRESE(KI,J)
780 CONTINUE
TIMBER = TIME-TIMEI
FIRSTM=0.
    TIMBER III
FIRS [M=0.
790 F2=0.
800 COMFINUE
XM1=0.0
FBAL=0.
810 FUTFUR=0.
                                                                                                                                                                                                      LPSC 4450
               00 1340 J=1,44REA
ASTRAT(J) = THEFAT(K1)*(AYNAC - Y(J))/DX
IE(EBAL.EQ.O.)GO (D 820
                                                                                                                                                                                                     IPSC4520
TPSC4530
IPSC4540
TPSC4550
       8011
     BSO CONFINDE
00000
                                                                                                                                                                                                     TPSC4590
TPSC4600
                ITTERATION FOR STRESS
                                                                                                                                                                                                     IPSC 4610
IPSC 4620
                SIGN=0.
               L=1

STRES(!)=STRESS(J)

IF(IINTP.E0.IEQNTP)GU T() 850

IF(IEONTP.E0.0)GU f() 340

X3=((9./5.)*T(K1,J)-459.67)/1000.
                                                                                                                                                                                                    FPSC 4650

TPSC 4660

TPSC 4670

TPSC 4680
             ·60 fo 860
                                                                                                                                                                                                    IPSC 4690
IPSC 4700
     840 X3=((5.79.)*(T(K1,J)+459.67)/1000.)
GO TO 860.
                                                                                                                                                                                                     IPSC4/LO
```

	850	X3=[(K[,.1)/[())(), CONTINUE		•	IPSC4/20
		X5=1./X3 X8=AL()G(X3)			12504730 12504740
		X11=X5*X5	-		14804750 14804750
		X12=X5*X11 X31=X3*X3	-	*	1PSC4770
		X32=X3*X31 X33=X8*X8	-	•	12804780 12804790
		X34=X8*X33		•	12804300 12804810
С	870	TE(HARDAP.EQ.2.)GU TU 1000	,		TPSC 4820
č		TIME HADDENING THEORY OF THE		• •	IPSC 48 30 IPSC 48 40
00000		TIME HARDENING THEORY OF CREEP ACCUMULATION		•	TPSC 4850 LPSC 4860
С		TECL NELLYCH FOLGOO		•	12.5C.48.70
		IF([.NE.1]GD FD 900 X4= IME		•	[PSC 4880 [PSC 4890
		X4X=[IME] X6=ALDG(X4)		•	IPSC 4900 IPSC 4910
		1F([[M=1.=0.0.]GO fO 880 X6X=ALOG(X4X)			IPSC 4920
	0.00	-GO (I) 890			12 SC 49 30 12 SC 49 40
	890	X6X=0. CONFINUE		•	1P SC 4950
		X27=X4*X4 X27X=X4X*X4X	_	•	12 SC 4950 12 SC 4970
		X28=X4*X27		•	12 SC 4930 T2 SC 4990
		X2HX=X4X*X27X X2Y=X6*X6	_	•	TPSC5000
		X29X=X6X*X6X X30=X6*X29	-	_	TPSC5010 LPSC5020
		X30X=X6X*X29X	-		TPSC5030 IPSC5040
		X 36=X 3*X6 X 36X=X 3*X6X	_	•	TRSCSOSO
		X38=X4#X8 X38X=X4X#X8	_	•	[PSC5060 [PSC5070
		X40=X6*X8		•	- TPSC5080 TPSC5090
		X40X=X6X*X8 X42=X5*X6	-	•	TPSC5100
		X42X=X5\XXX X45=X3*X4			IPSC5110 IPSC5120
		X45X=X3*X4X	-	·	12 S C S T 30 12 S C S T 40
	900	CONTINUE IE(S(RES(L).G(.0.)G) (U 910	_	•	IPSC5150
		1F(S)RES(1),FQ,0,1G0,T0,970	-	•	[PSC5160 [PSC5170
		STRES(L)=ABS(STRES(L)) SIGN=1.0		4	12865140 12865140
	910	ČŮŇĒŢŇŮĚ ĬF(1ĘŮNST•EЕO•)ĠŨ TU 920		•	TPSC5200
		X2=S(RES(L)/1000.			TP \$05210 [P \$05220
	920	GO TO 930 X2=5[RES(L)*6.8948/1000.			IPSC5230
	930	CONTINUE		•	TPSC5250 TPSC5260
		ĬĔ(X2.GŤ.1.)GO TU 940		•	JPSC5270
		IE(INDSFR.EQ.O)GO FO 940 X2=1.	-	•	[PSC5280 [PSC5290
		LINEAR=1	-		TH SC 5 300

940	CHALLMH																										IPS	(,53	110
	- X7= A1 ()G - X9= X2≠ X	(X2)																				•				162	(C5 3	320
	X10=X9*																											(053 (053	
	X13=X2# X14=X2/																										IPS	(53	350
	$\hat{x}_1 = \hat{x}_1 $		3																. .				•					C5 2	
	-X16=X15	\$X1	3																				٠				163	(15 d (15 d	380
	X17=X14 X18=X14	≈x [· ≈x1	7																								IPS	053	90
	X19=X7*	х7	•																									C5 4	
	X2()=X7* X21=X2*																		_								 148	iĆ5 4	20
	X22=X3* X23=X7*	λ̈́7																										C54	
	X23=X7* X24=X2*	XH	v															•						-			148	C54	50
	X24x=X2	^ ⊃~. * X 3:	^ 7 *X4	Х									*.*	•		•							•				16.0	C5 4	(60
	X25=X24	*X24	4																_				•				TPS	C5 4	() B
	X25X=X26 X26=X24	サ へ ~ . ※ X フ ′	344 5	X.																							145	C54	90
	X26X=X24	4 X *)	χ̃25	X														•	-							•	125	Co5 Co5	10
	X35=X2#. X35X=X2	* X 6)	x																_		•		•				TPS	655	20
	X37=X4#	x 7																					•				155	C55	<i>3</i> 0 40
	X 3 7 X = X 4 1 X 3 9 = X 6 # 1		7																•								148	こうう	50
	X39X=X6	X¥X	7																-								162	(55 (55	5()
	X41=X5*. X43=X42:																						•				THS	C55	80
	X43X=X4	~ ^ / 2 X *)	x 7																				-				155	Č55 C56	90
	X44=X2*		J																-								125	じりろ	10
	X44X=X2: TERM3=7:	**X 42 [2 15	ス ジメク	+ /	17	1 2 X		11	u 1:	z v v		7 ()		l iz v	LA		11:	21.6	77.1	c	,,,		باد				THS	C56	20
]	TERM 3= Z(1+Z(15)*)	Χį́́́́́́	+ Ž (16) * ;	Χįε	+ 7	Ţì	Ź):	×Х	ί7	ŧΖ	Ϊŧ	,) ŝ	Χĭ	8+	Żζ	191	×X	19.	+27	20	ĵ ŝ	XŽ:	0		THS	055 056	3() 4()
ζ.	TELTIME	1 . E	520	33	ιñ	^ fí	įŤά	56	21'	۴٨.	23	+ 4 (4 !	.) *	X 4	Ţ											ĪPŠ	Č56 C56	50
_		([]	řŽŰ	3)	*X	3+7	(4)*	(4)	(+,	7 (1	5):	× < 5	5+2	15) *	X5)	(+ <i>Ž</i>	_ ();) #)	(B+	11	1.1	1 *	x 1 1	l	盟を	056 056	60 70
1	(ナノ(コフ)※) (ナノ(コフ)※)	X 1 2 4	+ Z (27) 本) 1 2 2 3	X 2 7	X+	75	28) * .	X 2	8 X +	- <u>Z</u> (29)*	X 2	9 X +	+ Z (30) *)	(3 0	įΣ,					TPS	じりり	80
2	3+2(40)*	λ4'n)	Χ÷Ζ	(4,	27	へ) へ * X 4	2 x	+ Z	31° (4!	5):	≎χ.	7 6 1 4 5)	() `	+ J ~	4.3	++	۷ (:	37)	* 1	30.	(+2	(3	(d)	¥ X .	313 X		162	Č55 C57	90
1	3+2(40)*; FUNC1=16 I+2(37)*;	- 34	3+5	ĖK	131	+ 4 (24) *	124	ţX:	+ 1	2) #	4 2	<u> خ</u> ز	+2	(20	ر ز ا	X2	6 X +	-2(35) *	X 3	5 X		145	657	10
,	(+2(37)*) FUNCT=6)	· , , , ,	·	1 /	, ,	· ^	, , n	+ /_	14	3)	¥Χ	4 3)	(+2	. (4	4)	¥χ	44)	(-				•	-			162	Č57 C57	20
OFA	GO TO 98	50		•		•												•					•					657	
	CHALLMOR FUNCTED																										155	651	50
960	CHAIL LADE	-				_																					1125	657 657	70
1	TERM1=2((1)+ (124	12(3); 27	÷X∶ t±x	3+Z	(4) #. () :	X 4 +	- Z (5.5) * }	(5+	21	6)	¥Χ	6+4	(()) *	X8+	۲ <u>۲</u> (11) *	X 1	1		IPS	C57	80
· <u>ż</u>	+2(12)*) +2(32)*)	₹32+	Žĺ	33	(*)	k 33	+Ž	(3	4)	×χ	34	۲Žί	36	,) *	χŝ	7 T	Ž	38)	*X	301 384	71	2 L	.) *	X 4 (L }		162	C57	90 -
,	せんしせんりかん	\ <i>+ /</i> 7	T / 1	+)		\ '+ ')																			•		1125	じりむ	10
	FUNC = 168 +Z(37)*>	() / +	-/(34	1 74 8	(44	#/	"^,	241 31%	. X 4	. 3)] ¾ - / (44) +) *	4.1 4.4	26 4) *X	26	1+7	(35) *	Х3	5				15 6	Č58 C58	20
	トリハじニヒメト	?(Fl	JNC.	1/1	100) _				•		- 1	• •	•	• •	•			_								142	C58.	40
970	IF(FUNC. EPSCRP=	ه ادر. م(, = U	(د' N	1 16) ()	Ю	91	5()																		1251	0531	50
	60 fn 99)() ·																										(58) (58)	
980	EPSCRP=F IF(LINEA	-UNC	, = FI () 4	UN(. 1	ro		นก														•	•				11251	เรย	80
	# 1 % W # 1 % # M		. v y . 1	,,,		, ()	7	717																			142	วิริชิง	y ()

	EPSCRP=EPSCRP*(STRES())/1000.)			12565900 12565910
1000	CONTINUE TE(HAROOP.EQ.L)GU TO 1150 TE(T.ED.6.AND.KK.EQ.50)GU TO 1010			12505920 12505930
1010	GH 10 1020 WRIJE(6,1860)J.L.SIKES(L)		•	12505940 12505950
1020	CONCINUE			12505950 12505970 12505930
00000	STRAIN HARDENING THEORY OF CREEP ACCUMU	, A 110N _		18505990
C		••	•	125C6000 125C6010
_	1E(STRES(L).Gf.0.)GO TO 1030 STRES(L)=ABS(STRES(L))		•	IPŠČ6020 TPŠČ6030
	SIGN=1.0	-		12506040 12506050
1030	COMITINUE 16(SFR-S(L).Gi.10.)GU IH 1040	•		125C6060
	DSTR2=0.	*.		12566670 12566630
1060	GII (1) (150)		•	18.809040
1040	CONTINUÉ [EFF1=0.	•	•	12506100 12506110
	1EFF2=().	<u>.</u> .		16209150
	ACONST=O. BCONST=O.	-	•	FPSC6130 PPSC6140
	$CCOMSCI_{=0}$		•	IPSC6150
	1F(TEO481*60*0*)60 TO 1080	••		12506160 12506170
	X2=\$TRES(L)/1000. GO TO 1060			TPSC6180
1050	X2=\$TRE\$(L)*6.8948/1000. CUNTINUE		•	TPSC6190
1050	CONTINUE X7=ALUG(X2)		•	IPSC6210
	X9=X2*X2		,	12506220 12506230
	X10=X9*X2 X13=X2*X3	•		TP \$062.40
	X14=X2/X3	<u>.</u>	•	12506250 12506250
	X15=X13÷X13 X16=X15÷X13		•	TP\$66270
	X17=X14×X14	•		FPSC6290 TPSC6290
	X18=X14+X17 X19=X7+X7	••		JP 506 300
	X20=X7*X19	-	•	TP \$06 310 12 \$06 320
	X / 1 = X / 2 × X · 3 X / 2 = X / 3 × X /		•	18566 330
	X23=X7*X8	-		12506340 12506350
	X41=X5*X7 TERM5=7(1)+7(2)*X2+7(3)*X3+7(5)*X5+7(7)			1PSC6360
		/ ¥ X / †		12 SC6 370 12 SC6 330
	17(5+/(\\/)*X\/+/\\ 2+7/23)*X23+7/3	01*X10+ 11*X31+	TP SC6 390
	ス 11 30 1± 43 2± 11 44 1¤X 4 4+ 11 44 1¤X 44+1 U 41 1↑X +	l		12506400 12506410
	TF(CSTRAN(5);GTOOOT)GU TO 1070 X4=(TIME-TIMEL)			[PSC6420
	X4=(11Me=11Me() X6=ΛLOG(X4)		•	[2506430 [2506440
	X24=X2*X3*X4 X36=X36*X36		•	IPSC6 450
	X25=X24*X24 X26=X24*X25	-	,	12 S C 6 450
	X27=X4*X4	-		12 SC6 470 12 SC6 480
	X28=X4 *X27			

. X29=X6÷X6 X30=X6÷X29		•	12506490
X35=X2*X6		•	[PSC6500
X36=X3+46			TP SC6520
X 3 7 = X4 * X 7		••	1PSC6530
X 38 = X 4 # X 8		•	1PSC6540
X39=X64X7 X40=X64X8		4	[PSC6250
X42=X5*X6		•••	TPSC6560 TPSC6570
X43=X42×X7		•	TP SC6580
X44=X2*X4		•	FPSC6590
7 X45=X3*X4		المحاد والمعاد	TP SC6600
TERM6=7(4)*X4+Z(6)*X6+Z(2 1Z(28)*X28+Z(29)*X29+Z(30) 2Z(38)*X33+Z(39)*X39+Z(40)	(4)	(6)*X26+/(//)*X2/+	1PSC6610 1PSC6620 1PSC6630
27(38)*X38+7(39)*X39+7(40))*X40+Z(42)*X42+Z(43)	*X43+/1441*X44+	TP \$0.00 ZU
32(43)%A43			TP SC66 40
DŠTR2=TERM5+TERM6 DSTR2=EXP(DSTR2)/100•		•	14806650
50 f0 [150		•	TPSC6660
1070 CONTINUE			. 12506680
(EFF1=(MAX			IPSC6690
X4= TEFET	•	•	IPSC6590 IPSC6700
X6=^L()G(X4) X24=X2*X3*X4			12506710 12506720
X25=X24#X24	•	* **	16200150
X26=X24*X25		•	12506730 12506740
X27=X4≈X4		-	TPSC6750
X28=X4*X27		· .	IP\$66.460
X29=X6*X6 X30=X6*X29		•	12506770 12506780
X35=X2*X6		-	[P\$06790
X 36 = X 3 * X 6	•	****	TP\$06800
X37=X4%X7	,		PSC6d10
X38=X4*X8 X39=X6*X7		*	1286930 1286930
X40=X6*X8		•	TP SC68 40
X42=X5*X6		•	TPSC6850
X43=X42*X7		_	. IP\$C6860
X44=X2=X4		•	16869340
X45=X3*X4 _[FRM6=7(4)*X4+2(6)*X6+2(2	ひんきゅくひんエフ しつらきゅく シらエフ しつ	61443641137144371	7P\$Č6880 1P\$C6390
17(28)*X28+Z(29)*X29+Z(30)	1*X30+Z(35)*X35+Z(36)	*X 36+7 (37) *X 37+	TP \$06940
17(28)*X28+Z(29)*X29+Ž(30) 2Z(38)*X38+Z(39)*X39+Z(40))*X40+Z(42)*X42+Z(43)	*X43+2(44) *X44+	IPSC6910
32(45)*X45		*	JP SC 9 20
ĨĔŶŚĨ≐ ĨĖŔM5+ĬĖRM6 ĔŶŚĨ=FXP(ĘŶŚĨ)/100•		•	1PSC6930
IF(EPSt. GF. CSTRAN(J))30 ([O 1090		IPSC6940 IPSC6950
TEFF2=TEFF1+1./60.	10,0	_	18.80.6960
X4=TEFF2			TPSC6910
X6=ΔLOG(X4) X24=X2*X3*X4		<u> </u>	TP \$ C 6980
X25=X24*X24		÷	[PSC6990 [PSC7000
X26=X24#X25	•	-	
X27=X4*X4			TP5C7020
X28=X4 *X27			12 SC 70 30
X29=X6*X6 X30=X6*X29		-	12507040 12507050
X35=X2*X6		•	JPSC7060
X36=X3*X6		-	TPSC7070

X31=X4			TPSC/O
X38=X4*X8 X39=X6*X7	•	•	TPŠČ70 TPŠČ71
X40=X6*X8	-	•	- IPSČ71
X42=X5*X5 X43=X42*X7		•	TPSC/I
X44=X2*X4 X45=X3*X4	***		TPŠČŽÍ TPŠČŽÍ
JERM6=2(4)*X4+2(6)*X6+2(24)*X24+2(2	i)*X25+4(26)*X23+4	(21)*X27+	- 12 SC 7 I
TERM6=Z(4)*X4+Z(6)*X6+Z(24)*X24+Z(2 1Z(28)*X28+Z(29)*X29+Z(30)*X30+Z(35) 2Z(38)*X38+Z(39)*X39+Z(40)*X40+Z(42)*	*X35+Z(36)*X36+Z(3 *X42+Z(43)*X43+Z(4	7)*X37+ 4)*X44+	123071 123071
	the stage of the stage of		TPSC/1
EPS2=EXP(EPS2)/100. IF(EPS2.LE.EPS1)GO TO 1080 DSTR2=(EPS2-EPS1)*(TIME-TIME1)*60.		•	- 1PSC72
USTR2=(EPS2-EPS1)*(TIME-TIME1)*60.		•	TPSC72
BCONST = 2. GO TO 1150		•	TPSC/2
080 DS[R2=0]	-		IPSC/2
BCONST=3. GO [U 1150	and the second second		- JPSC/2
090 TEFF2=TMAX*(CSTRAN(J)/EPS1) 100 CONFINDE		•	125072 125072
X4=TEFF2		•	- FPSC73 - IPSC73
X6=AL(IG(X4) X24=X2*X3*X4		•	TPSC73 TPSC73
X25=X24*X24 X26=X24*X25		•	TPSC73
X27=X4*X4	The state of the s		TPSC73 TPSC73
X28=X4*X27 X29=X6*X6	-	•	TPSC13
X30=X6*X29 X35=X2*X6	· · · · · · · · · · · · · · · · · · ·	•	TPSC13
X36=X3*X6 :		•	IPSC74 IPSC74
X37=X4*X7 X38=X4*X8	-	•	125074
X39=X6*X7 X40=X6*X8	• =		TPŠČ74 IPSC74
X42=X5*X6	****	•	TPSC74 IPSC74
X43=X42*X7 X44=X2*X4		•	TPSC74
X45=X3*X4	_	•	TPSC74
[ERM6=Z(4)*X4+Z(6)*X6+Z(24)*X24+Z(25) 1Z(2H)*X2H+Z(29)*X29+Z(30)*X30+Z(35)* 2Z(3H)*X3H+Z(29)*X29+Z(30)*Z(3+Z(3+Z)*	5)*	(27)*X27+	12 SC 7 40
2Z(3H)*X3H+Z(39)*X39+Z(40)*X40+Z(42)* 3Z(45)*X45	142+2(43) * 243+2(44	+1*X44+	IPSC75
EPS2= 1E345+15RM6		•	TPSC75 TPSC75
EPS2=FXP(EPS2)/100. IE(EPS2:\E.EPS1)6U (U)110	· •		TPSC75
	-	•	TRSC150 TRSC15
GO TO 1100 110 IE(FPS2-GI-CSTRAN(J)-AND-EPS1-GT-CS1	TRANGOLISM TO 1120		1 V C C 7 5 7
[SiOPE=(14661-16662)/(6651-6652) TEFF1=TEFF2		•	TPSC75
EPS1=EPS2 TEFF2=[SLOPE*(CSTRAN(J)-EPS2)+TEFF2	-	•	TPSC76
TEFF2=[SLOPE*(CSTRAN(J)-EPS2)+TEFF2 GO TO 1130	-	•	1PSC76.
120 TEFF1=TEFF2		•	TPSC76
EPS1=EPS2			TPSC766

	The same of the sa					1.3000 10 10
	ゴトドトフ=デドドドクキ(りらご	KAN(コナノドセンシ)		_		IPSC (5/0
1130	CHN IINUE					[PSC/680
-	X4=广ビビデス					IPSC/690
	X6=ALDG(X4)			•	•	TPSC7700
	X24=X2*X3*X4			•		IPSC//To
	X / Y = X / Y \ 3 Y A Y					TPSC/720
	X25=X24*X24					
	X26=X24*X25		·			1880//30
	X27=X4~X4		•	`	-	18SC 1740
	X ? H = X 4 * X 2 7					1PSC//50
	X29=X6*X6				•	1PSC//60
	X30=X6*X29			-		IPSC 1110
				,	•	TPSC/770
	X35=X2*X6	1 ¥ 1 4 4		_		15 30 7 700
	X36=X3*X6					IPSC7790 IPSC7800
	X 37 = X 4 * X 7			_	_	inaciano
	X 38= X4 *XB					[PSC/810
	X39=X6*X7			,	-	TPSC7820
	X4()=X6*X3	•		-		TPSC 7830
	X42=X5*X6			•	•	1PSC7840
	X43=X42*X7			•••	•	ŤPŠČŽŠSÖ
					•	10007940
	X44=X2*X4			-		1PSC7860
	X45=X3*X4					ib20 (9 (0
	- 1ERM6=2(4)#X4+2(61*X6+Z(24)*X24+Z(25)*X25+Z(20	٤) *X26+Z(2	7)*X27+	162C1910 162C198U
	7 (28) * X 2 H + 7 (29) *	X29+Z(30)*X30+Z(35	i)*x35+2(36)*	×x36+2(3/)	¥ X31+	1PSC7390
	27 (38) *X 38+7 (39) *	X39+Z(40)*X40+Z(42))*X42+Z(43);	¢X43+7(44)	¥X44+	1PSC/900
	37(45)***45	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,				1PSC7910
	ÉPSZ=TERMS+TERM6			•	•	1PSC7920
	EPS2=EXP(EPS2)/1	00		• •		16867936
	- UP 0 4 = U 4 F U U F 3 6 7 / 1	ひとりょう しょうしゅ のずい みんしょうご	LIT ANDILO	3 70 1160		TPSC7940
	1E(VH2) (E625-02)	RAN(J)]/CSTRAN(J);	1.6.10001160	U 1140		16201940
	60.00 1110	==				1626 (330
1140	- [EFE2=]EFF2+TIME	- IIME1				1420,4420 1420,4420
	X4=[FFF2					TPSC/9/0
	X6=AL(16(X4)				•	TPSC/980
	X24=X2*X3*X4			-		[PSC7990
	X25=X24*X24				•	12508000
	X26=X24*X25			_		TPSCB010
	X27=X4*X4		•		•	TPŠČBOŽO
		-		-		TPSCBO30
	X28=X4*X27				•	16.5000.00
	X29=X6*X6			-		[PSC8040
	X30=X6*X29					TH 208020
	X35=X2*X6			-		TP ŠČBO60
	X36=X3*X6					TPSC8070
	X37=X4*X7			'	•	TPSC8080
	X38=X4*X8			_		TPSCR090
	X39=X6*X7				•	IPSC8100
						PŠČBILO
	X40=X6±X8					
	X42=X5*X6_			-		[PSC8130
	X43=X42*X7					LESCR130
	X44=X2*X4			* ·		TP SC8 1 40
	X45=X3*X4					15209120
	- 1 ERM6 = Z (4) * X 4 + Z (6)*X6+Z(24)*X24+Z([25]*X25+Z(2	6)*X26+Z(2	7)*X27+	JP SC8 160
	17(28)*X28+7(29)*	6)*X6+Z(24)*X24+Z(X29+Z(30)*X30+Z(3	5)*X35+Z(36):	× x 36+1(37)	∡ x37+	IPSC8170
	27/ 3H 1 x X 3H + 7/ 30 1#	X39+Z1401+X40+Z142	2)*X42+7(44):	*X43+71441	*X44+	19 SC 8 1 8 O
	37(45)*X45	7.37.21 (0) (ATO 21 T	22 7 7 7 2 7 2 7 1 3 7			IPSCB 190
		4		4	• .	TP SCR 200
	C3= 1 ERM5+ TERM	· ·		-	•	TPSC8200 [PSC8210
	C3=EXP(C3)/100.	* · ·			•	10000210
	OSTK2=C3-EPS2					[PSC8220
1150	CONTINUE					LE 208230
	EPSCRP=DSTR2					1PSC8240
1160	CONTINUE					TPSC8250
					and the second second	

	TELETO L. CO. O. N. S.			
	IE(SIGN. 60.0.)60 fo 1170			12208320
	STRES(L)=-STRES(L) SIGM=0.		•	TPSC8270
	EPSCRP=-EPSCRP		_	<u>L</u> PSC8280
1170	CHALLANE	• -	•	TP SC8 290
	\$S[ART=\$TRES(1)		,	18508390
	ĬŎĬĊŔŔŧĔŔŶĊŔŔĸĬſŚſĸŧŚſţ)+ĸŧŚŚſĸſIJŊŊŧſĸŧĸIJ			[PS683[6
C 40			•	16264350
Ç so	15	140		[PSC8 330 [PSC8 340
C	7 P L A C P L A T L L A L A L C A L		•	IP SC8 350
	IF(AS(RAT(J), EQ. [UTCR-160 TO 1320	•-	•	100004460
	CRATIO=TOTCRP/ASTRAT(J)			TP SC8 376
	IF(ABS(CRAFID-1.000)). F			FP SC8 380
	L=2	•	•	IPSC8 390
	Ĭ SŤĸ 1 = ſ ii TC v D		-	TPSCR400
	IF(STRES(1).NE.O.)GU TO 1200 IF(ASTRAT(J).GT.FUTCRP)GO TO 1190 STRES(2)-STRES(1)-100	· -		12508410 12508420
	IECASTRATCJ).GT.TOTCRP)GÖ TÖ 1190			16.578.420
1180	STRES(2)=\$TRE\$(1)-100.			12 S (8 4 30 12 S (8 4 40
1 1 . 1 / 1	60 10 870		•	IPSC8 450
1150	STRES(2)=STRES(1)+100. GD TO 870			P 508460
1200	TELACTUATELA ME O ACO CO 1210	-	•	1P SC8 470
1200	IF(ASTRAT(J).NE.O.)GO TO 1210 IF(JOJCRP.LT.O.)GO TO 1190			IPSC8480
	60 (0 [[80]	-	•	12 SC8 490
1210	TELSTRESLILL TO AND TOTODO CT O AND ACTO.	T/ 11 1	r rareana	1PSC8500 1PSC8510
				IPSC8510
	IF(SIMES(1) GT O . AND . FUTCRP I T.O AND . ASTUA	TLD G	E. TOTEPOL	12508520 12508530
			TATOTURE J.	[PSC8540
1000	GO TO 1230		•	JPSC8550
1550	ŠÍRĖŠ(Ž)̃≡ŠIRĖS(1)*2. GO TO 870			12 SC8560
1230	CONTINUE	-	•	TP \$08576
r	TELASSICRATION OF THEO TO 1250			
	IF(ABS(CRATIO),GT1)G() F() 1250 IF(AS(RAT(J),LF.0.)G() F() 1240 STRES(2)=STRES(1)+ABS(STRES(1)) G() F() 1260	_		IPSCHSUN
	STRES(2)=STRES(1)+ABS(STRES(1))			IPSC8600
		-		TPSC8610 LPSC8620
1240	ŠŤŘĚŠ(Ž)=ŠTŘES(1)-ABS(STŘES(1)) 60 [0][260		•	TP 808630
1250	CONTENUE			1PSC8640
1 /)()	CONTINUE STRESCON-STRESCONCER		•	IPSC8650
1260	STRES(2)=SFRES(1)/CRAFID CONTINUE		_	IPSC8550
• •	GO TO STO	_		IPSC8670
1270	[=!+]		. '	[PSC8580
	IF(L.ME.20)GU FO 1280			TP\$08690
	WKI 1F(6.18/011.1.KK.K1			12808700 12808710
1.200	60 (0.1320)			DCC8750
[580	CONTINUE		•	TP SKR 736
	(STR2=FOTCRP			TP \$ 08 7 30 LP \$ 08 7 40
	IF(ASTRAT(J).E0.0.)GO TO 1310 GRAFID=FORTAP/ASTRAT(J)	-	•	JP SC8 750
	1F(ABS(CRATIU-1.000).LT001)GO TO 1290			IPSC8760
	60 fo 1300			IPSTRIIA
1290	L=L-1			ŢŖŠČŖŢŖŎ
	GO TO 1320			TPSC8790
1300	CONTINUE		•	THE CARRIO
	\$\[\P\E=(\S\RES(L-1)+\S\RES(L-2))/(\GS\R2-\FS\R1)\\ \\$\TRES(L)=\S\TRES(L-1)+(\AS\TRA\T(J)+\FS\TR2)*S\UPE\\ \FS\R1=\FS\TR2\\ \]	-		TPSC8810 TPSC8820
	\$ TRES(1) = STRES(L-1)+(AS TRAT(J)-15 TR2) +SIMPE		•	IPSC8830
	1 S IK1=1 S TR2			F SC83 4()
				11 36007 70

```
GIT (1 87)

$LOPE=($ TRES(L-1)-$ TRES(L+2))/( T$ TR2- T$ TR1)

$LRES(L)=$ [RES(L-1)-1 $ TR2*$ LUPE

IF(ABS($ TRES(L)/$ TRES(L-1)-1.00)... T...001)GO TO 1320

IF(ABS($ CRES(L)/$ TRES(L-2)-1.00)... T...001)GO TO 1320

T$ TR1=($ TR2

GO [U 37)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      TP$08860
1320 CONTINUE

STRESS(J)=STRESS(J)*A(J)

1340 TOTEUR = TOTEUR + FORZ(J)

C 8010
                                              IE(EBAL.NE.O.)GO (U 1360
IE(I)TEOR.LI.O.O.AND.E2.GT.O.O) GO TO 1350
IE(I)TEOR.GT.O.O.AND.E2.LI.O.O) GO (U 1350
IE(ABS(I)TEOR).LI..OO1) GU (U 1380
                                             TECHNOLOGY AND TO TO THE TO TH
         1370 CONTINUE
[OTFOR = 0.0

1380 DO 1390 J=1,NAREA
FORC(J) = STRESS(J)*A(J)
TUTFOR = TUTFOR + FORC(J)
XM1 = XM1 + ARS(FORC(J)*(AYNAC - Y(J)))
     CCC
                        3013
           1390 CONCINUE
TOL1 = ABS(XM1 - XMOM(K1))/XMOM(K1)
                        8006
        IP SC9 400
     C
```

Ç	400	90 f			TPSC9440 TPSC9450
C.		[H411=]H412	-		IPSC9450
		X:4[()=X:4]	-	•	TP SC9 470
		- 60 ftt 790			12SC9430
14	10) COMPLETED ATTAXA CONTRACTOR ATTAXA			12509490 12509500
		SAVIHE=IHEIAI(()-IHEIAE(1,<) SAVIMP=T(K],)		•	TPSC9510
		ĬĒ(ĪNDUNO,ĒŪ,Į) GD [H 1420	 -	•	1PŠČ9520
		SAVPRS=PRESS(K1)		•	IPSC9530
1.	20	G() (() 1430)			PSC9540
14	30) SAVLOD≐PLOAD(K1)) CONTINUE	Ē		TPSC9550 TPSC9560
1 "7	,,,	DO 1440 J=1.NAREA		•	TPSC9570
		00 1440 J=1,NAREA RESS[R(J)=SIRESE(K1,J)-SIRESS(J)		•	1PSC9580
14	4()) CONTIMUE HETAC = HETAC + THETAT(< 1) - THETAE(1 , < 1) DO		•	TP\$09590
				•	TPSC9610 TPSC9610
14	50) CSFRAN(J)=THETAC*(AYNAC-Y(J))/DX	- :	• .	TPSC9620
•	ì	1-KESSTR(J)/E(K1,J)			TPSC9630
		IF(INCYC, EO. 0) GO (O 1460) IF(KK.NE.1)GO TO 1460 IF(KK.NE.1)GO TO 1460 IF(KI.NE.NTIME) GO TO 1530 DO 1470 N=1.NOMCYC NOMC1 = N IF(KK.ED.KCYC,E(N)) GO (O 1480) CONTINUE GO (O 1500) DO 1490 J=1.NAREA PSIRAN(I.J.NAREA		•	1PSC9540
		IF(KK.NE.1760 (U 1460)		•	IPSC9650 IPSC9660
14	60) [F(K1_NE_NTIME) GO TO 1530		•	TP 509670
•		DO 1470 N=1. NUMCYC			「PSC9ヵ80
		MIMC1 = N	-	•	TP SC9690
1.6	70	NUMC1 = N 1F(KK.=D.KCYCLE(N)) GU (U 1480)) CONTINUE GO (O 1500)) DD 1490 J=1,NAREA PSTRAN(I,J,NUMC1)=CSTRAN(J)*100. RESP(I,J,NUMC1)=RESSTR(J)) CONTINUE) CONTINUE DO 1510 N=1,NUMCYC NUMC2 = N) IF(KK.=D.*KCYCLE(N)) GU (O 1520) GO (O 10 1530)			18869700 18869710
14	(1)) CONTINUE GO TO 1500	-	•	[PSC9/10 [PSC9/20
14	80) DO 1490 J=1,NAREA		•	TPSC9736
-		PSTRAN(I.J.NUMCI)=CSTRAN(J)*100.			1PSC9740
		RESP(I,J,NUMC1)=RESSTR(J)	-	*	TPSC9750
16	90) CONTINUE CONTINUE		•	[PSC9750 [PSC9770
	()()	00 1510 N=1.AUMCYC			15863190
		NUMC2 = N		•	TPSC9790
15	10)	-	_	[bgcagoo
	20	CH 1530	-	,	TPSC9810 PSC9320
15	30	1 CONTINUE		•	IPSC9830
15	40) CONTINUE			12SC9340
15	50) CONTINUE		•	TPSC9850
		IF(INDELA.EQ.1) GO (O 1610		•	12509860
		00 1600 11=1,NUMCYC NMIN2=NSIAT-2			12264440 12264440
		00 1580 L2=1, NMIN2		•	TP 509890
		SUM 1 = 0.0	-		TPSC9900
		SUM 2 = 0 • 0		•	1P5C9910
		SUM3=0. IPRIL2=IPKINT(L2)		•	ÎP 80 99 20
		100 1560 MI=1.124112	-		TP SC9930 TP SC9940
		THETAX=(THETAP(N1,11)+THETAP(N1+1,11))*X(N1)	1/2.0	•	TPSC9950
		SUM1=SUM1+THETAX			125C9960
15	60) CONTINUE		,	IPSC9970
		IPRI 21 = IPRI 12+2		•	[P\$C9980
1.5	70	DO 1570 N2=1PR121,NSFAT > SUM2=SUM2+FHETAP(N2,LL)	-		TPSC9990 [PSC 10
' '	, , ,	DFFL(1,1,1,2) = SUM1 + SUM2 * X(1,2) + X(1,2) *	THE TAP (L2+	1.11/2.	ipsč žó
15	ㅂ()) CONTINUE	and the second of the King Star S		if SSAI

	MM 141 = 45 i 4 i - 1		IPSC 40
	DO 1590 NI=1.0MINI	•	1880 50 1880 60
	ដីអម្ដីកំγ័≘(ដីអម្ដីកំខ(សៀ), (t)) + (+ (t) (N1+1, (t))) ∻ ((N1)/2°•) SDA 3= SDM 3+ FHE fAY	•	148C 70
1590		3	1280 - 30 1280 - 30
	CONTINUE DEFL(!!, NSTA T-1)=SUM3+THE TAP(NSTAT, L1)*X(NSTAT-1)/2.0 DEFL(!!, NSTAT)=SUM3+F!=TAP(NSTAT, L1)*X(NSTAT)/2.0 CONTINUE		1986 96 1986 190 1986 110
1600	CONTINUE		IPSC 120
(1 / (1 /	DO 1660 L1=1,NFIME -	•	[PSC 130 PSC 140
	NMIN2=NS(A T-2 DD 1640 L2=1,NMIN2		TPSC 150
	\$11M4=(). \$11M5=().	•	IPSC INC
	SUM6=0.	•	TPSC 170 TPSC 180 TPSC 190
	IPRIL2=IPRINT(L2)		TPSC 200
	DIT 1620 NI=1, 134112 ETHETA = (THE TAE(NI, L1) + THE TAE(N1+1, L1))*X(N1)/2.0 SUM4=SUM4+EIH=1A	•	TPSC 210 LPSC 220
1620	William Witter	.*	IPSC 230
	[PRL21=IPRL2+2 DO 1630 N2=IPRL21.NSTAT	•	IPSC 240 IPSC 250
1630	SUMS = SUMS FIRE TAE (N2, L1)	41. □ 11/2	1480 260 1480 270
1640	CIM I NOTE		TPSC 280
	NMINITAL ALAL		18ŠČ 290 18ŠČ 300
	THE TAY= (THE TAE (N1+L1)+THE TAE (N1+1+L1))*X(N1)/2. SUMGESUMG+UMETAY	•	105C 310
1650	C1181 T J NO J E	•	148C 320
	NEFLE(:1, NSIA)-1)=SUMO+i:=IAE(NSIAI,LL)*X(NSIAI-1)/2. DEFLE(L1,NSIAI)=SUMO+ THE IAE(NSTAI,L1)*X(NSIAI)/2.		1856 340
1660	CONTINUE	•	TPSC 360
	IF(MCYC.E0.0)GO		TPŠČ 380
	MMIND=NSTAT-2	, •	FPSC 390 TPSC 400
	DO 1890 12=1,441N2 SUM7=0.0	•	IPSC 410
	\$U48=0.0 \$U49=0.0	•	1250 420 1250 430
	1 PRI 1 2 = I PRI 1 (1 2) 00 1 0 70 NI = 1 , I PRI 1 2		[PSC 440
	D() 1670 N1=1,1PRIU2 HETAX=(HET(N1,U1)+1HET(N1+1,U1))*X(N1)/2.0		[PSC 450 [PSC 450
1 / 7	SUM 7 = SUM 7 + FHE FAX	•	TPSC 470 TPSC 480
1010	CONTINUE IPRL21=IPRIL2+2	•	TP SC 490
1400	1)(1) 1680 N2=[PRL21,NS[AT		TPSC 500 TPSC 510
1000	IPRI2 =IPRIL2+2	1,111/2.	TPSC 510 1PSC 520 1PSC 530
1690	MMI41=42:41-1 CIMIINIE -		125C 540
	00.1700 61-1 66181	•	TPSC 550 TPSC 560
	THE TAY = (THE TAY) + THE T(NI+1, LI)) * X(NI)/2.0 SUM9 = SUM9 + THE TAY	•	IPSC 570
1700	COMPUNITE		128C 580
	DEFLIN(L1,NSTAI-1)=SUM9+FHET(NSTAT,L1)*X(NSTAI-1)/2.0 DEFLIN(L1,NSTAI)=SUM9+FHET(NSTAT,L1)*X(NSTAI)/2.0		1280 600 1280 610
1710 1720	CONTINUE CONTINUE		1286 20

```
IF(IDIMEN.EQ.[)60 f0 (730 DEPIH=0EPIH *2.540005 PICCH=PICH *2.540005 FLAT=FLAT *2.540005
                                                                                                                TPSC
TPSC
TPSC
                                                                                                                      6 40
                                                                                                                      050
                                                                                                                      660
                               *2.540-115
*2.540005
          FDGE=-0G-
                                                                                                                1250
1250
                                                                                                                      5/0
         TS=TS
TC=TC
TR=TR
680
                                                                                                               142C 980
142C 240
142C 120
                                                                                                               SUBROUTINE GEOM( INDGEU , DEPTH

LRIBELG , (S , (C , NCOR

2TZEE , NZEE , ZPNED1 , ZPNED2

3ZEESE , A , Y , DY
                                                            , TR
                                                                            , NRIB
                                                                                         , PI TÇH
                                                                                                               GEUM
                                                                              PHICUR , FLAT
ZEESF1 , ZEEFF
                              , ic , nchr , ebge
, zenedi , zenedz , zeeffi
, y , by , panalo
                                                                                                               GEUM
GEUM
                                                                                                                         36
       3ZEESF , A , 4 , 4 , 4 , 4 , 5 )
                                                                                                                         40
                                                                                                               GEUM
                                                                              7
                                                                                                               GEUM
                                                                                                                        50
                                                                                                                        60
C
C---- THIS SUBROUTINE DIVIDES THE TPS CROSS SECTION INTO DESCRETE
                                                                                                               GEOM
                                                                                                               GFUM
```

0000		ELEMENTS AND ASSIGNS $Y(\mathbf{J})$ CHARROLD EDUCATIONS EACH FLEMENT.	•	j 0	GEOM 100 GEOM 100
٠,		UIMENSION A(50) , Y(5)) COMMON PLANDM, PRIMIM, INDPIA DATA RAD757.29577957 NSECT2=NSECI-1 NSECT4=NSECI-4 NSECT5=NSECI-4 NSECT5=NSECI-3 GD TO (10 ,40 ,80 ,230), INDGEO CALCULATION OF RIB SECTION AREAS AND Y LOCAT		: : : : : :	GEUM 120 GEUM 130 GEUM 150 GEUM 160 GEUM 170 GEUM 170 GEUM 190 GEUM 200
č		CALCULATION OF RIB SECTION AREAS AND Y LOCAT	IONS; INDGE	U = 1	GEOW 550
Ŭ	20 20	DY= (DEPTH-TS)/(SEC-1.) A(1)=(DEPTH-TS)/(SEC-1.))*fR*NRI3 DO 20	- '		GEUM 230 GEUM 240 GEUM 250 GEUM 270 GEUM 270
Ç	30	DO 30	-		GEUM 290 GEUM 300 GEUM 310 GEUM 320 GEUM 330
c C		CALCULATION OF CORRUGATED SECTION AREAS AND	Y LUCATIONS	S; INDGEO =	GEUM 340 GEUM 350
	40 50	DY= (DEPTH-TS-2.*TC)/(SEC-3.) Y(1) = iC/2.0 DO 50			GEOM 360 GEOM 370 GEOM 380 GEOM 390 GEOM 400 GEOM 410
r	60 70	JE(S.GE.O.O) GO TO GO WRITE (6,240) RETURN A(1) = S*NCOR*TC DU 70 J=2,NSECT3 A(J)=(DY/CUS(PHICOR/RAD))*TC*NCOR*2.0 A(NSECT2)= (NCOR*ECAT + 2.0*EDGE)*TC A(NSECT)= PANWIO*TS RETURN CALCULATION OF Z SECTION AREAS AND Y LOCATION DY= (DEPTH - IS - 2.0*TZEE)/(SEC-5.) Y(1) = TZEE/2.0 DO 1=2,NSECT4 Y(I) = TZEE + (1 - 2)*DY + DY/2.0 JE(ZEEFI.CEE,ZEE) GU TO 120	/KAD]]]-F[]		GEUM 430 GEUM 430 GEUM 450 GEUM 460 GEUM 470 GEUM 480 GEUM 500 GEUM 510
CCC		CALCULATION OF Z SECTION AREAS AND Y LUCATION	NS; INDGEO) = 3	GEUM 520 GEUM 530
3	30 90	DY= (DEP(H - (S - 2.0)*(ZEE)/(SEC-5.) Y(1) = IZEE/2.0 DO 90	· · · · · · · · · · · · · · · · · · ·	•	GEUM 600
	100 110	THE (Y(1) + DY / 2 • 0) • GT • Z==== 1) GD	-		GEUM 610 GEUM 620 GEUM 630 GEUM 640 GEUM 650 GEUM 660 GEUM 670

170	Y(NSEC(5)) = 0.0	GE114 680
•	A(NSECTS) = 0.0	6EUM 690
120	TECZĘŁŚEL.CE.CZĘE) GO CO (SO	
1 7.7	DO 140 J=2. NSECT	GEOR 700
	107) 140 U-X4N3EU	6EUM (10
	DEPTHI = OFPTHI- IS - ZEESHI	660M (20
110	îf((ˈv(ປ) + ກິ່ນ/2.0).G1.ກິຣິບ ກິດໄ) GO TO 150	GE(114 / 30)
	CONCINUE	GE(101 740)
もつい	IHGT2 = J + 1	GEUM 750
	$H48 = Y(1) + 0Y/2 \cdot 0 - 0 + 2[H1]$	GEUM (50
	Y(NSECT3)= DEPTH1 + H48/2.0	GEOM 770
	A(NSECT3)= H48*NZEE*TZEE	GEUM 730
	60 10 170	GEUM 790
160	$ \begin{array}{ll} Y(NSEC[3]) = 0.0 \\ A(NSEC[3]) = 0.0 \end{array} $	GEUM 900
	A(NSECT3) = 0.0	GEOM 810
140	Y(NSECIZ) = 0.121H -[S -1454/2.0	GEUM 820
	Y(NSECT) = DEPTH - TS/2.0	GEUM 830
	A(1) = fZEE#ZEEE#XXEE	GEUM 840
	DO 180 K=2.NSECT4	GEOM 850
130	$\Lambda(X) = 0Y * NZ = \frac{1}{2} * 1Z = \frac{1}{2}$	GEDM 860
	IF(ZEEFF1.LE.TZEE) GO TO 200	GEUM 870
_	UI 190 L=2,1H511	GEUM สสถ
	$\Delta(L) = \Delta(L) + DY*NZEE*TZEE$	ĠĔŨM 89Ô
200	CUNTINGE	GEUM 900
	IF(ZEESF1.E0.0.0.0R.ZEESF1.LE.TZEE) GO TO 220	GEOM 910
	DO 210 M=IHGI2.NSECT4	GEOM 920
210	A(M) = A(M) + DY*NZEE*1ZEE	GEUM 930
220	CONTINUE	6EUM 940
	A(NSECT2)= NZEE*ZEESF*TZEE	GEDM 950
_	A(NSECL) = PANWID * LS	GEUM 960
230	CONTINUE	CEOM OZA
		GEUM 970
	REFURN	GEIIM 980
	REFURN	GEIIM 980
	REFURN FORMAT(50H CORRUGATION INPUT DATA YIELDS A NEGATIVE 'S LE	GEIIM 980
	REFURN FORMAT(50H CORRUGATION INPUT DATA YIELDS A NEGATIVE 'S LE	GEIIM 980
	REFURN FURMAT(50H CORRUGATION IMPUT DATA YIELDS A NEGATIVE S LE END SUBROUTINE TBLKP(T, IEX, XIN, YIN, Z, IE) DIMENSION [[1]]	ENGTH) GEUM 980
	REFURN FURMAT(50H CORRUGATION IMPUT DATA YIELDS A NEGATIVE S LE END SUBROUTINE TBLKP(T, IEX, XIN, YIN, Z, IE) DIMENSION F(1) COMMON PLAMOM, PRIMOM, INDPLA	ENGTH) GEUM 980 GEUM 990 [BLK 10
	REFURN FURMAT(50H CORRUGATION INPUT DATA YIELDS A NEGATIVE S LE ENO) SUBROUTINE TBLKP(T, IEX, XIN, YIN, Z, IE) DIMENSION [(1) COMMON PLAMOM, PRIMOM, INDPLA [= IAAS(IEX)	GEUM 980 GEUM 990 [BLK 10 [BLK 20
	REFURN FORMAT(50H CORRUGATION INPUT DATA YIELDS A NEGATIVE S LE ENO SUBROUTINE TRIKP(T, IEX, XIN, YIN, Z, IE) DIMENSION F(1) COMMON PLAMOM, PRIMOM, INDPLA I = IANS(IEX) IF = 0	GEUM 980 GEUM 990 IBLK 10 IBLK 20 TBLK 30
	REFURN FORMAT(50H CORRUGATION INPUT DATA YIELDS A NEGATIVE S LE END SUBROUTINE TRIKP(T, IEX, XIN, YIN, Z, IE) DIMENSION F(1) COMMON PLAMOM, PRIMOM, INDPLA I = IAHS(IEX) IE = 0 NX = F(1+2)	GEUM 980 GEUM 990 BEK 10 BEK 20 TBEK 30 BEK 40
240	REFURN FÜRMAT(50H CORRUGATION INPUT DATA YIELDS A NEGATIVE S LE END SUBROUTINE TBLKP(T, IEX, XIN, YIN, Z, IE) DIMENSION F(1) COMMON PLAMOM, PRIMOM, INDPLA I = IAHS(IEX) IE = 0 NX = F(I+2) NY = I(I+3)	GEUM 980 GEUM 990 BELK 10 FBLK 20 TBLK 30 BBLK 40 1BLK 50
240	REFURN FURMAT(50H CORRUGATION INPUT DATA YIELDS A NEGATIVE S LE ENO) SUBROUTINE TBLKP(T, IEX, XIN, YIN, Z, IE) DIMENSION [(1) COMMON PLAMOM, PRIMOM, INDPLA I = IANS(IEX) IE = 0 NX = F(1+2) NY = I(1+3) INDEPENDENT VARIABLE, X IANLE LODG-UP	GEUM 980 GEUM 990 IBLK 10 IBLK 20 IBLK 30 IBLK 40 IBLK 50 IBLK 60 IBLK 70
240	REFURN FURMAT(50H CORRUGATION INPUT DATA YIELDS A NEGATIVE S LE ENO SUBROUTINE TRIKP(T, IEX, XIN, YIN, Z, IE) DIMENSION [(1) COMMON PLAMOM, PRIMOM, INDPLA I = IAAS(IEX) IE = 0 NX = [(I+2) NY = I(I+3) INDEPENDENT VARIABLE, X TABLE LODG-UP L = 5	GEUM 980 GEUM 990 IBLK 10 IBLK 20 IBLK 30 IBLK 40 IBLK 50 IBLK 60 IBLK 70
240	REFURN FORMAT(50H CORRUGATION INPUT DATA YIELDS A NEGATIVE S LE END SUBROUTINE TRIKP(T, IEX, XIN, YIN, Z, IE) DIMENSION F(1) COMMON PLAMOM, PRIMOM, INDPLA I = IANS(IEX) IE = 0 NX = F(I+2) NY = I(I+3) INDEPENDENT VARIABLE, X TABLE LODG-UP LL = 5 LD = NX + 4	GEUM 980 GEUM 990 IBLK 10 IBLK 20 IBLK 30 IBLK 40 IBLK 50 IBLK 60 IBLK 60 IBLK 60 IBLK 80
240	REFURN FURMAT(50H CORRUGATION INPUT DATA YIELDS A NEGATIVE S LE FORMAT(50H CORRUGATION INPUT DATA YIELDS A NEGATIVE S LE ROY SUBROUTINE TBLKP(T, IEX, XIN, YIN, Z, IE) DIMENSION [[]] COMMON PLAMOM, PRIMOM, INDPLA [= IAAS(IEX) IE = () NX = [(I+2) NY = I(I+3) INDEPENDENT VARIABLE, X TABLE LODG-UP LL = 5 LU = NX + 4 LLS = I(I)	GEUM 980 GEUM 990 IBLK 10 IBLK 20 IBLK 30 IBLK 40 IBLK 50 IBLK 60 IBLK 60 IBLK 80 IBLK 80 IBLK 80
240	REFURN FURMAT(50H CORRUGATION IMPUT DATA YIELDS A NEGATIVE S LE ENO) SUBROUTINE TBLKP(T, IEX, XIN, YIN, Z, IE) DIMENSION [(1) COMMON PLAMOM, PRIMOM, INDPLA I = IAHS(IEX) IE = 0 NX = [(1+2) NY = I(1+2) NY = I(1+3) INDEPENDENT VARIABLE, X IAHLE LOUX-UP LL = 5 LU = NX + 4 LLS = I(I) VAR = XIN	GEUM 980 GEUM 990 IBLK 10 IBLK 20 IBLK 30 IBLK 40 IBLK 60 IBLK 60 IBLK 60 IBLK 70 IBLK 90 IBLK 90 IBLK 100
240	REFURN FURMAT(50H CORRUGATION INPUT DATA YIELDS A NEGATIVE S LE ENO SUBROUTINE TBLKP(T, IEX, XIN, YIN, Z, IE) DIMENSION [(1) COMMON PLAMOM, PRIMOM, INDPLA I = IAAS([EX) IE = 0 NX = [(I+2) NY = I[I+3) INDEPENDENT VARIABLE, X IABLE LOUX-UP L = 5 LU = NX + 4 LLS = I(I) VAR = XIN NRIN= 0	GEUM 980 GEUM 990 IBLK 10 IBLK 20 IBLK 30 IBLK 50 IBLK 60 IBLK 60 IBLK 60 IBLK 80 IBLK 90 IBLK 100 IBLK 110 IBLK 120
240 C	REFURN FURMAT(50H CORRUGATION INPUT DATA YIELDS A NEGATIVE S LE FNO SUBROUTINE TBLKP(T, IEX, XIN, YIN, Z, IE) DIMENSION [(1) COMMON PLAMOM, PRIMOM, INDPLA [= IAAS(IEX) IE = 0 NX = [(I+2) NY = I(I+3) INDEPENDENT VARIABLE, X TABLE LODG-UP LL = 5 LU = NX + 4 LLS = I(I) VAR = XIN NRINE O GO FO 50	GEUM 980 GEUM 990 IBLK 10 IBLK 20 IBLK 30 IBLK 40 IBLK 60 IBLK 60 IBLK 60 IBLK 70 IBLK 90 IBLK 100 IBLK 100 IBLK 100
240 C	REFURN FURMAT(50H CORRUGATION IMPUT DATA YIELDS A NEGATIVE S LE FURMAT(50H CORRUGATION IMPUT DATA YIELDS A NEGATIVE S LE RNO SUBROUTINE TBLKP(T, IEX, XIN, YIN, Z, IE) DIMENSION [[]] COMMON PLAMOM, PRIMOM, INDPLA I = IAAS(IEX) IE = 0 NX = [(I+2) NX = [(I+2) NY = I[I+3) INDEPENDENT VARIABLE, X IABLE LODG-UP LL = 5 LU = NX + 4 LLS = I(I) VAR = XIN NRIN= 0 GD [O 50 T(I) = LL	GEUM 980 GEUM 990 IBLK 10 IBLK 20 IBLK 30 IBLK 40 IBLK 60 IBLK 60 IBLK 60 IBLK 100 IBLK 110 IBLK 130 IBLK 130 IBLK 130 IBLK 140
240 C	REFURN FURMAT(50H CORRUGATION INPUT DATA YIELDS A NEGATIVE S LE FNO SUBROUTINE TBLKP(T, IEX, XIN, YIN, Z, IE) DIMENSION [(1) COMMON PLAMOM, PRIMOM, INDPLA [= IAAS(IEX) IE = 0 NX = [(I+2) NY = I(I+3) INDEPENDENT VARIABLE, X TABLE LODG-UP LL = 5 LU = NX + 4 LLS = I(I) VAR = XIN NRINE O GO FO 50	GEUM 980 GEUM 990 IBLK 10 IBLK 20 IBLK 30 IBLK 50 IBLK 60 IBLK 60 IBLK 100 IBLK 110 IBLK 120 IBLK 130 IBLK 130 IBLK 140 IBLK 140 IBLK 140 IBLK 150
240 C	REFURN FURMAT(50H CORRUGATION INPUT DATA YIELDS A NEGATIVE S LE ENO SUBROUTINE TBLKP(T, IEX, XIN, YIN, Z, IE) DIMENSION [(1) COMMON PLAMOM, PRIMOM, INDPLA I = IAAS([EX) IE = 0 NX = [(I+2) NY = I[I+3) INDEPENDENT VARIABLE, X IABLE LOUX-UP L = 5 LU = NX + 4 LLS = I(I) VAR = XIN NRIN= 0 GD [(1 50) T(I) = L IF (NY.GF.0) GD [(1 20) LZ = LL + NX	GEUM 980 GEUM 990 BLK 10 FBLK 20 FBLK 30 FBLK 40 FBLK 50 FBLK 60 FBLK 60 FBLK 80 FBLK 110 FBLK 120 FBLK 120 FBLK 120 FBLK 140 FBLK 150 FBLK 150 FBLK 150
240 C	REFURN FURMAT(50H CORRUGATION IMPUT DATA YIELDS A NEGATIVE S LE FORM SUBROUTINE TBLKP(T, IEX, XIN, YIN, Z, IE) DIMENSION [(1) COMMON PLAMOM, PRIMOM, INDPLA I = IAAS(IEX) IE = 0 NX = F(I+2) NY = T(I+3) INDEPENDENT VARIABLE, X TABLE LOUX-UP LL = 5 LU = NX + 4 LLS = I(I) VAR = XIN NRIN= 0 GO FO 50 T(I) = LL IF (NY, GF, O) GO FO 20 LZ = LL + NX Z = FRACC**(F(LZ+1) - F(LZ)) + T(LZ)	GEUM 980 GEUM 990 IBLK 10 IBLK 20 IBLK 30 IBLK 50 IBLK 60 IBLK 60 IBLK 100 IBLK 110 IBLK 120 IBLK 130 IBLK 130 IBLK 140 IBLK 140 IBLK 140 IBLK 150
240 C	REFURN FURMAT(50H CORRUGATION INPUT DATA YIELDS A NEGATIVE S LE FORMAT(50H CORRUGATION INPUT DATA YIELDS A NEGATIVE S LE RNO SUBROUTINE TBLKP(T, IEX, XIN, YIN, Z, IE) DIMENSION (1) COMMON PLAMOM, PRIMOM, INDPLA I = IAHS(IEX) IE = 0 NX = [(1+2) NY = I(I+2) NY = I(I+3) INDEPENDENT VARIABLE, X IAHLE LODG-UP LL = 5 LU = NX + 4 LLS = I(I) VAR = XIN NRIN= 0 GD fO 50 T(I) = LL IF (NY.GI.O) GD FU 20 LZ = LL + NX Z = FRACCE*([(LZ+1) - I(LZ)) + T(LZ) GO TU 190	GEUM 980 GEUM 990 IBLK 10 IBLK 20 IBLK 30 IBLK 50 IBLK 60 IBLK 60 IBLK 100 IBLK 110 IBLK 120 IBLK 120 IBLK 120 IBLK 140 IBLK 140 IBLK 140 IBLK 150 IBLK 160 IBLK 160
240 C	REFURN FURMAT(50H CORRUGATION IMPUT DATA YIELDS A NEGATIVE S LE FORM SUBROUTINE TBLKP(T, IEX, XIN, YIN, Z, IE) DIMENSION [(1) COMMON PLAMOM, PRIMOM, INDPLA I = IAHS([EX) IE = 0 NX = [(1+2) NY = I[(1+2) NY = I[(1+3) INDEPENDENT VARIABLE, X IABLE LODG-UP L = 5 LU = NX + 4 LLS = I[I] VAR = XIN NRIN= 0 GD fD 50 T(I) = L IF (NY.GF.0) GD fD 20 LZ = LL + NX Z = FRACI*([(LZ+1) - I(LZ)) + I(LZ) GO ID 190 INDEPENDENT VARIABLE, Y IABLE LODG-UP B[VARIAGE	GEUM 980 GEUM 990 IBLK 10 IBLK 20 IBLK 30 IBLK 50 IBLK 60 IBLK 60 IBLK 100 IBLK 110 IBLK 120 IBLK 120 IBLK 140 IBLK 140 IBLK 150 IBLK 150 IBLK 150 IBLK 170 IBLK 180 IBLK 180 IBLK 180 IBLK 180 IBLK 180
240 C	REFURN FURMAT(50H CORRUGATION IMPUT DATA YIELDS A NEGATIVE S LE ENO SUBROUTINE TBLKP(T, IEX, XIN, YIN, Z, IE) DIMENSION [(1) COMMON PLAMOM, PRIMOM, INDPLA I = IAHS([EX) IE = 0 NX = [(I+2) NY = I(I+3) INDEPENDENT VARIABLE, X IAHLE LODG-UP L = 5 LU = NX + 4 LLS = I(I) VAR = XIN NRIN= 0 GD [0 50 T(I) = L IF (NY.GI.O) GD [0 20 LZ = LL + NX Z = FRACI**([(LZ+1) - I(LZ)) + I(LZ) GO [0 10 190 INDEPENDENT VARIABLE, Y IAHLE LODG-UP BIVARIATE LX = LL - 4	GEUM 980 GEUM 990 BLK 10 FBLK 20 FBLK 30 FBLK 40 FBLK 60 FBLK 60 FBLK 100 FBLK 110 FBLK 120 FBLK 120 FBLK 140 FBLK 150 FBLK 140 FBLK 150 FBLK 180 FBLK 180
240 C	FURMAT(50H CORRUGATION IMPUT DATA YIELDS A NEGATIVE S LE FORMAT(50H CORRUGATION IMPUT DATA YIELDS A NEGATIVE S LE SUBROUTINE TBLKP(T, IEX, XIN, YIN, Z, IE) DIMENSION [[]] COMMON PLAMOM, PRIMOM, INDPLA I = IANS(IEX) IE = 0 NX = [(I+2) NX = [(I+2) NY = I(I+3) INDEPENDENT VARIABLE, X IANLE LODG-UP LL = 5 LU = NX + 4 LLS = I(I) VAR = XIN NRIN= 0 GO fO 10 50 T(I) = LL IF (NY,GI,O) GO FO 20 LZ = LL + NX Z = FRACIE*([(LZ+1) - ((LZ)) + T(LZ)) GO TO 190 INDEPENDENT VARIABLE, Y IANLE LODG-UP B[VARIAGE LX = LL - IEXACI	GEUM 980 GEUM 990 IBLK 10 IBLK 20 IBLK 30 IBLK 50 IBLK 60 IBLK 60 IBLK 100 IBLK 110 IBLK 120 IBLK 120 IBLK 140 IBLK 140 IBLK 150 IBLK 150 IBLK 150 IBLK 170 IBLK 180 IBLK 180 IBLK 180 IBLK 180 IBLK 180
240 C	REFURN FURMAT(50H CORRUGATION IMPUT DATA YIELDS A NEGATIVE S LE FORM SUBROUTINE TBLKP(T, IEX, XIN, YIN, Z, IE) DIMENSION ((1) COMMON PLAMOM, PRIMOM, INDPLA I = IAHS(IEX) IE = 0 NX = [(1+2) NY = I(1+3) INDEPENDENT VARIABLE, X TABLE LODG-UP LL = 5 LU = NX + 4 LLS = I(I) VAR = XIN NRIVE 0 GO FO 50 T(I) = LL IF (NY.GI.O) GO FO 20 LZ = LL + NX Z = FRACI**([(LZ+1) - I(LZ)) + I(LZ) GO TO 190 INDEPENDENT VARIABLE, Y TABLE LODG-UP BIVARIATE LX = LL - 4 FRX = FRACI LL = NX + 5	GEUM 980 GEUM 990 BLK 10 FBLK 20 FBLK 30 FBLK 50 FBLK 60 FBLK 60 FBLK 10 FBLK 110 FBLK 120 FBLK 130 FBLK 130 FBLK 140 FBLK 150 FBLK 150 FBLK 160 FBLK 160 FB
240 C	######################################	GEUM 980 GEUM 990 BLK 10 FBLK 20 FBLK 30 FBLK 40 FBLK 60 FBLK 60 FBLK 110 FBLK 120 FBLK 120 FBLK 120 FBLK 140 FBLK 140 FBLK 140 FBLK 140 FBLK 140 FBLK 220 FBLK 220 FBLK 220
240 C	FURMAT(50H CORRUGATION IMPUT DATA YIELDS A NEGATIVE S LE FORMAT(50H CORRUGATION IMPUT DATA YIELDS A NEGATIVE S LE FORMATOR (50H COMMON PLAND, FROM, INDPLATED AND FLAMBLE (1) I = IAAS(IEX) IE = 0 NX = I(I+2) NY = I(I+3) INDEPENDENT VARIABLE, X IABLE LODG-UP LL = 5 LU = NX + 4 LLS = I(I) VAR = XIN NRTN= 0 GO IO 50 T(I) = LL IF (NY,GI.O) GO IO 20 LZ = LL + NX Z = FRACI*(I(IZ+1) - I(LZ)) + I(LZ) GO IO 190 INDEPENDENT VARIABLE, Y IABLE LODG-UP BIVARIATE LX = LI - 4 FRX = FRACI LI = NX + 5 LI = NX + 5 LI = NX + NY + 4 LLS = I(I+1)	GEUM 980 GEUM 990 BLK 10 FBLK 20 FBLK 30 FBLK 50 FBLK 60 FBLK 80 FBLK 110 FBLK 120 FBLK 220 FBLK 220 FBLK 220 FBLK 220
240 C	######################################	GEUM 980 GEUM 990 BLK 10 FBLK 20 FBLK 30 FBLK 50 FBLK 60 FBLK 80 FBLK 100 FBLK 120 FBLK 120 FBLK 120 FBLK 120 FBLK 120 FBLK 120 FBLK 120 FBLK 120 FBLK 120 FBLK 220 FBLK 230 FBLK 220 FBLK 220

	NRIN = 1			TRUK 270
	G() T() 5() ∴([+1) =		•	TBLK 280 TBLK 290
C	INTERPOLATION L/ = LL F NY * LX			181K 300
	$IF(FRX,FO_1,_1) = G(1/2+NY) - I(1/2+) + I(1/2+)$	•-		181K 310
	LL = LL + 1	-	•	HLK 330 BLK 340
	$\frac{22}{2} = FRX * (I(LZ+dY) - I(LZ)) + I(LZ)$ $\frac{2}{2} = FRACI* (Z2 - Z1) + Z1$	_		18LK 350 18LK 360
40	GO [() [9) Z = FRACT* (T(LZ+NY+1) - T(LZ+NY)) +	NY)		THEK 370 THEK 380
C	GO CO 190 BASIC SEARCH ROUTINE USING HALVING TECHNIQUE	•	•	TBEK 390 TBEK 400
C	CONCINUE TEST IF INDEPENDENT VARIABLE EXCEEDS BOUNDS			IBLK 410
	IF (VAR. E. F((LI))) G() f() G() LL = LI) - 1			BLK 420 BLK 430
	ĬĒ (1ĒX.G(.0) VAR = ((.0)	-	-	[BLK 440]
60	GU TO 70 TE (VAB-GE-C(UL)) GO (U 80			[BLK 460 [BLK 470
70	IF (IEX.GI.O) VAR = I(LL) IE = 1	•	•	TBEK 480 TBEK 490
C	GO TO 180 [EST_IE_SAVED INDEX_IS_VITEIN TABLE BOUNDS		•	TBEK 500
80	LUS = $MAXO(MINO(LLS,LU),LLS)$ JE(LLS,GI,LL),LLS = LLS-I	_	•	IBLK 520
	LK = M[NO(LLS+2.LU]		•	TBEK 530 TBEK 540
90	IE (VAR-TUTES+11) 110 110 100		•	TBLK 550 TBLK 560
[1]()	LLS = LLS+1		•	TREK 570 TREK 580
110	GO [0 90 LL = LLS			IBLK 590
	GÖ [O [80 LU = LLS			BEK 600 BEK 510
	GÖ FO 140 UL = ULS+1			IBLK 620 IBLK 630
140	IF (UU-LL.EQ.1) GO (U 180		•	FBLK 640 TBLK 550
	MIO = (U + U)/2. $O = VAR - (MIO)$		•	FBEK 660 FBEK 670
	IF (D) 150,170,160 LU = M[D		-	18LK 680
	Ğ()]() [4() LL = M]()			TBLK 700
	60 10 140 Lt = MID		•	IBLK 710 IBLK 720
180	ČÔN TINÚE	_	•	18LK 730 18LK 740
	FRACÍ =(VAR - ľ(LL))/ (ľ(LL+1) - ľ(LL)) IĘ_(NRIN) 10,10,30		•	IBLK 750 IBLK 760
	RETURN END	_		THER TYO
1	Y XI F SITIME A	XMOM .	YHAR ,	ŢŢŢW 10
	STRANE , THETAE , STRESE , YNA , I ,	INDIFID.	NICON :	IIIM 20 IIIM 30
_	DIMENSION (4) , D(4) , XMOM()	(Õ) , Y	(60)	I [M 40]
1	YNA(10) , A(60) , FORCE DIMENSION STRESE(10,60) , STRANE(10,60) , E(1	£(60) L0,60}	•	111M 60 111m 70

IF(ITCON.EO.1)GO TO 10 IF(1907F).EO.0.AND.U(2).EO.0.AND.D(3).EU.0. 1GO TO 10				1 1 1 i 1 l
GO FO 60 10 DO 30 M=1,NTIME DO 20 J=1,NAR=4		•		Ĭ 1
$\begin{array}{lll} & \text{STRESE}(M,J) = & \text{XMUM}(M) + (18AK - 1637776) \\ & \text{SIRANE}(M,J) = & \text{SIRESE}(M,J) / E(M,J) \end{array}$	_	•		1 1 1
30 CONTINUE 00 50 K=1.NIME YNA(K)=YHAR 50 THETAE(I,K) = (XMOM(K)*OX)/(E(K,1)*XI) GO TO 220	· <u> </u>	*		I J
1111	-	•		i i
70 THE TAE(I,K)=(XMUM(K)*DX)/(E(K,NSEC))*A1/ DO 180 M=1,NIIME	•••	•	•	[] [] []
60 DO 70 (= (, N) IME 70 THE TAF(I, K) = (XMUM(K)*DX)/(E(K, NSEC T)*XI) DO 180 M=1, NI IME 80 YNA(M) = YBAR F1 = 0.0 90 TO TE = 0.0 XM = 0.0		•		įį
XM = 0.0 DO 120 J=1.NAREA S[RANE(M.J) = (YMA(M) - Y(J))*[HETAH([.M)/OX	-			1 ! []
XM = 0.0 DO 120 J=1.NAREA STRAME(M,J) = (YMA(M) - Y(J))*FHETAE([,M)/OX STRESE(M,J) = STRAME(M,J)*E(M,J) FORCEE(J) = STRESE(M,J)*A(J) IF([.EU.3) GD TO 110	_			i
TO CONCINE - FORESTA D				Ĭ.
20 [OTF = TOTF + FURCES(3):00:0) GO (U L40 IF([OTF:GI:0:0:AND:FI-LT:0:0) GO TO 140 Y1 = YNA(4)	-			l l
		•		Ĭ I I
IF(TOTE.11.0.0) YNA(M) = YNA(M) - OY IF(TOTE.61.0.0) YNA(M) = YNA(M) - OY IF(TOTE.E0.0.0) GO TO 150 F1 = TOTE GO TO 90 140 YNA(M) = YNA(M) - (ABS(TOTE)*(YNA(M) - Y1))/ 150 DO 160 K=1.NAREA	/(ABS(លោក) ។	F ABS(F	1)) [
150 DD 160 K=1.NAREA STRANG(M.K) = (YNA(M) - Y(K))*[HG[AG([,M)/O)	<			I I
150 DD 160 K=1,NAREA STRANE(M, <) = [YNA(M) - Y(<))*[HE[AE([,M)/0)*] STRESE(M, K) = STRANE(M, K)*E(M, K) EDROFE(K) = STRESE(M, <)*A(<) FORCEE(K) = STRESE(M, <)*A(A) - Y(K))) (D) = ABS(XM - XMUM(M))/XMUM(M) - Y(K)))				l I
160 XM = XM + ABS(FIRCEE(\)\(\)\(\)\(\)\(\)\(\)\(\)\(\)\(\)\(\		•		I I I
170 TECNICON. 50.1) GO (U 190			•	Î
180 CONTINUE GO FU 220 190 DO 210 M=2.NTIME				i I I
00.500 N=1,NASEA $100.500 N=1,NASEA$	-		•	İ I I
STRANE(M,N) = STRANE(L,N)*XMOM(M)/XMOM(1) STRESE(M,N) = STRESE(1,N)*XMOM(M)/XMOM(1) 200	-		•	Į I
510 CONTINUE 220 REFURN	-			Ĭ

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OU IP
                                                                                                                                    ĐÙ TP
                                                                                                                                     1)() TP
                                                                                                                                    HÜLP
                                                                                                                                                50
                                                                                                                                    UH IP
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                                                                                                                                    UI) 12
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                                                                                                                                     QÜİP
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                                                                                                                                     אז טט
                                                                                                                                     ōŭ ie
                                                                                                                                               170
                                                                                                                                     OU TH
                                                                                                                                     ŬÜ [P
     1XI YHAR
GO TO BO
 20 XI=XI*2.54*2.54*2.54*2.54
YBAR=YBAR*2.54
WRIFE(5,1310) IS,TR,MKI3.PIFCH,RIBELG,DEPIH
                                                                                                                                     00 TP
                                                                                                                                               250
                                                                                                                                     UCTP
                                                                                                                                               260
270
                                                                                                                                     אז נוט
     TXT.YBAR
GO TO B
                                                                                                                                               280
290
 GO [0 90

30 ]F([0]MEN.EQ.O)GO TO 40

WRITE (6.2210 ) IS,TC,NCUR,PITCH,FLAT,EDGE,PHICUR,DEPTH,

1XI,YBAR

GO [0 80

40 XI=XI*2.54*2.54*2.54*2.54

YBAR=Y3AR*2.54

WRITE(6.1320) FS,TC,NCOR,PITCH,FLAT,EDGE,PHICOR,DEPTH,
                                                                                                                                     00 1P 320
00 1P 330
 WRITE(0,:220)

1XI,YBAR

(G) TO BO

50 IF(IDIMEN.E0.0) GU TU 60

WRITE(6,2220) TS,TZEE,NZEE,PITCH,ZPNED1,ZPNED2,DEPTH,ZEESE,
ZEESEL,ZEEFE,ZEEEEL,
                                                                                                                                     iiú ie
                                                                                                                                     UÚ TP
2XI,YBAR

GD TO 80

60 XI=XI+2.54*2.54*2.54*2.54

YBAR=YBAR*2.54

WRITE ( 6.1330 ) TS,1ZEE,NZEE,PITCH,ZPNED1,ZPNED2,DEPTH,ZEESF,

ZEES-1,ZEEFH,ZEEFHI,
                                                                                                                                     UÜTP
                                                                                                                                     ŬŬ ÎP
 (0.1000) 80
70 CONTINUE
80 IF(101454.50.0) GU (0.90
WRITE(6,2230) XLGTH, PANWID
                                                                                                                                              480
                                                                                                                                      υŬ IP
                                                                                                                                      OUTP
GO TO LOO

90 WRITE(6,1340) XLGTH, PANWID

100 CONTINUE
                                                                                                                                               520
530
                                                                                                                                      uŭ le
                                                                                                                                     00 F 540
00 TP 550
       IF(INDBD.EQ.0) GO TO 150
IF(BRAD.GF.0.0) GO TO 110
WRITE ( 6.2240 )
GO TO 120
                                                                                                                                     00 12 560
00 12 570
                                                                                                                                      ŨŨ TP
                                                                                                                                               580
```

150) WRITE (6.2250)) IF(IDIMEN.EQ.O)GO TO 130 WRITE(6.2260) BRAD.BWID		00 FP 590 00 FP 600
	00 10 140 0 WRIFE(6,[350) BRAD,BU[O		00 P 610 00 P 620 00 P 630
וזכן	WRITE (5,2270) TE(1MDPLA.EQ.O)GO TO 220 WRITE(5,1360) WRITE(5,2190)		UUTP 640 UUTP 650 UUTP 660 UUTP 670
	WRIFE(6,1370) IF(IDIMEN.EQ.O)GO TO 170 WRIFE(6,1380)		00 TP 680 00 TP 690 00 TP 700
	WRITE(6,1390) (XPRINT(N),N=1,NSTAT) WRITE(6,1400) DU 160 M=1,NTIME WRITE(6,1400)	•	00 P 710 00 P 720 00 P 730 00 P 740
	WRITE(6,[410]))XTTHE(M),(프로디에)에(I+M),[=1,NSTAT) CONTINUE GO TO ZIO CONTINUE		00 1P 750 00 1P 760 00 1P 770
180	DD 180 N=1,NS[AT XPRINT(N)=XPRINT(N)*2.54 MRITE(6,1420) WRITE(6,1390) (XPRINT(N),N=1,NSTAT)	•	00 P 780 00 P 790 00 P 800 00 P 810
•	00 200 M=1,NTIME		00 TP 820 00 [P 830 00 [P 840
	PRIMOM(I,M)=PRIMOM(I,M)*.4536*2.54 WRIFE(6,1410)DXFIME(M), [PRIMOM(I,M),I=1,NSFAF) CONTINUE GO FO 350	•	00 12 350 00 12 860 00 12 370 00 12 880
2 2 0	CONTINUE IE ([ND - D) - EQ - E) GO TO 240		00 F 900 00 P 910 00 P 910
230	TE(TNDSOP.E0.1) GO FO 230 WRITE (6,2290) GO FO 350 WRITE (6,2300)	•	00 TP 920 00 TP 930 00 TP 940 00 TP 950
	GD FO 350 IF(IDIMEN.EO.O)GO TO 250 WRIFE(5.1440)ALEN GO TO 260		80 12 968 00 12 970 00 12 980 00 12 990
250 260	WRITE(6.1450)ALEN CONTINUE WRITE(6.1460)	•	00 12 1000 00 121010 00 121020
270	IF(11)ME.E0.6) GD TO 270 WRITE(4,1470) GD TO 280 WRITE(4,1480)	•	00 (21030 00 (21030 00 (21050 00 (21050
280	CONTINUE IF(ILIAD.EQ.O.)GO (O 290 WRITE(6.1490)	•	00 (51040 00 (51040 00 (51040
	GO (O 31) WRITE(6,1500) DO 300 (L=1,NIIME PLOAD(LL)=PLOAD(LL)*.45359		00 /P1100 00 /P1110 00 /P1120 00 /P1130
310	CONTINUE JF(IINTP.EQ.O')GD TO 320 WRITE(6,1510)		001P1140 001P1150 001P1160
			00 (FTT76

	$60^{\circ} \cdot 10^{\circ} \cdot 330^{\circ}$	10151150
	₩RIJE(6,1520)	00 6 200
330	COM(140=	00 12 12 10
	WRI JE (6+1530)	000 (22)
	981[6(6,1500)0X[[0:(1),0:000(1),6:42(1)	00 12 230
	TE(MTIME.E0.1) GD TO 340 WRITE(6.2330)(OXTIME(N-1),OXT[ME(N),PLOAD(N),TEMP(N),M=2,NTIME)	00 12 1240
260	CONTINUE MAINELANTINE (AND LINE LAND LINE AND ADJUST OF A CANADA AND AND AND AND AND AND AND AND AN	DÚ 121250
240	GD 10 430	UU 12 [250
350	CONTINUE'	OU IP1270
5 20	₩RITE(6,1460)	OO [51580
	ÎÊ(ÎTÎMÊ.ÊŬ.O) GO TO 360	OU [F1390
	WRITE(6.1470)	00 15 1 300
	60 10 370	OU [P1310
360	ŴRI[E(6,1480) · · · · · · · · · · · · · · · · · · ·	00 [51350
370	CONTINUE	00 [P1330 00 [P1340
	ĬĔ(ŢŢŰŸĎ.ĒĢ.O) GO fO 380	UU IP 1 350
	WRIJE(6,1550)	UU [P] 350
	60 [0 400]	OUTP1376
380	WRITE(6,1560)	ที่ที่ โคที่ อีสด์
200	DO 390 LL=[.NIME PRESS(LL)=PRESS(LL)*6894.8	00 TP 1 390
	CDMLIMAGE	ÜÜ 12 1400
400	IF(IINTP.EQ.0) GO TO 410	UU 121 410
	WRITE(6, 1510)	UU [P1420
	GN 10 426 1	00 [21430
410	ŴŔŢĹĖ(ĠŶĴ520)	UU (Y 1 440)
	CONTINUÉ	UU IP 1 450
	WP (E(6. 1570)	00 [P] 460 00 [P] 470
	WRITE(8,1546)DXTIME(1).PRESS(1).TEMP(1)	00 12 1 470
	IF(N[IME.E0.1]G0_[0.430]	00 IP 1 490
	MK1 16(0+5000) (DX 11M6(M-1)+DX 11M6(M)+1 M603(M)+ 1600 (M)+100 (M)	00 P 1500
43()	CONTINUE	00 1P 15 10
	WRITE(6,2190) WRITE(6,1580)	ÜÜ TP 1520
	WRITE(3,1590)Z(1)	U(111530
	IE(7(2).50.0.30) (0 440	UU TP 15 4()
	wk î=(6,1600)2(2)	UU JP 1550
440	COM (100)	00 15 15 60
	ÍF(Z(3).Ev.o.)GO TO 450	00 P1570
	พื้นได้(6,1610)Z(3)	00 12 1580
450	COM TIMOF	00 121590 00 121500
	TE(元(4)。元(0.0。)	00 FF 1500
	WRITE(6,1620)2(4)	UU [P 1620
460	CONTINUE - 200 TO 770	00 12 16 30
	IF(Z(5).E0.0.)GD TO 470	00121540
. 70	WRIFE(5,1630)Z(5)	00 IP 1650
.470	CONTINUE IF(Z(6), FO, O, JGO, 430	00 12 [560
	WRITE(6,1640)Z(6)	00 121670
420	CONSTANDE	00151290
,.,	IF(Z(7).E0.0.)GD TO 490	DO 15 1 6 3 0
	WRITE(6,1650)Z(7)	- <u>00 (81700</u>
490	CONTINUÉ	00 [217]0
	ĬF(Z(8),EQ.O.)GU (U 500	00 121720
	WRITE(6,1660)Z(8)	00 (P1730 00 (P1740
500	CONCINDÉ .	00 P 1750
	ĬF(<u>Z[9), E0.0.1G</u> 0, TO 510	UU FP 1760
	WRIFE(6.1670)Z(9)	00 11 1100



510	CONTINUE IF(Z(10).E0.0.1GD TO 520		,	00 (P) (70 00 (P) 780
L DA	WRITE(6,1680)2(10)			00 12 1796 00 12 1800
220	CONTINUE 1E(/(11),60,0,)60,70 33			00 (2 (3 (a) 00 (2 (3 (a) 00 (2 (3 (a)
530	WRITE(6,1690)Z(11) CHALLOUE		•	00 12 13 30 00 12 13 30
	TF(7(12).E0.0.)GU TU 540 WR1[F(6,1700)Z(12)			00 17 18 50 00 17 1850 00 17 1860
540	COM TIMUE IF(Z(13).E0.0.)GU (U 550			00 (21370
550	WR1 TE(6,1710)Z(13) CUNTINUE		•	UU IP1880 OU IP1890
	IF(Z(14).E0.0.)GU TO 560 WRITE(6,1720)Z(14)	•	,	00 [P1900 00 [P1910
560	CONTINUE IF(Z(15).60.0.)60 (U 570		Ÿ	00 12 1920 00 12 1930
570	WRITE(6.1730)Z(15) CONCINUE			00 (P1940 00 (P1950
_	IF(Z(16).EU.O.)GU TU 580 WRITE(6.1740)Z(16)			00 (P1960 00 (P1970
580	CONTINUE LE(Z(17).EQ.O.)GO TO 590 WRITE(6.1750)Z(17)		•	00 12 1930
59n	COMPINAR	. •		00 (P2000 00 (P2010
	IF(Z(J8).E0.0.)G0 TO 600 WRITE(6,1760)Z(18)			80 122020 00 122030 00 122040
6(11)	COM TIMUE TE(Z(19).50.0.)GU TO 510			00 122050 00 122050 00 122060
610	WRTTE(6,1770)Z(19) COMTINUE			00 (2070) 00 (2070) 00 (2080)
4.20	IF(7(20),E0.0.)GD TO 620 WRITE(5,1780)Z(20)			00 12 2090 00 12 2100
020	COMITAGE IF(Z(21).EQ.O.)GO (O 530 WRITE(6,1790)Z(21)			00 122 1 10 00 122 1 20
630	CONTINUE IF(Z(22).ED.O.)GD TO 640		•	00 F2 1 36 00 F2 1 40
640	WRITE(5, (800)) Z(22) CONTINUE			00 P2150 00 P2160
. 040	ĬĔ(7(23).E0.0.)GO (0.550 WRITE(6,1810)Z(23)			00 122170 00 122180
650	CONTINUE IF(7(24).E0.0.1G0 TO 660			00122190 00122190
660	ÑRŤſĖ(Ġ;ťä2ŏ)Ž(24) COMTIMUE			UU 122210 UU 122220
	ĬĔ(Z(25).E0.0.)GO [O 570 WRITE(4,1830)Z(25)		•	00 122230 00 122240
670	CONTINUÉ TE(Z(25).E0.0.)GO TO 680		•	UU 12250 UU 12250
680	- WRITE(6, (840)Z(26) - CON TINUE		-	00 TP 2270 00 TP 2280
	- ÎF(Z(27).€0.0.)GU (U 590 - WRIJE(6.1850)Z(27)		•	00 122290 00 122300
690	CONTINUE 16(7(28)=60=0=160 TO 700		•	00 (P 231) 00 (P 232)
700	WRIFE(6,1860)2(28) CONTINUE		•	00 (P 2 3 40) 00 (P 2 3 40)
	- [F(7(29).EQ.O.)60 (U 710			0012350

	·필보 [[년년(5 + [보기이) Z (2 9)		_	1111 165320
110	CHIMIR			(B) 122370
	IE(7(3)).E0.0.160 (0 720			(11) 122330
	WRITE(5.1880)7(30)		•	00 12 390
120	्राज्यों कित्री के			00122400
, .,	JE(2(31).E0.0.)60 TO 730			00122410
770	MK1[E[6, L490]Z(31)			10 122420
130	CUM TINUE		·	UU [P 2 4 30
	16(7(32).60.0.)GU (U 740			HU (P 2 4 40)
	WRITE(6,1900)Z(32)		•	00 12 2 450
740	CONFINUE	-		UU [+2450
• • • • •	ĬĔ(Z(33).E0.0.)GU TO 750		•	UU 12 24/0
	WRITE(6,1910)2(33)	** * * * * ** ** ** ** ** ** ** ** ** *		บับ โค วิ 480
750			4	00 TP 2 490
100	CONTINUE		ė	
	[F(Z(34),EQ.O.)GO [O 760		_	00 155500
	WRIJE(6,1920)Z(34)	And the second second		UU [P2510
760	COMPINATE			UU 122520
	IF(Z(35).EQ.O.)GD TO 770		•	OU 12530
	WRITE(6,1930)2(35)			DU TP 25 40
770	CONTINUE		•	00 TP 2550
				UÜ 12560
	IF(7(36).E0.0.)G0 f0 780 WRIJE(6,1940)Z(36)	A Company of the Comp	•	00 15 22 20
7	WKI 15 (0) (940 / 2 (30 /	*		00 TP 25 70
730	CONTINUE			00 12580
	IF(2(3/).E0.0.)G0 TO 790		4	OU 145240
	WRITE(6,1950)2(37)			UU [P 2500
790	CHATINUE		•	UU 12610
	IF(7(38).E0.0.)GO FO 300			UU 122620
	WRITE(6,1960)Z(38)		•	UU [P 26 30
ROO	CHALLANG	•	*	UU 122640
.,,,,,,	IF(7(39).EQ.0.160 TO 810		•	ŬŰ ŤĽ 2650
	WRITE(6,1970)2(39)		-	00 12 2660
u 1 /	かいし こしい チャンチンフィンファー			
OTO	CONTINUE			00 1539 (0
	IF(Z(40),EQ.0,)GU (U 320			NO 155090
	WRITE (6,1980)Z(40)		, •	OO 15590
おくひ	CONLINGE			00/155700
	IF(Z(41).E0.0.)GO TO 830		•	0072710
	WRITE(6,1990)2(41)	,		UUTP2720
830	CONTINUE		•	110/12/27/30
	IF(Z(42).50.0.)60 (0.340)		•	OU 12740
	WRITE(6,2000)Z(42)		•	UÜ TP 2750
U 4.0	CONFIANG			UÚ 1PŽ/60
רו זיי כי			•	DU 15 2770
	IF(Z(43),EQ.Q.)GU, TO 850		•	
	MRITE(5,2010)Z(43)	•		00 155190
おうり	COM 11 MUE			00 TP 2790
	[F(Z(44).60.0.)GD [D 360	•		00 15 5900
		•	•	00152400
850	[F(Z(44).60.0.)GD [D 360	•		00152400
850	ĬE(7(44).E0.0.)GU (U 360 WRITE(6,2020)Z(44) CONTINUE			00 12810 00 12810 00 12810
850	F(Z(44).E0.0.)GH (H 360 WRITE(4,2020)Z(44) CONTINUE IF(Z(45).E0.0.) GU TU 870			00 123420 00 123420 00 123420 00 12330
	IF(Z(44).E0.0.)GH (H 360 WRITE(4,2020)Z(44) CONTINUE IF(Z(45).E0.0.) GH TO 870 WRITE(6,2030)Z(45)	•	· ·	00 122800 00 122810 00 122820 00 122830 00 122840
	IF(Z(44).E0.0.)GH (H 360 WRITE(5,2020)Z(44) CONITOUE IF(Z(45).E0.0.) GU TO 870 WRITE(5,2030)Z(45) CONTINUE	•	•	00 122800 00 122810 00 122820 00 122830 00 122840 00 122850
	IF(Z(44).E0.0.)GH (H 360 WRITE(5,2020)Z(44) CONTINUE IF(Z(45).E0.0.) GH TO 870 WRITE(5,2030)Z(45) CONTINUE IF(IFIME.E0.0)GH (H 830			00 122300 00 122320 00 122320 00 122340 00 122340 00 122360
	F(7(44).60.0.)GH (H 360 WRITE(4.2020)Z(44) CONTINUE IF(2(45).E0.0.) GH TO 870 WRITE(4.2030)Z(45) CONTINUE IF(1F(1F.60.0)GH (H 830) WRITE(4.2040)		•	00 122300 00 122810 00 122820 00 122830 00 122840 00 122850 00 122860
8 7 0	IF(Z(44).E0.0.)GH (H 360 WRITE(4,2020)Z(44) CONTINUE IF(Z(45).E0.0.) GH TO 870 WRITE(6,2030)Z(45) CONTINUE IF(ITIME.E0.0)GH (H 830 WRITE(6,2040) GH (H 890		•	00 12230 00 122310 00 122320 00 122330 00 122340 00 122350 00 122360 00 122360
8 7 0 880	IF(Z(44).E0.0.)GH (H 360 WRITE(4,2020)Z(44) CONFINUE IF(Z(45).E0.0.) GH TO 870 WRITE(6,2030)Z(45) CONTINUE IF(IITHE.E0.0)GH (H 340) WRITE(6,2040) GH (B 890) WRITE(6,2050)		•	00 122300 00 122810 00 122820 00 122830 00 122850 00 122850 00 122860 00 122880 00 122880
8 7 0 880	F(7(44).60.0.)GH (H 360 WRITE(4.2020)Z(44) CONTINUE IF(2(45).E0.0.) GU TO 870 WRITE(6.2030)Z(45) CONTINUE IF(1[146.60.0)GH (H 330) WRITE(6.2040) GO (H 890) WRITE(6.2050)		•	00 122300 00 122320 00 122320 00 122330 00 122340 00 122360 00 122360 00 122360 00 122360 00 122300
8 7 0 880	F(7(44).60.0.)GH (H 360 WRITE(4.2020)Z(44) CONTINUE IF(2(45).E0.0.) GU TO 870 WRITE(6.2030)Z(45) CONTINUE IF(1[146.60.0)GH (H 330) WRITE(6.2040) GO (H 890) WRITE(6.2050) CONTINUE			00 122300 00 122810 00 122820 00 122830 00 122850 00 122850 00 122860 00 122880 00 122880
8 7 0 880	F(Z(44).E0.0.)GH CH 360 WRITE(4.2020)Z(44) CONTINUE IF(Z(45).E0.0.) GH TO 870 WRITE(6.2030)Z(45) CONTINUE IF(IF(IF(4.E0.0)GH F(4.2040) GO F(4.2040) GO F(4.2040) GO F(4.2050) GO TO S00 WRITE(6.2050) CONTINUE IF(IFONTP.E0.0)GH TO 900 TO 900 GO GO GO GO GO GO GO			00 122300 00 122310 00 122320 00 122320 00 122320 00 122360 00 122360 00 122360 00 122390 00 12230 00 12230 00 12230
8 7 0 880	F(Z(44).E0.0.)GH CH 360 WRITE(4.2020)Z(44) CONTINUE TF(Z(45).E0.0.) GU TU 870 WRITE(6.2030)Z(45) CONTINUE TF(ITHE.E0.0)GO FU 830 WRITE(4.2040) GO FU 890 WRITE(4.2050) CONTINUE TF(IFONTP.E0.0)GU TU 900 WRITE(6.2060) WRITE(6.2060) WRITE(6.2060) CONTINUE TF(IFONTP.E0.0)GU TU 900 WRITE(6.2060) CONTINUE		00 122300 00 122310 00 122320 00 122320 00 122320 00 122360 00 122360 00 122360 00 122390 00 12230 00 12230 00 12230	
870 880 890	F(Z(44).E0.0.)GH CH 360 WRITE(4.2020)Z(44) CONTINUE IF(Z(45).E0.0.) GH TO 870 WRITE(6.2030)Z(45) CONTINUE IF(IF(IF(4.E0.0)GH F(4.2040) GO F(4.2040) GO F(4.2040) GO F(4.2050) GO TO S00 WRITE(6.2050) CONTINUE IF(IFONTP.E0.0)GH TO 900 TO 900 GO GO GO GO GO GO GO	_		00 122300 00 122810 00 122820 00 122820 00 122840 00 122860 00 122870 00 122890 00 122890 00 122900

(11/)	CHALIMIE		けいしとえょうロ
710		•	UU 122950
	IE(IEONST.EQ.O)GO TO 920		ÜÜTEŽŦĨŎ
	MRT[E(6,2080)		
	$60 \cdot 10^{-9.30}$		DD 12340
	WRT「「(っ, 2090)		11/11/23/3/1
(3.31)	CITALLEGIE		HH 1P 3000
	「「「「「」「」「」「」「」「」「」「」「」「」「」「「」「」「」「」「」「		110 jg 30 Fo
	WRT 1F(5.2340)	•	110 j.b. 30.50
	WRI 1E(5.2360) IE(1[14E.=0.0)GO fO 9+0 WRI 1E(5.2350) (XPRINT(N),N=1,NSTAT) GO fO 950 WRI 1E(6.2100) (XPRINT(N),N=1,NSTAT) CONFINUE DO 960 M=1,NTIME WRITE (6.2360) OXFI4E(M),(DEFLE(M,N),N=1,NSTAT)		UU [+ 30 30
	WRITE (6.2350) (XPRINTON).N=1.NSTAT)	•	UU 12 30 40
	60 (0.950		UU 12 3050
940	WRITELE 21001 (XPRINTINIAN=1-NSTAT)	•	UU TP 3060
050	WALLE THE CONTRACTOR OF THE CO		00 12 30 70
9 111	SUNTINUE	• •	บับ โห 3กัชกั
	WRITE (6,2360) DXF[4E(M),(DEFLE(M,N),N=1,NS[AT)		ŬŬ TP 3090
	WRITE (0,2300) DXII 46(M)) DECEMBENT ALL INSTACTOR	•	DÚ ÍP 31 00
950	CONTINUE		00 17 31 10
	60 [0 1030		00 17 31 20
970	CONTINUE		
	WRIFE(6,2110)		UIT P 31 30
	IF(ITIME.E0.0)GO TO 980	4.4	00 12 31 40
	WRITE(6,2110) IF(ITIME.E0.0)GU TU 980 WRITE(6,2350) (XPRINT(N),N=1,NSFAT)	_	00 15 31 20
	(1) [1] 9.7()	•	UU 12 3160
930	WKITE(6,2100) (XPR[NT(N),N=1,NSTAT)		UU (P 31 70
	CONTINUE	•	UU IP 3180
, , , ,	DO 1010 M=1,NIIME		UU TP 3[90
	00 1000 N=1.NSf4T	•	UU TP 3200
	DEFLE(M, N)=0)EFLE(M,N)32.04		00123210
1000	COMTINUE	•	ÜÜ (P 3220)
			ŬŬ ÎP 32 36
LOTO	COMFINUE	•	UU TP 32 40
	DD 1020 M=1,NTIME		UU IP 3250
	WRITE(A, 2360)DXTIME(M), (DEFLE(M, N), N=L, NSTAT)		UŬ TP 3260
1050	CONTINUE	•	UU FP 3270
1030	CONTINUE	•	
	IF(INDELA.EQ.1) REJURN		UU 12 3280
	TÍF(ÍNGYĞ.EO.O) GU IO tloo		00 (5 3550
	IF(101MEN.EQ.0)GO TO 1050		UU [P 3300
	WRT[F(6.2120)		อกโรจิริโบ
	WRITE(5.2130) (XPRINT(N).N=1.NS (A.I.)	•	00153350
	DO 1040 M=1.NETME		OU [F 3330
	ŴŔŢŤĔ(6,2140) ĎXŤIME(M),(DEFLIN(M,N),N=1,NSTAT)	•	UU 1P 3340
1040	CHNEINOR		ひけ (とろろうり)
11141	GU 10 1090	•	OU IP 3360
1050	WRIFE(6,2150)		00 12 3370
Fubu	WRITE(6,2130) (XPRINT(N),N=1,NSTAT)	•	ÜÜ TP 3 380
	WK 15 (0 + 2 30) (AFK IN 1 (N / + N = 1 + N 3) A /		ÜÜ İP 3390
	DO 1070 M=1,NIIME DO 1060 N=1,NSIAT	•	ΰΰ le 3400
	DO [089 N=[+N5] A1		ŬŬ ÎP 34Î Ô
2.4	DEETIN(M*N)=DEETIN(M*N)*2*24		00 IP 3420
1050	COM I MOE		
1070	CONTINUE		UU 12 3430
	.00°1080 M=1.NTIME		UU 12 3440
	WRITE(A, 2140) DXTIME(M), (DEFLIN(M, N), N=1, NSTAT)		UU 1P 3450
1080	CONTINUE		UU IP 3460
1090	CHALIMIE		00 [83470
	CONTINUÉ -	•	UU TP 3480
LIUM	ĬF([DIMĒM.EQ.O.)GO FO 1120		UÜ 12 3490
	WRITE (6,2370)	-	00 TP 3500
			บับ โค 35 ไ อ
	WRITE (5,2380) (XPRINI(N),N=1,NSIAI)	•	00 12 35 20
	DO 1110 M=1.NUMCYC		00 IP 35 30
	WRITE (6.2390) KCYCLE(M), (DEFL (M, N), N=1, NSTA !-)		0011 3730

1110 dualimet	1111123540
GO TO 1160	110 12 3550
1120 38(1) (6,2160)	UU 12 3560
WRITE(5,2380) (XPRIGIT(N),N=1,NS TAIT)	HÚ 12 35 70
DO 1140 4=1,404646	1111 15 3290
DO 1130 N=L, \S[A]	00 12 3590
OEF((M,N)=0-F((M,N)*2.54	00123500
1130 CONTIMIE 1140 CONTINUE	UU 12 36 [0 UU 12 36 20
DO 1150 M=1, NUMCYC	00 TP 36 30
WRITE(6,2390) KCYCLE(M), (DEFL(M,M), N=1, NSTAT)	UU 12 36 40
1150 CONTINUE	OU IP 3650
ĬĬ60 ČQNFĬNUE	OU 12 3660
ĬĔ(ĬĎĬMĔŊ.ĘO.Į)ĢO TO 1180	OU TP 3670
DO 1170 N=1,NAREA	00 FP 3680 00 FP 3690
1170 Y(N)=Y(N)*2.54 1180 COMFINUE	00 17 3690
DO 1290 N1=1.NUMCYC	iiii ir 3/10
ĬĔ(ĬĎĬŃĘŇĴĔĠĴŎĬĠĠĬſO 1190	θŰ 1P 37 ŽÓ
GO TO 1200	OU 12 37 30
1190 MKICE(6:5170)KCYCLE(NL)	UU 12 37 40
GO TO 1210	00 TP 3750 00 TP 3760
1200 WRIFE(6,2430)KCYCLE(NL) 1210 CONTINUE	UÚ 12 37 76
WRITE (6,2440) (XPRINT(N),N=1,NSTAT)	00 TH 3/80
DΩ 1220 M2=1.NARFA	ÖÜ TP 379Ö
WRITE (6,2450) Y(N2), (PSTRAN(N3,N2,NL),N3=1,NSTAT)	00 js 3900
1220 CONTINUE	DU 19 38 10
IE(IDIMEN, E0.0)60 f0 L230	00 12 3420 00 12 38 30
GO TO 1260 - 1230 WRITE(6,2180)KCYCLE(NU)	00 TP 38 40
DO 1250 (2=1, Narea	00 Tr 3850
DO 1240 13=1.NS[Δ]	00 (5 3990)
RESP(13,12,N1)=RESP(13,12,N1)*.0068948	DÜ TP 3870
1240 CONTINUE	00 15 35 50
1250 CONTINUE GO FO 1270	00 12 3890 00 12 3900
1260 WRITE(6,2400)KCYCLE(NI)	00 Tr 3910
1270 CONTINUE	ÜÜ İP 3920
WRITE (6,2410) (XPRINT(N),N=1,NSTAT)	DD [15 39 <u>3</u> 0
DO 1280 N2=1.4AREA	00 16 39 40
WRITE (6,2420) Y(N2) , (RESP(N3,N2,N1),N3=1,NSTAT)	OU 12 3950
1280 CONTINUE 1290 CONTINUE	110 TP 3950 00 TP 3970
TO CONTROL	00 15 33 990
1300 FORMA I (50X.5A10.//)	UD IP 3990
-1310 FORMAT(43X.23HRIB STIFFENEO TPS PANEU//53X.12HSKIN GAGE = .Fb.	4 · _ UU JP 4000 -
17H CM 1/53X, LIHRIB GAGE = , F5.4, 7H CM / 753X, L/HNUMBER OF R	185 UU IP 4010
2= , 13/53x, 15HP[13H]	UENGUU IP 4020
453X,31HCALCULATED MUMENT NOT INCRETA = ,610.7,50 CM //	00 12 40 40
553X.23HELASTIC NEUTRAL AXIS = .F5.3.7H CM /)	ŬŬ FP 4050
553X,230FLASTIC NEUTRAL AXIS = ,F5,3,7H CM //) 1320 FORMAT(43X,28HSINGLE TACTO CURRUGATION FPS//53X,12HSKIN GAGE =	· HH [P 4060
165.4.7H CM	UU JP 4070
225HNBMBER OF CORRUGATIONS = .13753X.15HPITCH LENGTH = .E6.3.	00 12 4080
37H CM 753X,14HFLAT LENGTH = ,F6.3,7H CM 753X,	UU IP 4090
420HPANEL EDGE LENGTH = .F6.3,/H CM /53X,20HCORRUGALLON ANGL 5,66.3,8H DEGREES/53X,14HPANEL DEPTH = .F5.3,7H CM	1111114110
653X,31HCALCULATED MOMENT OF INERTIA = ,F10.7.64 CM**4/	00 124[20
OBSERVABLE OF COMPANY OF CONTRACT OF CONTRACT OF THE CONTRACT OF C	0000

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